

W3G560-DP68-35 ebmpapst Datasheet

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## Nominal data

Type	W3G560-DP68-35	
Motor	M3G112-GA	
Phase		1~
Nominal voltage	VAC	230
Nominal voltage range	VAC	200 .. 277
Frequency	Hz	50/60
Type of data definition		ml
Speed	min <sup>-1</sup>	1000
Power input	W	400
Current draw	A	1.8
Max. back pressure	Pa	100
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	60

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit  
Subject to alterations

## Data according to ErP directive

Installation category	A
Efficiency category	Static
Variable speed drive	Yes
Specific ratio*	1.00

\* Specific ratio =  $1 + p_b / 100\,000\text{ Pa}$

		Actual	Request 2013	Request 2015
Overall efficiency $\eta_{es}$	%	41.1	27.2	31.2
Efficiency grade N		49.9	36	40
Power input $P_{ed}$	kW	0.4		
Air flow $q_v$	m <sup>3</sup> /h	5245		
Pressure increase $p_{fs}$	Pa	102		
Speed n	min <sup>-1</sup>	995		

Data definition with optimum efficiency. LU-118048  
The ErP data is determined using a motor-impeller combination in a standardised measurement configuration.



## Technical features

<b>Mass</b>	18.7 kg
<b>Size</b>	560 mm
<b>Surface of rotor</b>	Coated in black
<b>Material of electronics housing</b>	Die-cast aluminium, coated in black
<b>Material of blades</b>	Aluminium sheet insert (coated in black), sprayed with PP plastic
<b>Material of mounting ring</b>	Steel, galvanised and coated in black plastic (RAL9005)
<b>Material of wall ring</b>	Sheet steel, galvanised and coated in black plastic (RAL 9005)
<b>Number of blades</b>	5
<b>Blade angle</b>	-5°
<b>Direction of air flow</b>	"A"
<b>Direction of rotation</b>	Clockwise, seen on rotor
<b>Type of protection</b>	IP 54
<b>Insulation class</b>	"B"
<b>Humidity class</b>	F4-2
<b>Max. permissible ambient motor temp. (transp./ storage)</b>	+80 °C
<b>Min. permissible ambient motor temp. (transp./storage)</b>	-40 °C
<b>Mounting position</b>	Shaft horizontal or rotor on top
<b>Condensate discharge holes</b>	On the stator side
<b>Operation mode</b>	S1
<b>Motor bearing</b>	Ball bearing
<b>Technical features</b>	<ul style="list-style-type: none"> <li>- Output 10 VDC, max. 10 mA</li> <li>- Output 20 VDC, max. 50 mA</li> <li>- Output for slave 0-10 V</li> <li>- Operation and alarm display</li> <li>- Direction of rotation selection counter-clockwise / clockwise</li> <li>- Input for sensor 0-10 V or 4-20 mA</li> <li>- External 24 V input (programming)</li> <li>- Alarm relay</li> <li>- Integrated PID controller</li> <li>- Motor current limit</li> <li>- PFC, active</li> <li>- RS485 MODBUS RTU</li> <li>- Soft start</li> <li>- Control input 0-10 VDC / PWM</li> <li>- Control interface with SELV potential safely disconnected from the mains</li> <li>- Over-temperature protected electronics / motor</li> <li>- Line undervoltage / phase failure detection</li> </ul>
<b>EMC interference immunity</b>	Acc. to EN 61000-6-2 (industrial environment)
<b>EMC harmonics</b>	Acc. to EN 61000-3-2/3
<b>EMC interference emission</b>	Acc. to EN 55022 (Class A, industrial environment)
<b>Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)</b>	<= 3.5 mA
<b>Electrical leads</b>	Via terminal box
<b>Motor protection</b>	Thermal overload protector (TOP) wired internally
<b>Protection class</b>	I (if protective earth is connected by customer)
<b>Product conforming to standard</b>	EN 61800-5-1; CE

