

EC axial fan - HyBlade

sickle-shaped blades (S series)

with square full nozzle

W3G990-GZ02-01 ebmpapst Datasheet

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Nominal data

Type	W3G990-GZ02-01	
Motor	M3G150-NA	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min ⁻¹	960
Power consumption	W	2580
Current draw	A	4.0
Max. back pressure	Pa	180
Max. back pressure	in. wg	0.72
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	70

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to Commission Regulation (EU) 327/2011

		Actual	Req. 2015			
01 Overall efficiency η_{es}	%	54.4	36.2	09 Power consumption P_{ed}	kW	2.54
02 Measurement category		A		09 Air flow q_v	m ³ /h	24185
03 Efficiency category		Static		09 Pressure increase p_{fs}	Pa	194
04 Efficiency grade N		58.2	40	10 Speed (rpm) n	min ⁻¹	965
05 Variable speed drive		Yes		11 Specific ratio*		1.00

Data obtained at optimum efficiency level.

The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

* Specific ratio = $1 + p_s / 100\,000\text{ Pa}$

LU-170333



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Technical description

Weight	61.9 kg
Size	990 mm
Motor size	150
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum, painted black
Blade material	Sheet aluminum insert, sprayed with PP plastic
Fan housing material	Sheet steel, galvanized and coated with black plastic (RAL 9005)
Guard grille material	Steel, coated with black plastic (RAL 9005)
Number of blades	5
Blade pitch	-5°
Airflow direction	V
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	"F"
Moisture (F) / Environmental (H) protection class	H2
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	<ul style="list-style-type: none"> - Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Operation and alarm display - Input for sensor 0-10 V or 4-20 mA - External 24 V input (parameter setting) - External release input - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from supply - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC interference emission	According to EN 61000-6-3 (household environment)
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (with customer connection of protective earth)



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Conformity with standards	EN 61800-5-1; CE
Approval	CSA C22.2 No. 77 + CAN/CSA-E60730-1; EAC; UL 1004-7 + 60730-1

