

EC axial fan - HyBlade

sickled blades (S series)
with full square nozzle

W3G500-GM03-I1 ebmpapst Datasheet
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Nominal data

Type	W3G500-GM03-I1	
Motor	M3G084-GF	
Phase		1~
Nominal voltage	VAC	230
Nominal voltage range	VAC	200 .. 277
Frequency	Hz	50/60
Type of data definition		ml
Speed (rpm)	min ⁻¹	1370
Power input	W	650
Current draw	A	2.9
Max. back pressure	Pa	150
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	50

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations

Data according to ErP directive

		Actual	Request 2015
01 Overall efficiency η_{es}	%	44.8	32.4
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		52.4	40
05 Variable speed drive		Yes	

Data definition with optimum efficiency.
The ErP data is determined using a motor-impeller combination in a standardised measurement configuration.

09 Power input P_{ed}	kW	0.64
09 Air flow q_v	m³/h	5760
09 Pressure increase p_{fs}	Pa	165
10 Speed (rpm) n	min ⁻¹	1375
11 Specific ratio*		1.00

* Specific ratio = $1 + p_{fs} / 100\,000\text{ Pa}$

LU-182217



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Technical features

Mass	12.2 kg
Size	500 mm
Surface of rotor	Coated in black
Material of terminal box	PP plastic
Material of electronics housing	Die-cast aluminium, coated in black
Material of blades	Press-fitted sheet steel blank, sprayed with PP plastic
Material of wall ring	Sheet steel, galvanised and coated in black plastic (RAL 9005)
Material of guard grille	Steel, coated in black plastic (RAL9005)
Number of blades	5
Direction of air flow	"V"
Direction of rotation	Counter-clockwise, seen on rotor
Type of protection	IP 55
Insulation class	"F"
Humidity (F)/environmental protection class (H)	F4-1
Note ambient temperature	Occasional start-up between -40°C and -25°C is permissible. For continuous operation at ambient temperatures below -25°C (e.g. refrigeration applications) we recommend our fan version with special low-temperature bearings.
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensate discharge holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Operation and alarm display - Alarm relay - Integrated PID controller - Output limit - Motor current limit - PFC, active - RS485 MODBUS RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical leads	Via terminal box
Motor protection	Thermal overload protector (TOP) wired internally
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE
Approval	UL 1004-7 + 60730; C22.2 Nr.77 + CAN/CSA-E60730-1; EAC
Remark	Standard conformity as per EN 60335-1 in preparation

