

W3G800-GF05-01 ebmpapst Datasheet

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Nominal data

Type	W3G800-GF05-01	
Motor	M3G150-NA	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min ⁻¹	1430
Power consumption	W	4000
Current draw	A	6.2
Max. back pressure	Pa	300
Max. back pressure	in. wg	1.2
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	60

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to Commission Regulation (EU) 327/2011 (EN 17166)

		Actual	Req. 2015			
01 Overall efficiency η_{es}	%	48.8	37.6	09 Power consumption P_{ed}	kW	4.12
02 Measurement category		A		09 Air flow q_v	m ³ /h	19970
03 Efficiency category		Static		09 Pressure increase p_{fs}	Pa	363
04 Efficiency grade N		51.2	40	10 Speed (rpm) n	min ⁻¹	1420
05 Variable speed drive		Yes		11 Specific ratio*		1.00

Data obtained at optimum efficiency level.

* Specific ratio = $1 + p_s / 100\,000\text{ Pa}$

LU-128882

The efficiency values displayed for achieving conformity with the Ecodesign Regulation EU 327/2011 has been reached with defined air duct components (e.g. inlet rings).
The dimensions must be requested from ebm-papst. If other air conduction geometries are used on the installation side, the ebm-papst evaluation loses its validity/the conformity must be confirmed again.
The product does not fall within the scope of Regulation (EU) 2019/1781 due to the exception specified in Article 2 (2a) (motors completely integrated into a product).



Technical description

Weight	56.5 kg
Size	800 mm
Motor size	150
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum, painted black
Blade material	Die-cast aluminum
Fan housing material	Sheet steel, galvanized and coated with black plastic (RAL 9005)
Guard grille material	Steel, coated with black plastic (RAL 9005)
Number of blades	5
Blade pitch	-5°
Airflow direction	V
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	"F"
Moisture (F) / Environmental (H) protection class	H2
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	<ul style="list-style-type: none"> - Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - External 24 V input (parameter setting) - External release input - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - EEPROM write cycles: 100,000 maximum - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC interference emission	According to EN 61000-6-3 (household environment), except EN 61000-3-2 for professionally used equipment with a total rated power greater than 1 kW
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Terminal box
Motor protection	Reverse polarity and locked-rotor protection

EC axial fan

sickle-shaped blades (S series)

with square full nozzle

Protection class assignment	I; If a protective earth is connected by the customer This component for installation may have several local protection classes. This information relates to this component's basic design. The final protection class is based on the component's intended installation and connection.
Conformity with standards	EN 61800-5-1; CE
Approval	UL 1004-7 + 60730-1; CSA C22.2 No. 77 + CAN/CSA-E60730-1