W3G560-DP68-35

# EC axial fan - HyBlade®

sickled blades (S series)

for agricultural ventilation

Approval

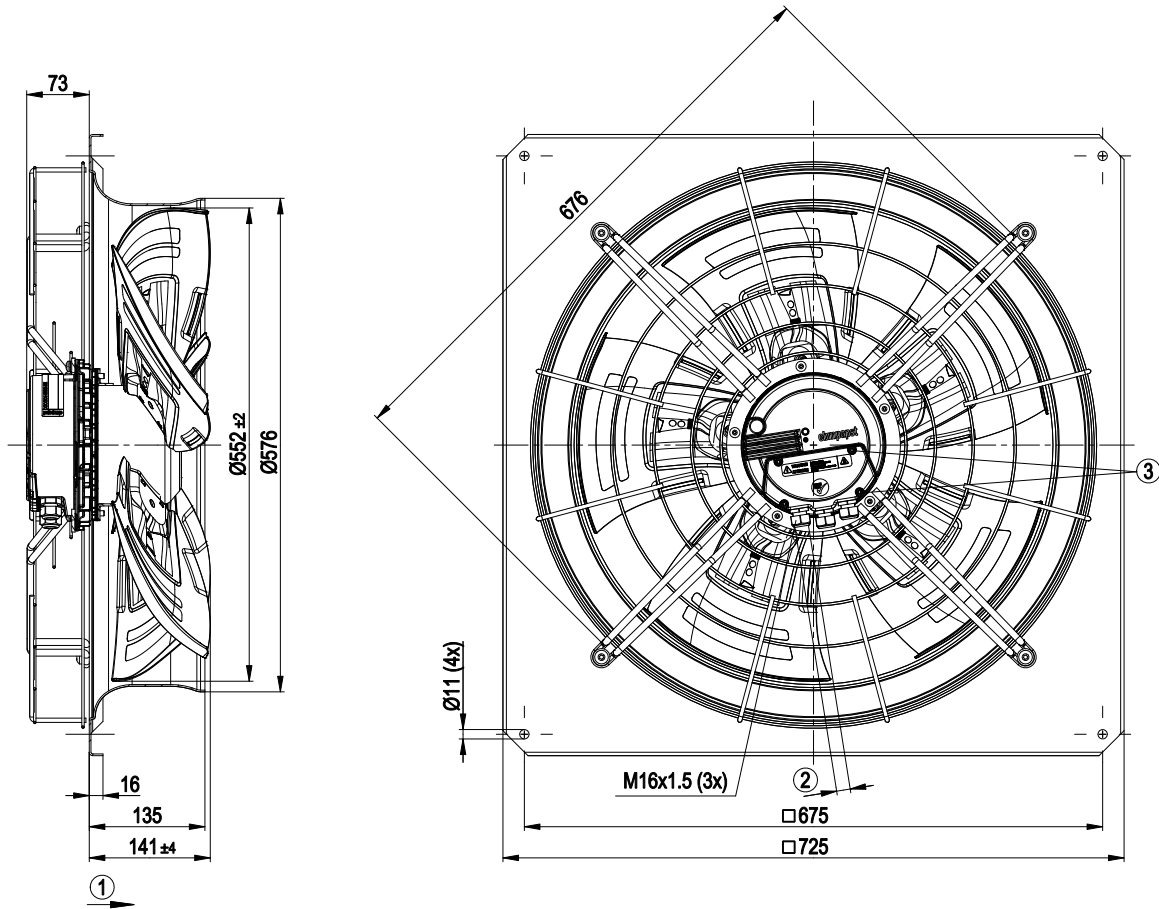
EAC



# EC axial fan - HyBlade®

sickled blades (S series)  
