

EC axial fan - HyBlade

sickled blades (S series)
with support ring

S3G800-DU23-75 ebmpapst Datasheet
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Nominal data

Type	S3G800-DU23-75	
Motor	M3G150-IF	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
Speed (rpm)	min ⁻¹	1020
Power input	W	2325
Current draw	A	3.5
Max. back pressure	Pa	225
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	70

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations

Data according to ErP directive

		Actual	Request 2015
01 Overall efficiency η_{es}	%	47.5	35.9
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		51.6	40
05 Variable speed drive		Yes	

Data definition with optimum efficiency.
The ErP data is determined using a motor-impeller combination in a standardised measurement configuration.

09 Power input P_{ed}	kW	2.25
09 Air flow q_v	m³/h	17940
09 Pressure increase p_{fs}	Pa	202
10 Speed (rpm) n	min ⁻¹	1020
11 Specific ratio*		1.00

* Specific ratio = $1 + p_{fs} / 100\,000\text{ Pa}$

LU-148033



Technical features

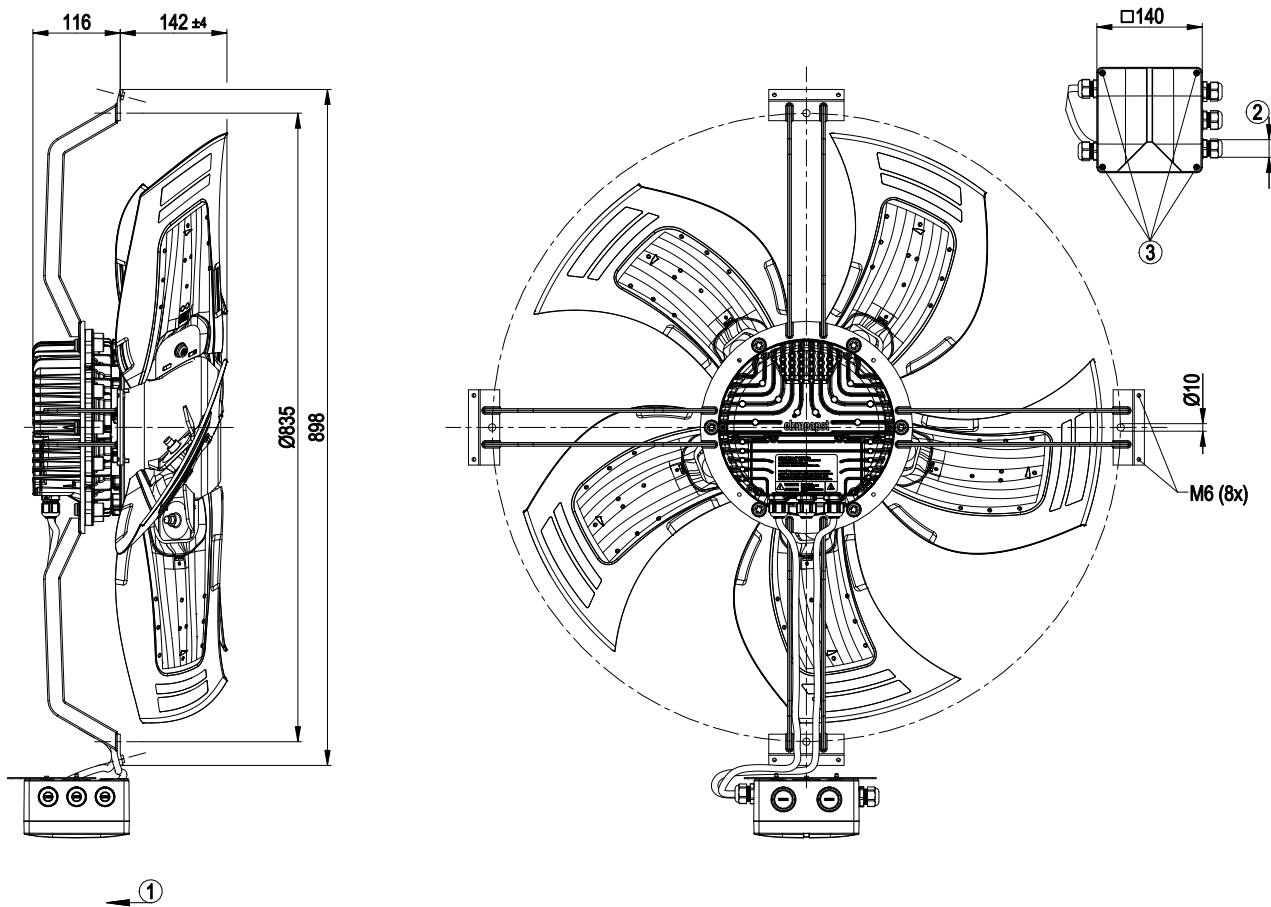
Mass	29.5 kg
Size	800 mm
Surface of rotor	Coated in black
Material of terminal box	PC plastic
Material of electronics housing	Die-cast aluminium, coated in black
Material of blades	Aluminium sheet insert, sprayed with PP plastic
Material of mounting ring	Steel, coated in black plastic (RAL 9005)
Number of blades	5
Blade angle	0°
Direction of air flow	"V"
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP 55
Insulation class	"F"
Humidity (F)/environmental protection class (H)	F4-1
Note ambient temperature	Occasional start-up between -40°C and -25°C is permissible. For continuous operation at ambient temperatures below -25°C (e.g. refrigeration applications) we recommend our fan version with special low-temperature bearings.
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensate discharge holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (programming) - External release input - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive - RS485 MODBUS RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical leads	Via terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE
Approval	EAC