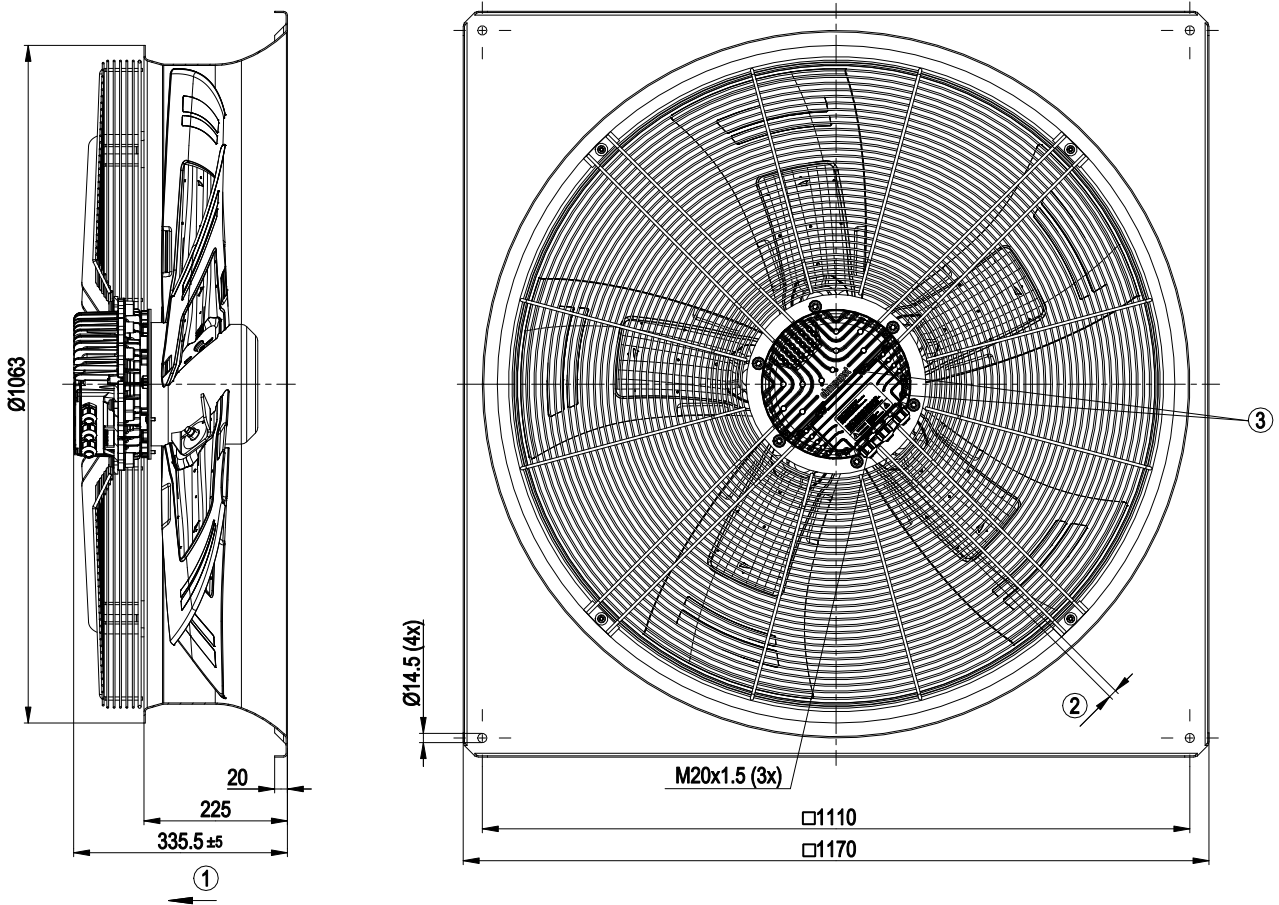


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Product drawing



1	Direction of air flow "V"
2	Cable diameter min. 4 mm, max. 10 mm, tightening torque 4 ± 0.6 Nm
3	Tightening torque 3.5 ± 0.5 Nm

