

W3G500-DM56-35 ebmpapst Datasheet

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Nominal data

Type	W3G500-DM56-35	
Motor	M3G112-EA	
Phase		1~
Nominal voltage	VAC	230
Nominal voltage range	VAC	200 .. 277
Frequency	Hz	50/60
Type of data definition		ml
Speed	min ⁻¹	1420
Power input	W	750
Current draw	A	3.4
Max. back pressure	Pa	175
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	60

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations

Data according to ErP directive

Installation category	A
Efficiency category	Static
Variable speed drive	Yes
Specific ratio*	1.00

* Specific ratio = $1 + p_{fs} / 100\,000\text{ Pa}$

		Actual	Request 2013	Request 2015
Overall efficiency η_{es}	%	41.6	28.8	32.8
Efficiency grade N		48.8	36	40
Power input P_{ed}	kW	0.73		
Air flow q_v	m ³ /h	5850		
Pressure increase p_{fs}	Pa	173		
Speed n	min ⁻¹	1425		

Data definition with optimum efficiency.

LU-121382

The ErP data is determined using a motor-impeller combination in a standardised measurement configuration.



Technical features

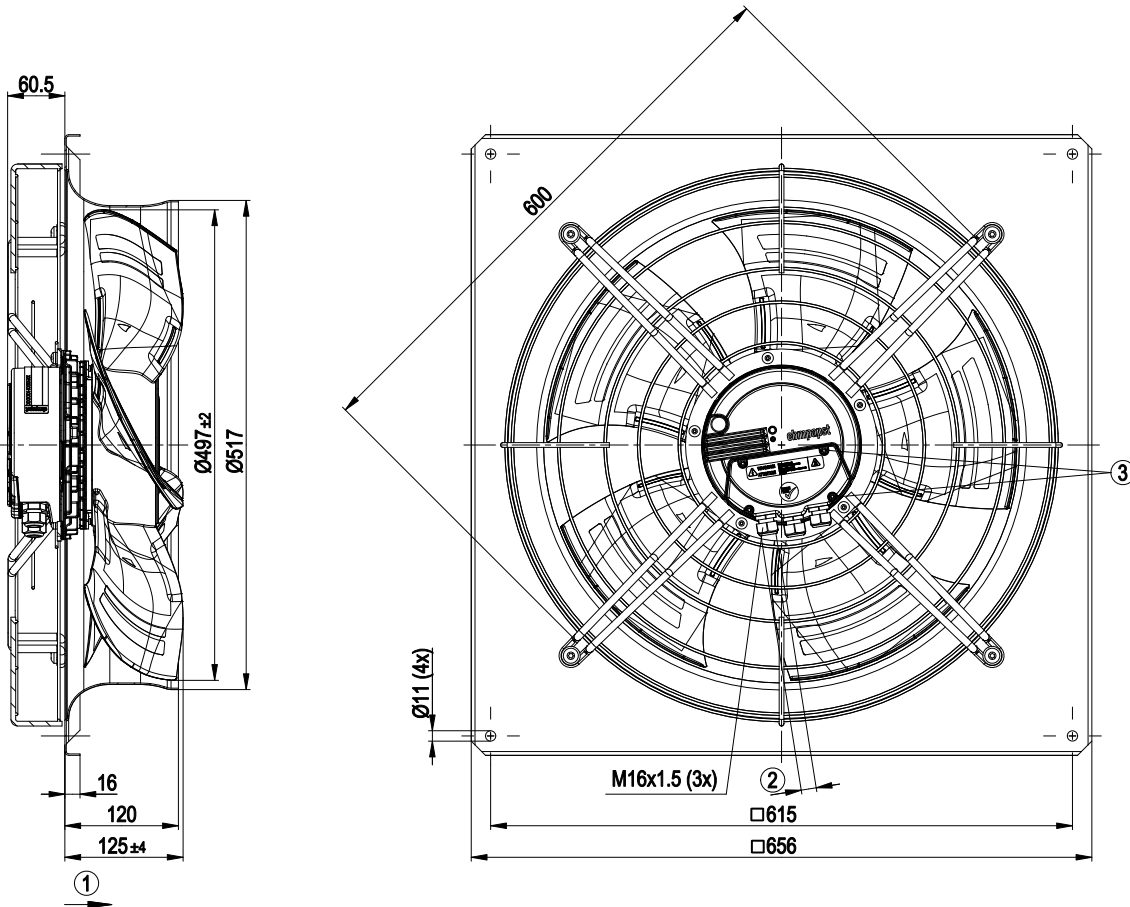
Mass	14.3 kg
Size	500 mm
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium, coated in black
Material of blades	Press-fitted, coated sheet steel blank, sprayed with PP plastic
Material of mounting ring	Steel, galvanised and coated in black plastic (RAL9005)
Material of wall ring	Sheet steel, pre-galvanised and coated in black plastic (RAL 9005)
Number of blades	5
Direction of air flow	"A"
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP 54
Insulation class	"B"
Humidity class	F4-2
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Shaft horizontal or rotor on top
Condensate discharge holes	On the stator side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	<ul style="list-style-type: none"> - Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - Alarm relay - Integrated PID controller - Motor current limit - PFC, active - RS485 ebmBUS - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection
EMC interference immunity	Acc. to EN 61000-6-2 (industrial environment)
EMC harmonics	Acc. to EN 61000-3-2/3
EMC interference emission	Acc. to EN 55022 (Class A, industrial environment)
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical leads	Via terminal box
Motor protection	Thermal overload protector (TOP) wired internally
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE
Approval	EAC

EC axial fan - HyBlade®

sickled blades (S series)

with full square nozzle, for agricultural ventilation

Product drawing



1	Direction of air flow "A"
2	Cable diameter: min. 4 mm, max. 10 mm, tightening torque: 2.5±0.4 Nm
3	Tightening torque 3.5±0.5 Nm

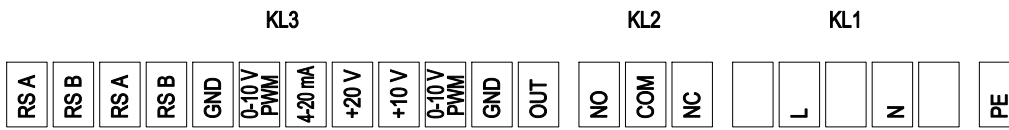


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Connection screen



No.	Conn.	Designation	Function / assignment
PE		PE	Protective earth
KL1		N	Mains 50/60 Hz, neutral
KL1		L	Mains 50/60 Hz, phase
KL2		COM	Alarm relay, COMMON (2A, 250 VAC, AC1)
KL2		NC	Alarm relay, normally closed connection
KL2		NO	Alarm relay, close with error
KL3		+10 V	Supply for external potentiometer, 10 VDC (+10%) @ 10 mA
KL3		+20 V	Supply for external sensor, 20 VDC (±20%) @ 50 mA
KL3		0-10 V/PWM	Control / Actual sensor value input
KL3		0-10 V/PWM	Control / Actual sensor value input (impedance 100 kΩ)
KL3		4-20 mA	Control / Actual sensor value input
KL3		GND	GND
KL3		GND	GND
KL3		OUT	Master output 0-10 V max. 3 mA
KL3		RSA	RS485 interface for ebmBUS; RS A
KL3		RSA	RS485 interface for ebmBUS; RS A
KL3		RSB	RS485 interface for ebmBUS; RS B
KL3		RSB	RS485 interface for ebmBUS; RS B