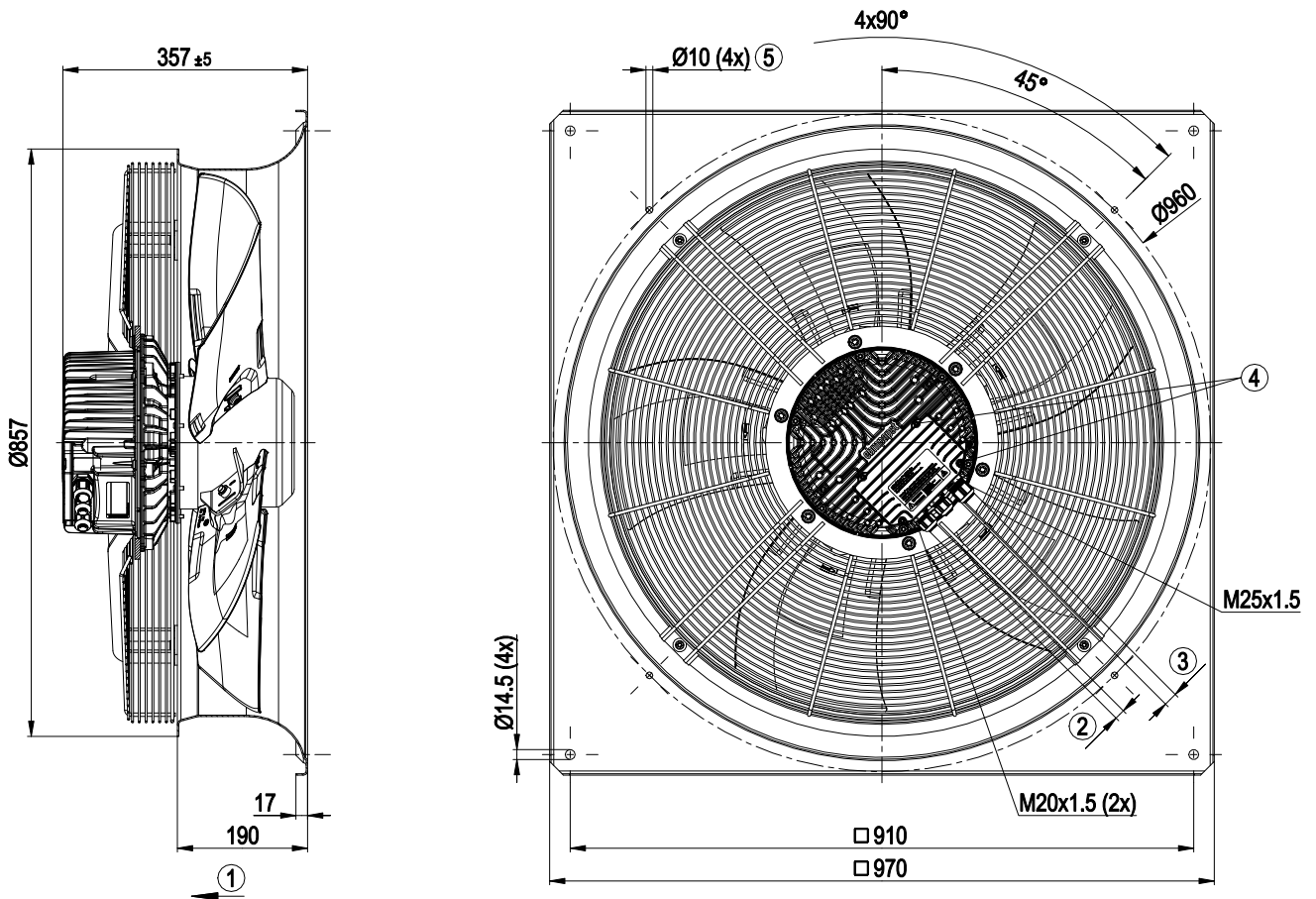


EC axial fan

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Product drawing



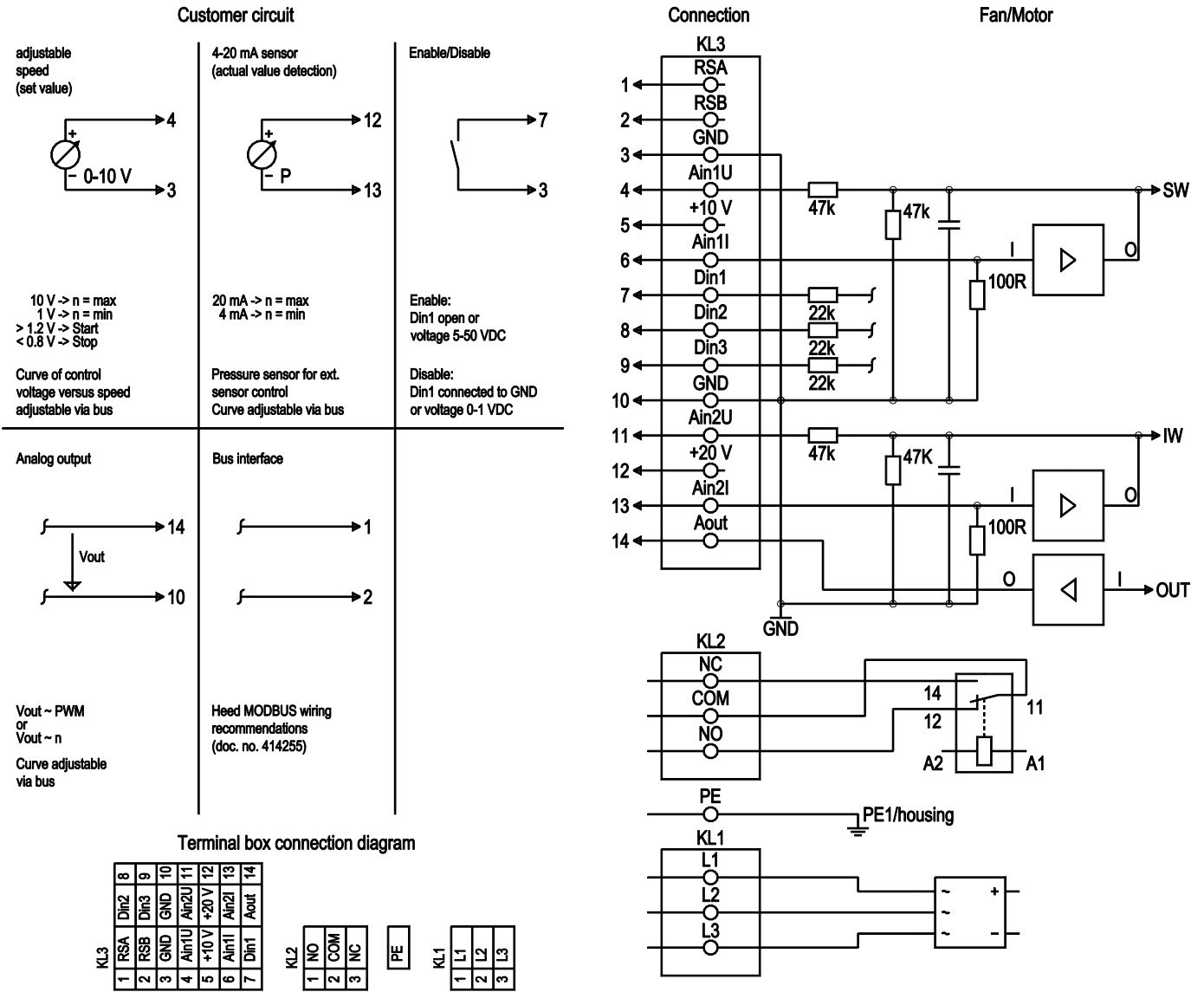
1	Direction of air flow "V"
2	Cable diameter min. 4 mm, max. 10 mm, tightening torque 4 ± 0.6 Nm
3	Cable diameter min. 9 mm, max. 16 mm, tightening torque 6 ± 0.9 Nm
4	Tightening torque 3.5 ± 0.5 Nm
5	Attachment holes for FlowGrid 80000-2-2957 (not included in scope of delivery)