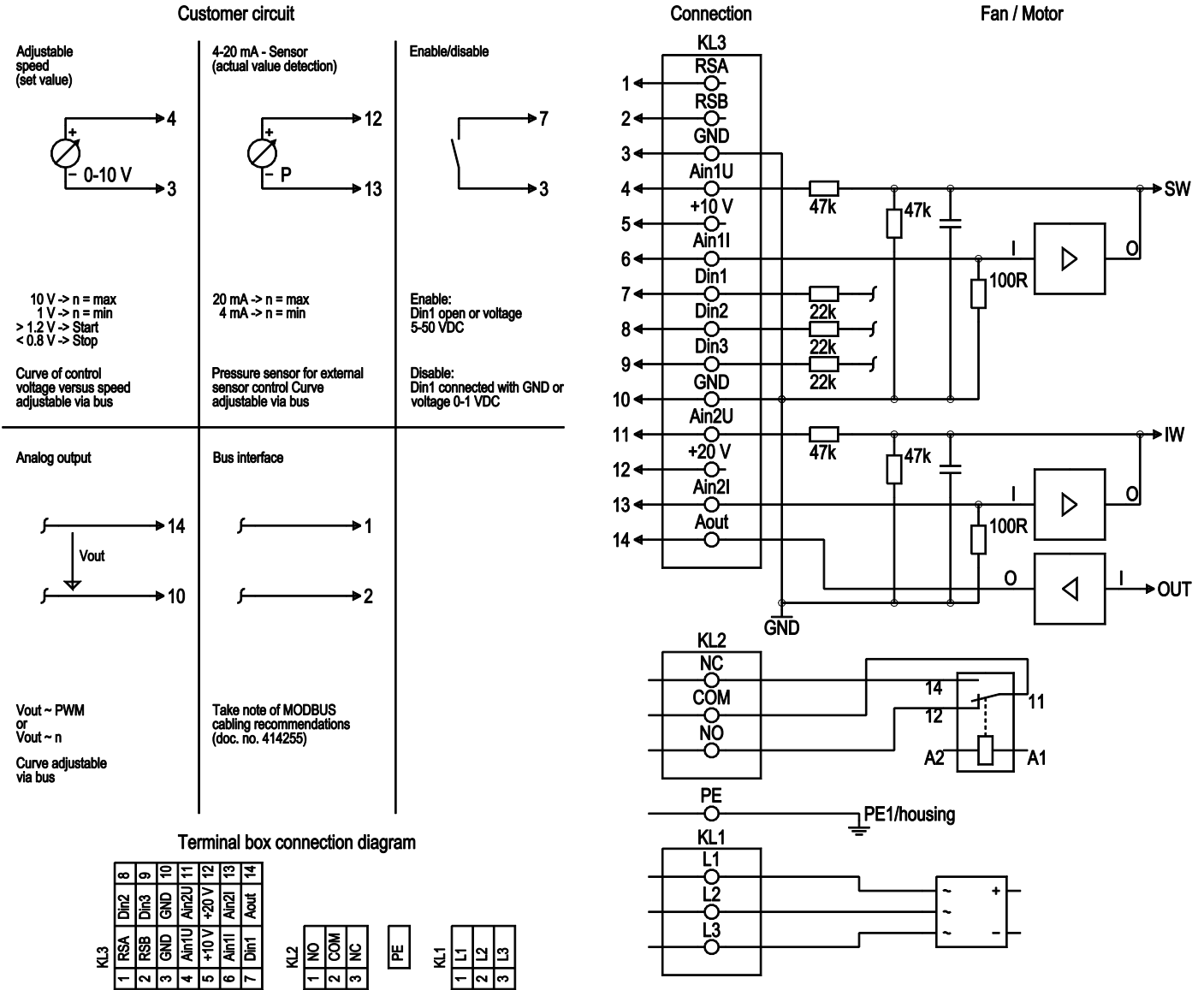


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Connection diagram



No.	Conn.	Designation	Function/assignment
KL 1	1	L1	Supply connection, power supply; for nominal voltage range see technical data
KL 1	2	L2	Supply connection, power supply; for nominal voltage range see technical data
KL 1	3	L3	Supply connection, power supply; for nominal voltage range see technical data
PE		PE	Ground connection, PE connection
KL 2	1	NO	Status relay, floating status contact, make for failure
KL2	2	COM	Status relay, floating status contact, changeover contact, common connection, contact rating 250 VAC / max. 2 A (AC1) / min. 10 mA
KL2	3	NC	Status relay, floating status contact, break for failure
KL 3	1	RSA	Bus connection RS485, RSA, MODBUS-RTU; SELV
KL 3	2	RSB	Bus connection RS485, RSB, MODBUS-RTU; SELV
KL 3	3 / 10	GND	Reference ground for control interface; SELV
KL 3	4	Ain1 U	Analog input 1, set value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain1I; SELV



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No.	Conn.	Designation	Function/assignment
KL 3	5	+ 10 V	Fixed voltage output 10 VDC, +10 V \pm 3%, max. 10 mA, short-circuit-proof power supply for external devices (e.g. pot); SELV
KL 3	6	Ain1 I	Analog input 1, set value: 4-20 mA, $R_i = 100 \Omega$, adjustable curve, only usable as alternative to input Ain1U; SELV
KL 3	7	Din1	Digital input 1: enable electronics, enable: pin open or applied voltage 5-50 VDC disable: bridge to GND or applied voltage < 1 VDC reset function: triggers software reset after a level change to < 1 VDC; SELV
KL 3	8	Din2	Digital input 2: Switching parameter sets 1/2, according to EEPROM setting, the valid or used parameter set can be selected via bus or via digital input DIN2. Parameter set 1: pin open or applied voltage 5-50 VDC Parameter set 2: bridge to GND or applied voltage < 1 VDC; SELV
KL 3	9	Din3	Digital input 3: according to EEPROM setting, the integrated controller's direction of action can be selected via bus or digital input Din3; normal: pin open or applied voltage 5-50 VDC inverse: bridge to GND or applied voltage < 1 VDC; SELV
KL 3	11	Ain2 U	Analog input 2, measured value: 0-10 V, $R_i = 100 \text{ k}\Omega$, adjustable curve, only usable as alternative to input Ain2I; SELV
KL 3	12	+ 20 V	Fixed voltage output 20 VDC, +20 V \pm 25/-10%, max. 50 mA, short-circuit-proof power supply for external devices (e.g. sensors); SELV or: +24 VDC input for parameter setting without line voltage
KL 3	13	Ain2 I	Analog input 2, measured value: 4-20 mA, $R_i = 100 \Omega$, adjustable curve, only usable as alternative to input Ain2U; SELV
KL 3	14	Aout	Analog output 0-10 VDC, max. 5 mA, output of current motor modulation level / motor speed adjustable curve; SELV