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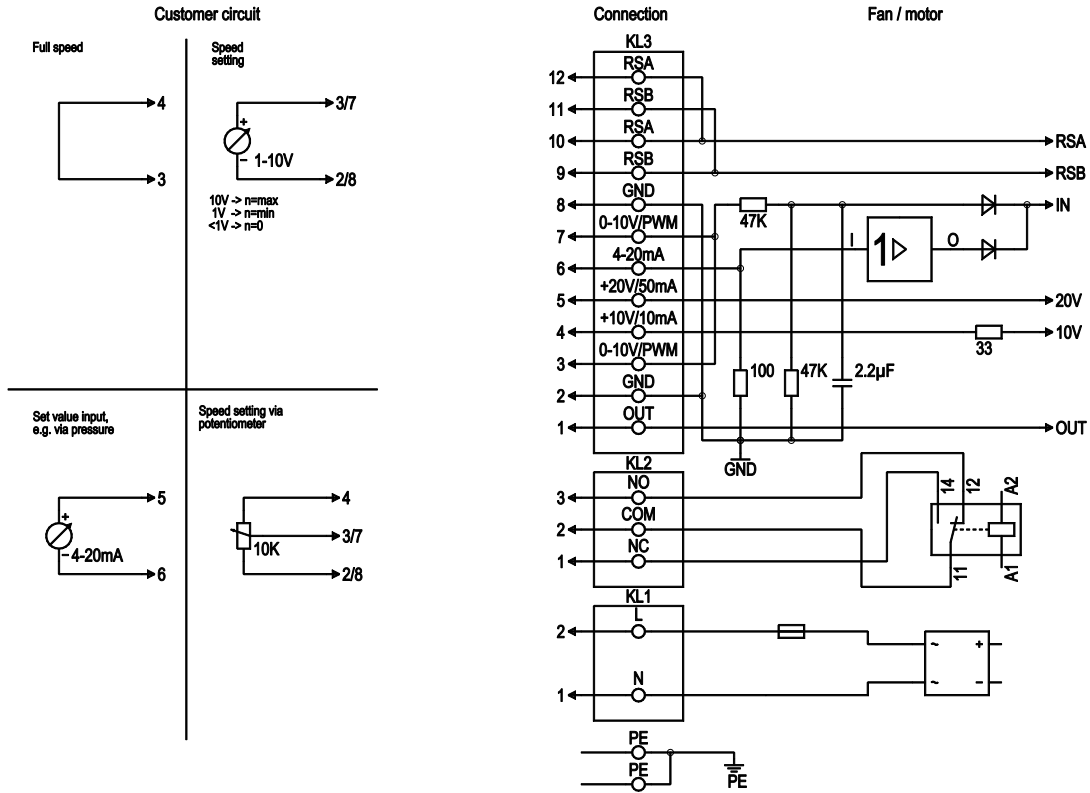
## Product drawing



1	Direction of air flow "A"
2	Cable diameter: min. 4 mm, max. 10 mm, tightening torque: 2.5±0.4 Nm
3	Tightening torque 3.5±0.5 Nm