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Connection diagram



No.	Conn.	Designation	Function/assignment
KL 1	1	L1	Supply connection, power supply, phase, see nameplate for voltage range
KL 1	2	L2	Supply connection, power supply, phase, see nameplate for voltage range
KL 1	3	L3	Supply connection, power supply, phase, see nameplate for voltage range
PE		PE	Ground connection, PE connection
KL 2	1	NO	Status relay, floating status contact, make for failure
KL 2	2	COM	Status relay, floating status contact, changeover contact, common connection, contact rating, max. 250 VAC/2 A (AC1)/min. 10 mA
KL 2	3	NC	Status relay, floating status contact, break for failure
KL 3	1	RSA	Bus connection RS485, RSA, MODBUS RTU; SELV
KL 3	2	RSB	Bus connection RS485, RSB, MODBUS RTU; SELV
KL 3	3 / 10	GND	Reference ground for control interface, SELV
KL 3	4	Ain1 U	Analog input 1, set value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain1 I; SELV



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No.	Conn.	Designation	Function/assignment
KL 3	5	+ 10 V	Fixed voltage output 10 VDC, +10 V \pm 3%, max. 10 mA, short-circuit-proof, power supply for external devices (e.g. pot); SELV
KL 3	6	Ain1 I	Analog input 1, set value: 4-20 mA, Ri = 100 Ω , adjustable curve, only usable as alternative to input Ain1 U; SELV
KL 3	7	Din1	Digital input 1: enable electronics, enable: pin open or applied voltage 5-50 VDC disable: bridge to GND or applied voltage < 1 VDC reset function: triggers software reset after a level change to < 1 VDC; SELV
KL 3	8	Din2	Digital input 2: Switching parameter sets 1/2, according to EEPROM setting, the valid or used parameter set can be selected via bus or via digital input DIN2. Parameter set 1: pin open or applied voltage 5-50 VDC Parameter set 2: bridge to GND or applied voltage < 1 VDC; SELV
KL 3	9	Din3	Digital input 3: Direction of action of integrated controller, according to EEPROM setting, the direction of action of the integrated controller can be selected as normal/inverse via bus or digital input Normal: Pin open or applied voltage 5-50 VDC Inverse: Bridge to GND or applied voltage < 1 VDC; SELV
KL 3	11	Ain2 U	Analog input 2, measured value: 0-10 V, Ri = 100 k Ω , adjustable curve, only usable as alternative to input Ain2 I; SELV
KL 3	12	+ 20 V	Fixed voltage output 20 VDC, +20 V +25/-10%, max. 50 mA, short-circuit-proof, power supply for external devices (e.g. sensors); SELV Alternatively: +24 VDC input for parameterization without line voltage
KL 3	13	Ain2 I	Analog input 2, measured value: 4-20 mA, Ri = 100 Ω , adjustable curve, only usable as alternative to input Ain2 U; SELV
KL 3	14	Aout	Analog output 0-10 V, max. 5 mA, output of current motor modulation level; adjustable curve; SELV