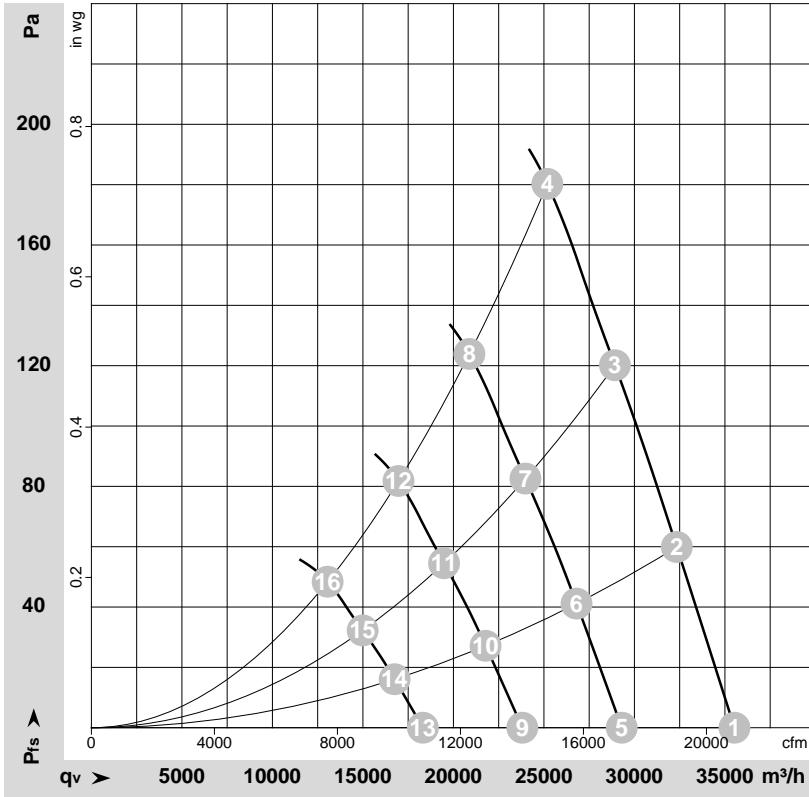


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Curves: Air performance 50 Hz



$\rho = 1.15 \text{ kg/m}^3 \pm 2 \%$

Measurement: LU-170333-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebmpapst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	LwA _{out}	q _v	P _{fs}	q _v	P _{fs}
	V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m ³ /h	Pa	cfm	in. wg
1	400	50	970	1498	2.33	74	81	81	35525	0	20910	0.00
2	400	50	965	1846	2.84	72	80	79	32340	60	19035	0.24
3	400	50	965	2193	3.36	73	80	79	28925	120	17025	0.48
4	400	50	960	2580	4.00	75	82	82	25190	180	14825	0.72
5	400	50	800	840	1.31	69	77	76	29300	0	17245	0.00
6	400	50	800	1054	1.62	68	75	74	26800	42	15775	0.17
7	400	50	800	1249	1.91	68	75	74	23980	83	14115	0.33
8	400	50	800	1411	2.16	70	77	77	20880	124	12290	0.50
9	400	50	650	451	0.70	64	71	71	23805	0	14010	0.00
10	400	50	650	565	0.87	62	70	69	21775	28	12815	0.11
11	400	50	650	670	1.03	63	70	69	19485	55	11465	0.22
12	400	50	650	757	1.16	65	72	72	16965	82	9985	0.33
13	400	50	500	205	0.32	57	65	64	18315	0	10780	0.00
14	400	50	500	257	0.40	56	63	62	16750	16	9860	0.06
15	400	50	500	305	0.47	56	63	62	14985	32	8820	0.13
16	400	50	500	345	0.53	58	65	65	13050	48	7680	0.19

U = Voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
 LwA_{out} = Sound power level outlet side · q_v = Air flow · P_{fs} = Pressure increase