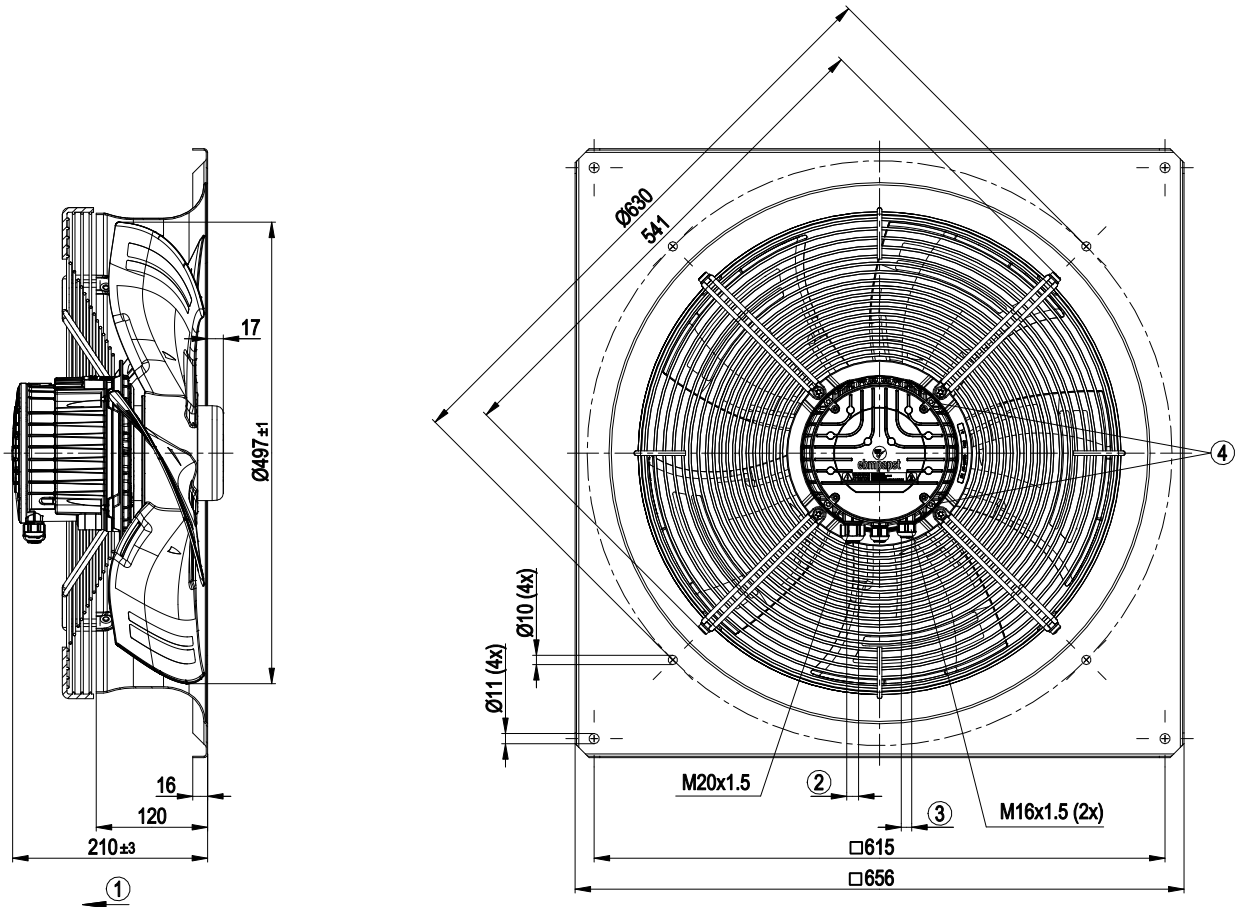


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Product drawing



1	Direction of air flow "V"
2	Cable diameter min. 8 mm, max. 12 mm, tightening torque 2.5 ± 0.4 Nm
3	Cable diameter min. 6 mm, max. 10 mm, tightening torque 2.5 ± 0.4 Nm Cable diameter min. 4 mm, max. 7 mm, tightening torque 2.5 ± 0.4 Nm (use must be made of sealing ring provided)
4	Tightening torque 1.5 ± 0.2 Nm

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Connection screen

PE	PE	N		L	NC	COM	GND	RSA	RSB	0-10 V	+10 V	
1	2	3	4	5	6	7	8	9	10	11	12	

No.	Conn.	Designation	Function / assignment
	1	PE	Protective earth
	2	PE	Protective earth
	3	N	Power supply, neutral conductor
	4	-	not used
	5	L	Power supply, phase
	6	NC	Status relay, floating status contact, break for failure, contact rating 250 VAC / 2 A (AC1) min. 10 mA, basic insulation on mains side and reinforced insulation on control interface side
	7	COM	Status relay, floating status contact, common connection, contact rating 250 VAC / 2 A (AC1) / min. 10 mA, basic insulation on mains side and reinforced insulation on control interface side
	8	GND	Signal ground for control interface, SELV
	9	RSA	RS-485 interface for MODBUS, RSA; SELV
	10	RSB	RS-485 interface for MODBUS, RSB; SELV
	11	0-10 V	Analogue input (set value) SELV, 0-10 V, Ri=100kΩ, parametrisable curve
	12	+10 V	Fixed voltage output 10 VDC, SELV, +10 V ±3%, max. 10 mA, short-circuit-proof, power supply for external devices (e.g. potentiometer)