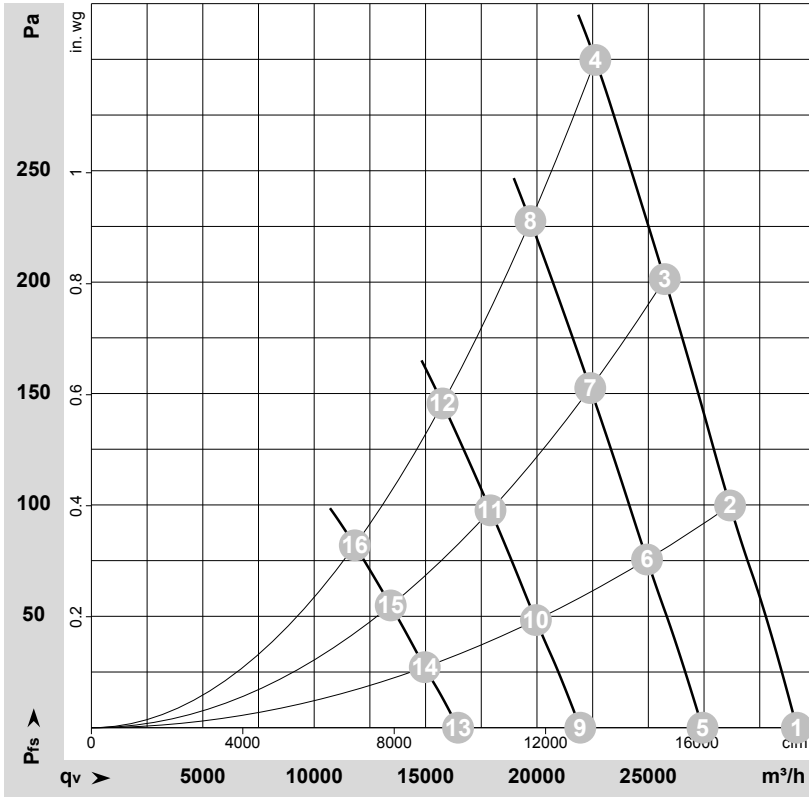


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Curves: Air performance 50 Hz



$\rho = 1.15 \text{ kg/m}^3 \pm 2 \%$

Measurement: LU-128882-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	LwA _{out}	q _v	P _{fs}	q _v	P _{fs}
	V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m ³ /h	Pa	cfm	in. wg
1	400	50	1430	2715	4.21	80	87	87	31665	0	18640	0.00
2	400	50	1430	3160	4.91	76	84	83	28670	100	16875	0.40
3	400	50	1430	3629	5.63	76	83	83	25735	200	15145	0.80
4	400	50	1430	4000	6.20	77	84	83	22620	300	13315	1.20
5	400	50	1250	1765	2.74	76	83	83	27430	0	16145	0.00
6	400	50	1250	2086	3.24	73	80	80	24940	75	14680	0.30
7	400	50	1250	2391	3.71	72	79	79	22390	152	13180	0.61
8	400	50	1250	2638	4.09	73	80	80	19705	228	11595	0.92
9	400	50	1000	904	1.40	71	78	78	21945	0	12915	0.00
10	400	50	1000	1068	1.66	67	74	74	19955	48	11745	0.19
11	400	50	1000	1224	1.90	67	74	73	17915	98	10545	0.39
12	400	50	1000	1350	2.09	68	75	74	15765	146	9280	0.59
13	400	50	750	381	0.59	63	71	71	16460	0	9685	0.00
14	400	50	750	450	0.70	60	67	67	14965	27	8805	0.11
15	400	50	750	516	0.80	59	66	66	13435	55	7910	0.22
16	400	50	750	570	0.88	60	67	67	11820	82	6960	0.33

U = Voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
 LwA_{out} = Sound power level outlet side · q_v = Air flow · P_{fs} = Pressure increase