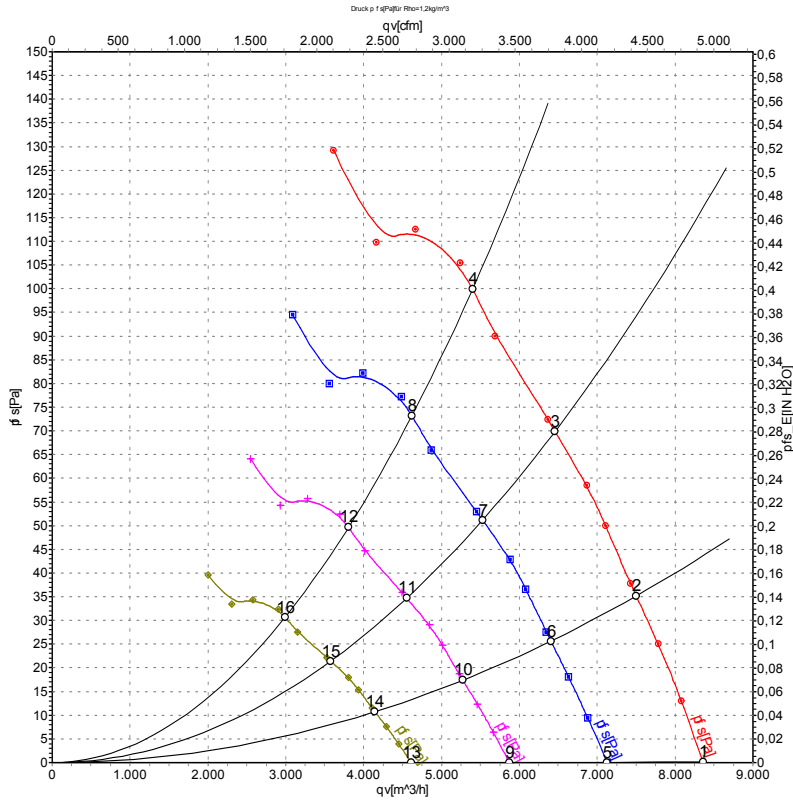


## Connection screen



No.	Conn.	Designation	Function / assignment
PE	-	PE	Protective earth connection
KL1	1, 2	N, L	Supply voltage, 50/60 Hz
KL2	1	NC	Floating status message contact, break for failure
KL2	2	COM	Floating status message contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status message contact, normally open, make for failure
KL3	1	OUT	Analogue output, 0-10 VDC, max. 3 mA, SELV, Output of the current motor level control coefficient: 1 V corresponds to 10% level control coefficient, 10 V correspond to 100% level control coefficient.
KL3	2, 8	GND	Reference mass for control interface, SELV
KL3	3, 7	0-10 V	Use control / actual value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (+/- 3%), max. 10 mA, Supply voltage for ext. devices (e.g. potentiometer), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25%/-10%), max. 50 mA Supply voltage for ext. devices (e.g. sensors), SELV
KL3	6	4-20 mA	Use control / actual value input 4-20 mA, impedance 100 Ω, only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for MODBUS, RSB
KL3	10, 12	RSA	RS485 interface for MODBUS, RSA

## Charts: Air flow 50 Hz



Measurement: LU-118048

Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebmpapst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

## Measured values

	U	f	n	P <sub>ed</sub>	I	LpA <sub>in</sub>	LwA <sub>in</sub>	LwA <sub>out</sub>	qv	p <sub>fs</sub>
	V	Hz	min <sup>-1</sup>	W	A	dB(A)	dB(A)	dB(A)	m <sup>3</sup> /h	Pa
1	230	50	1000	293	1.29	60	67	67	8360	0
2	230	50	1000	336	1.48	59	66	66	7500	35
3	230	50	1000	369	1.61	60	67	66	6460	70
4	230	50	1000	400	1.80	62	69	68	5400	100
5	230	50	850	182	0.80	57	64	64	7130	0
6	230	50	850	209	0.92	56	63	62	6405	26
7	230	50	850	231	1.01	57	63	62	5530	51
8	230	50	850	249	1.09	59	65	65	4620	73
9	230	50	700	102	0.45	53	59	59	5870	0
10	230	50	700	117	0.51	52	58	58	5275	17
11	230	50	700	129	0.57	52	59	58	4550	35
12	230	50	700	139	0.61	55	61	61	3805	50
13	230	50	550	49	0.22	47	54	54	4610	0
14	230	50	550	57	0.25	46	53	53	4145	11
15	230	50	550	63	0.27	47	54	53	3575	21
16	230	50	550	68	0.30	49	56	55	2990	31

U = Supply voltage · f = Frequency · n = Speed · P<sub>ed</sub> = Power input · I = Current draw · LpA<sub>in</sub> = Sound pressure level inlet side · LwA<sub>in</sub> = Sound power level inlet side · LwA<sub>out</sub> = Sound power level outlet side  
qv = Air flow · p<sub>fs</sub> = Pressure increase

