

EC axial fan - HyBlade

sickled blades (S series)

with full round nozzle, Transformator fan

W3G990-CU32-85 ebmpapst Datasheet

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Nominal data

Type	W3G990-CU32-85	
Motor	M3G150-IF	
Phase		3~
Nominal voltage	VAC	200
Nominal voltage range	VAC	200 .. 240
Frequency	Hz	50/60
Type of data definition		fa
Speed (rpm)	min ⁻¹	750
Power input	W	1350
Current draw	A	4.2
Max. back pressure	Pa	130
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	60

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations



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Technical features

Mass	57.3 kg
Size	990 mm
Motor size	150
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium, coated in black
Material of blades	Aluminium sheet insert (coated in black), sprayed with PP plastic
Material of wall ring	Sheet steel, galvanised and plastic-coated in light grey (RAL 7035)
Material of guard grille	Steel, coated with light grey plastic (RAL7035)
Number of blades	5
Blade angle	0°
Direction of air flow	A
Direction of rotation	Counter-clockwise, seen on rotor
Type of protection	IP55
Insulation class	"F"
Humidity (F) / environmental protection class (H)	H2+T
Note ambient temperature	Occasional start-up between -40 °C and -25 °C is permissible. For continuous operation at ambient temperatures below -25 °C (e.g. refrigeration applications), a fan version with special low-temperature bearings must be used.
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Shaft horizontal or rotor on top
Condensation drainage holes	On the stator side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Operation and alarm display - Input for sensor 0-10 V or 4-20 mA - External 24 V input (programming) - External release input - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive - RS485 MODBUS RTU - Soft start -Maximum EEPROM write cycles 100,000 - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection
EMC interference immunity	Acc. to EN 61000-6-2 (industrial environment)
EMC interference emission	Acc. to EN 61000-6-4 (industrial environment)



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Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical connection	Terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE
Approval	UL 1004-7 + 60730-1; CSA C22.2 no. 77 + CAN/CSA-E60730-1; EAC