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Product drawing



1	Direction of air flow "V"
2	Cable diameter min. 4 mm, max. 10 mm, tightening torque 4 ± 0.6 Nm
3	Tightening torque 1.7 ± 0.2 Nm

Connection screen

L1	L2	L3	PE
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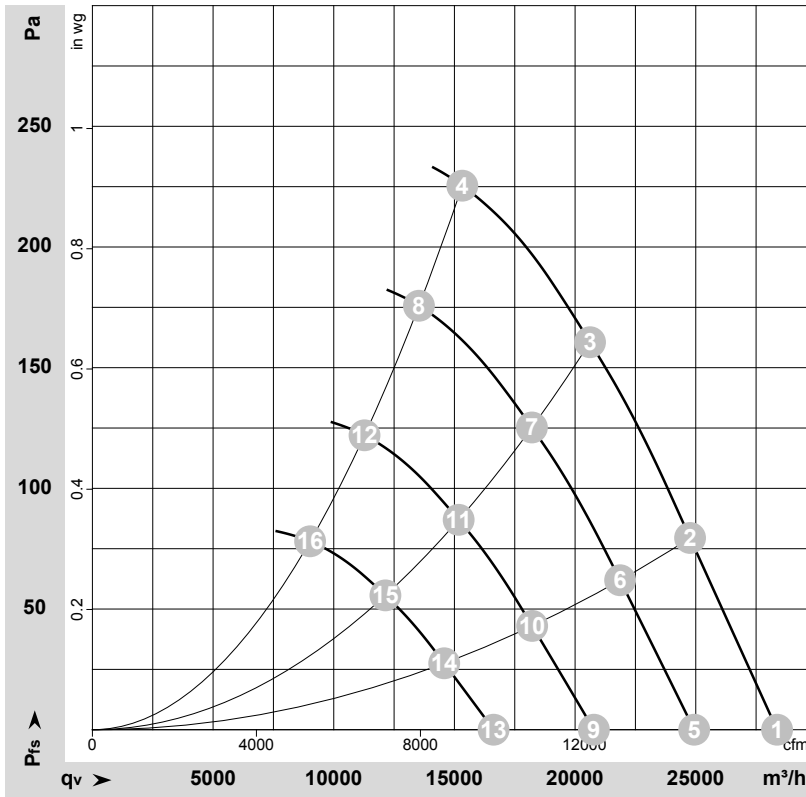
KL 1

RSA	RSB	GND	Din 1	+10 V	Ain 1 U		C	NC
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KL 2

No.	Conn.	Designation	Function / assignment
KL 1		L1	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
KL 1		L2	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
KL 1		L3	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
KL 1		PE	Earth connection, PE connection
KL 2		RSA	Bus connection RS-485, RSA, MODBUS RTU; SELV
KL 2		RSB	Bus connection RS-485, RSB, MODBUS RTU; SELV
KL 2		GND	Signal ground for control interface; SELV
KL 2		Din1	Digital input 1 enabling of electronics, enabling: open pin or applied voltage 5-50 VDC disabling: bridge to GND or applied voltage <1 VDC reset function: triggers software reset after a level change to <1 V; SELV
KL 2		+ 10 V	Fixed voltage output 10 VDC, +10 V +/-3%, max. 10 mA, short-circuit-proof, power supply for ext. devices (e.g. potentiometer); SELV Alternatively: +24 V DC input for parametrisation via MODBUS without mains power
KL 2		Ain1 U	Analogue input 1 (set value) 0-10 V, Ri=100 kΩ, parametrisable curve; SELV
KL2		C	Status relay; floating status contact; changeover contact; common connection; contact rating 250 VAC / max. 2 A (AC1) / min. 10 mA
KL2		NC	Status relay, floating status contact; break for failure

Charts: Air flow 50 Hz



$$\rho = 1.15 \text{ kg/m}^3 \pm 2 \%$$

Measurement: LU-148033-1

Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebm-papst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

Measured values

	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	LwA _{out}	q _v	P _{fs}	q _v	P _{fs}
	V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m ³ /h	Pa	cfm	inH ₂ O
1	400	50	1020	1446	2.31	70	77	78	28370	0	16700	0.00
2	400	50	1020	1786	2.81	68	75	75	24765	80	14575	0.32
3	400	50	1020	2092	3.26	68	76	76	20620	160	12135	0.64
4	400	50	1020	2325	3.50	74	81	81	15325	225	9020	0.90
5	400	50	900	982	1.57	66	74	75	24935	0	14675	0.00
6	400	50	900	1231	1.93	65	72	72	21865	62	12870	0.25
7	400	50	900	1441	2.25	65	73	73	18210	125	10720	0.50
8	400	50	900	1603	2.49	71	78	78	13530	176	7965	0.71
9	400	50	750	568	0.91	62	69	70	20780	0	12230	0.00
10	400	50	750	712	1.12	60	67	68	18220	43	10725	0.17
11	400	50	750	834	1.30	61	68	68	15175	87	8930	0.35
12	400	50	750	927	1.44	66	74	74	11275	122	6635	0.49
13	400	50	600	291	0.46	56	64	64	16625	0	9785	0.00
14	400	50	600	365	0.57	54	62	62	14575	28	8580	0.11
15	400	50	600	427	0.67	55	62	62	12140	56	7145	0.22
16	400	50	600	475	0.74	60	68	68	9020	78	5310	0.31

U = Supply voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power input · I = Current draw · LpA_{in} = Sound pressure level inlet side · LwA_{in} = Sound power level inlet side · LwA_{out} = Sound power level outlet side
q_v = Air flow · P_{fs} = Pressure increase