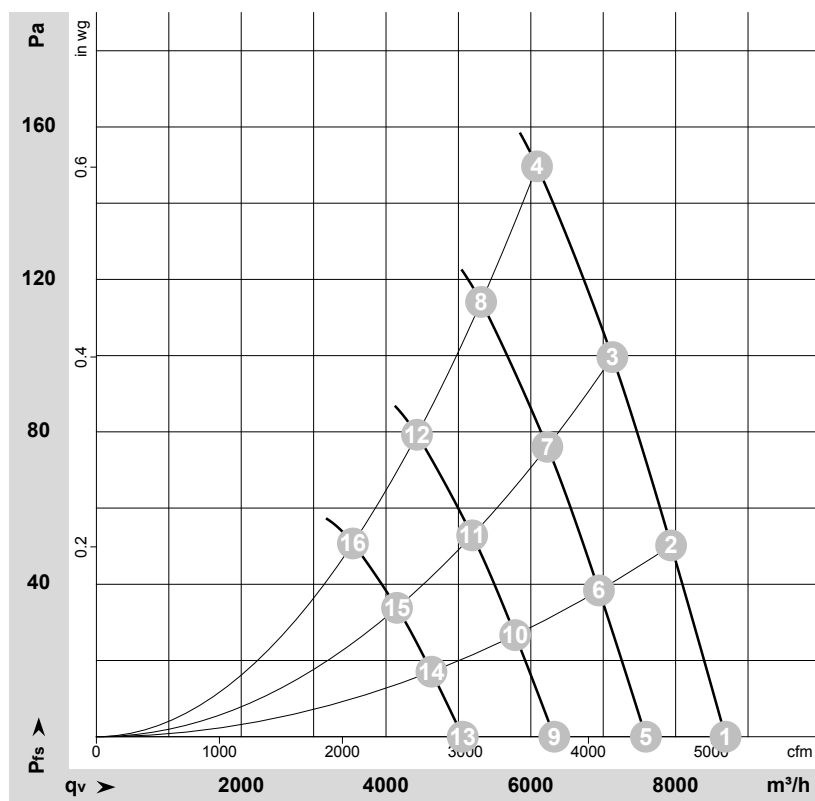


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Charts: Air flow 50 Hz



$$\rho = 1.15 \text{ kg/m}^3 \pm 2 \%$$

Measurement: LU-182217-1

Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebm-papst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

Measured values

	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	LwA _{out}	q _v	P _{fs}	q _v	P _{fs}
	V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m ³ /h	Pa	cfm	inH ₂ O
1	230	50	1370	476	2.09	66	74	73	8690	0	5115	0.00
2	230	50	1370	533	2.33	64	72	71	7940	50	4670	0.20
3	230	50	1370	586	2.56	63	71	70	7125	100	4195	0.40
4	230	50	1370	650	2.90	64	71	70	6085	150	3580	0.60
5	230	50	1200	317	1.39	63	70	69	7590	0	4465	0.00
6	230	50	1200	357	1.56	61	68	67	6940	39	4085	0.16
7	230	50	1200	391	1.71	60	67	66	6230	76	3665	0.31
8	230	50	1200	422	1.84	60	68	67	5315	114	3130	0.46
9	230	50	1000	183	0.80	58	66	65	6325	0	3725	0.00
10	230	50	1000	207	0.90	56	64	63	5785	27	3405	0.11
11	230	50	1000	226	0.99	55	63	62	5190	53	3055	0.21
12	230	50	1000	244	1.06	56	63	62	4430	79	2605	0.32
13	230	50	800	94	0.41	52	60	59	5060	0	2980	0.00
14	230	50	800	106	0.46	51	58	57	4625	17	2725	0.07
15	230	50	800	116	0.51	50	57	56	4150	34	2445	0.14
16	230	50	800	125	0.55	50	58	57	3540	51	2085	0.20

U = Supply voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power input · I = Current draw · LpA_{in} = Sound pressure level inlet side · LwA_{in} = Sound power level inlet side · LwA_{out} = Sound power level outlet side
q_v = Air flow · P_{fs} = Pressure increase