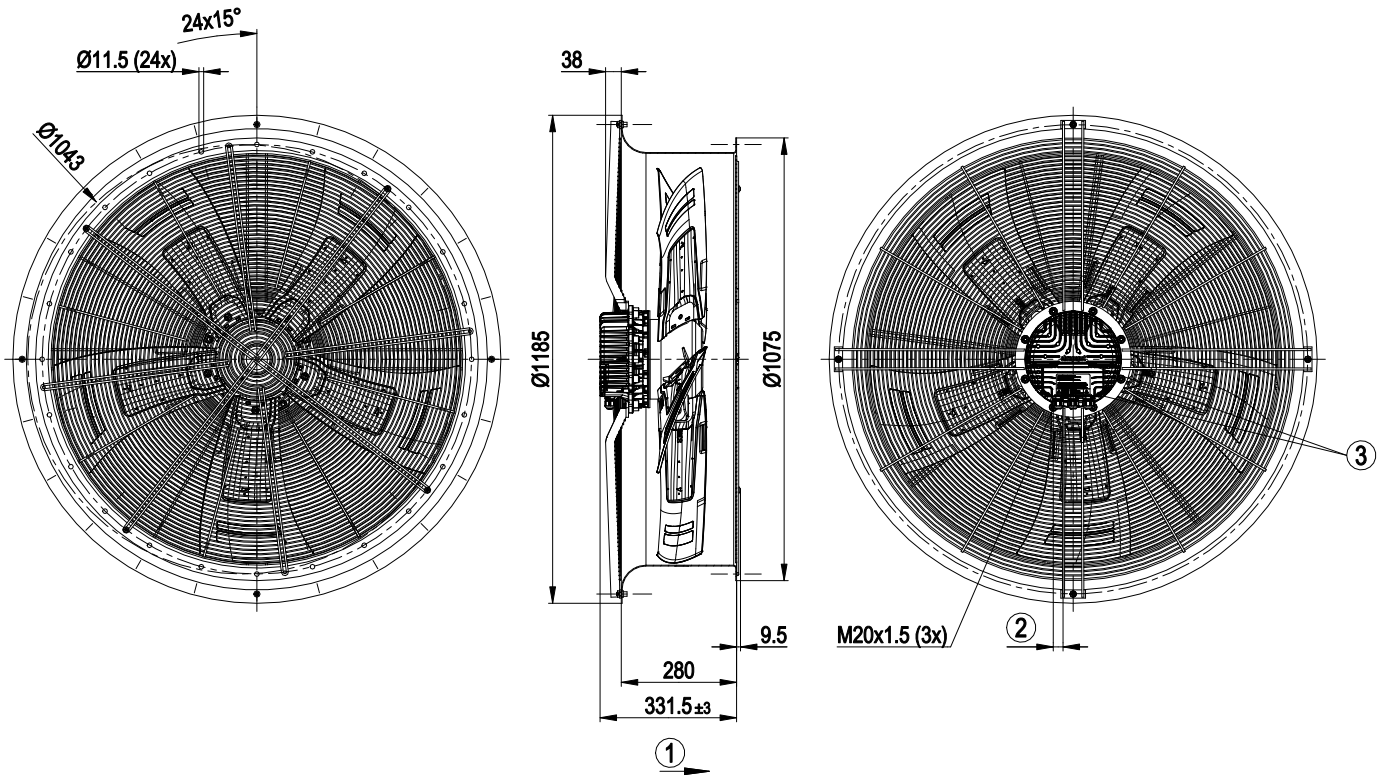


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Product drawing



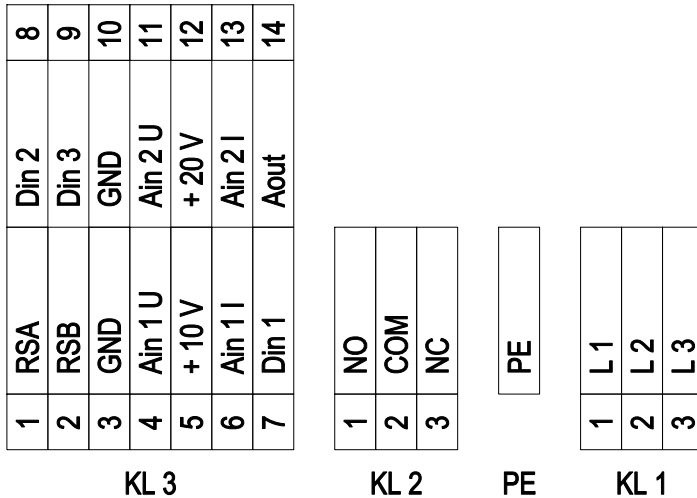
1	Direction of air flow "A"
2	Cable diameter min. 5 mm, max. 13 mm, tightening torque 4 ± 0.6 Nm
3	Tightening torque 3.5 ± 0.5 Nm

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Connection screen



No.	Conn.	Designation	Function / assignment
KL 1	1	L1	Mains supply connection, supply voltage 3~200-240 VAC; 50/60 Hz
KL 1	2	L2	Mains supply connection, supply voltage 3~200-240 VAC; 50/60 Hz
KL 1	3	L3	Mains supply connection, supply voltage 3~200-240 VAC; 50/60 Hz
PE		PE	Earth connection, PE connection
KL 2	1	NO	Status relay, floating status contact; normally open; close with error
KL2	2	COM	Status relay; floating status contact; changeover contact; common connection; contact rating 250 VAC / max. 2 A (AC1) / min. 10 mA
KL2	3	NC	Status relay, floating status contact; break with error
KL 3	1	RSA	Bus connection RS-485, RSA, MODBUS RTU; SELV
KL 3	2	RSB	Bus connection RS-485, RSB, MODBUS RTU; SELV
KL 3	3 / 10	GND	Signal ground for control interface; SELV
KL 3	4	Ain1 U	Analogue input 1, set value: 0-10 V, Ri = 100 kΩ, parametrisable curve, only usable as alternative to input Ain1; SELV
KL 3	5	+ 10 V	Fixed voltage output 10 VDC, +10 V ±3%, max. 10 mA, short-circuit-proof, power supply for external devices (e.g. potentiometer), SELV
KL 3	6	Ain1 I	Analogue input 1, set value: 4-20 mA; Ri = 100 Ω, parametrisable curve, only usable as alternative to input Ain1 U; SELV
KL 3	7	Din1	Digital input 1: enabling of electronics, enabling: open pin or applied voltage 5-50 VDC disabling: bridge to GND or applied voltage <1 VDC reset function: triggers software reset after a level change to <1 VDC; SELV
KL 3	8	Din2	Digital input 2: parameter set switch 1/2, according to EEPROM setting, the valid/used parameter set can be selected via bus or via digital input DIN2. Parameter set 1: open pin or applied voltage 5-50 VDC Parameter set 2: bridge to GND or applied voltage <1 VDC; SELV
KL 3	9	Din3	Digital input 3: controller function of integrated controller, according to EEPROM setting, the controller function of the integrated controller is normally/inversely selectable per bus or per digital input normal: open pin or applied voltage 5-50 VDC inverse: bridge to GND or applied voltage <1 VDC; SELV
KL 3	11	Ain2 U	Analogue input 2, actual value: 0-10 V, Ri = 100 kΩ, parametrisable curve, only usable as alternative to input Ain2; SELV
KL 3	12	+ 20 V	Fixed voltage output 20 VDC, +20 V ±5/-10%, max. 50 mA, short-circuit-proof, power supply for external devices (e.g. sensors); SELV



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No.	Conn.	Designation	Function / assignment
KL 3	13	Ain2 I	Analogue input 2, actual value: 4-20 mA, $R_i = 100\ \Omega$, parametrisable curve, only usable as alternative to input Ain2 U; SELV
KL 3	14	Aout	Analogue output 0-10 VDC, max. 5 mA, output of the current motor level control coefficient / motor speed parametrisable curve; SELV

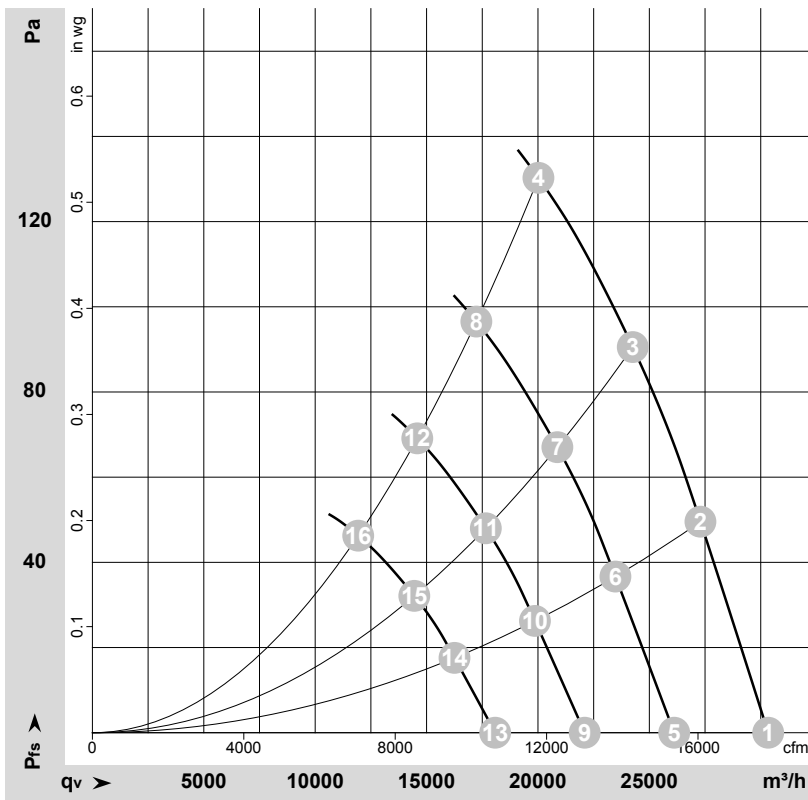


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Charts: Air flow 50 Hz



$$\rho = 1.15 \text{ kg/m}^3 \pm 2 \%$$

Measurement: LU-177469-1

Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebm-papst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

Measured values

	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	LwA _{out}	q _v	P _{fs}	q _v	P _{fs}
	V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m ³ /h	Pa	cfm	in. wg
1	200	50	750	1350	4.20	75	81	81	30335	0	17855	0.00
2	200	50	750	1569	4.85	73	80	80	27295	50	16065	0.20
3	200	50	750	1723	5.32	73	80	79	24255	90	14275	0.36
4	200	50	750	1850	5.70	78	84	84	20020	130	11785	0.52
5	200	50	650	863	2.68	71	78	77	26115	0	15370	0.00
6	200	50	650	997	3.08	69	76	76	23475	37	13820	0.15
7	200	50	650	1098	3.39	69	76	76	20870	67	12285	0.27
8	200	50	650	1186	3.63	74	80	80	17235	97	10145	0.39
9	200	50	550	523	1.62	67	73	73	22100	0	13005	0.00
10	200	50	550	604	1.87	65	72	72	19865	26	11690	0.10
11	200	50	550	665	2.05	65	72	71	17660	48	10395	0.19
12	200	50	550	718	2.20	70	76	76	14585	69	8585	0.28
13	200	50	450	286	0.89	62	68	68	18080	0	10640	0.00
14	200	50	450	331	1.02	60	67	67	16255	18	9565	0.07
15	200	50	450	364	1.12	60	66	66	14450	32	8505	0.13
16	200	50	450	393	1.21	65	71	71	11930	46	7020	0.18

U = Supply voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power input · I = Current draw · LpA_{in} = Sound pressure level inlet side · LwA_{in} = Sound power level inlet side · LwA_{out} = Sound power level outlet side
 q_v = Air flow · P_{fs} = Pressure increase

