

EC axial fan - HyBlade

sickled blades (S series)
with guard grille for full nozzle



S3G800-CT21-07 ebmpapst Datasheet
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Nominal data

Type	S3G800-CT21-07	
Motor	M3G150-GF	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
Speed (rpm)	min ⁻¹	925
Power input	W	1850
Current draw	A	2.85
Max. back pressure	Pa	190
Min. ambient temperature	°C	-40
Max. ambient temperature	°C	40

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations

Data in accordance with ecodesign regulation EU 327/2011

		Actual	Request 2015
01 Overall efficiency η_{es}	%	42.9	35.1
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		47.8	40
05 Variable speed drive		Yes	

Data definition with optimum efficiency.
The ErP data is determined using a motor-impeller combination in a standardised measurement configuration.

09 Power input P_{ed}	kW	1.68
09 Air flow q_v	m³/h	15810
09 Pressure increase p_{fs}	Pa	154
10 Speed (rpm) n	min ⁻¹	930
11 Specific ratio*		1.00

* Specific ratio = $1 + p_{fs} / 100\,000\text{ Pa}$

LU-121612



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Technical features

Mass	29.3 kg
Size	800 mm
Motor size	150
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium, coated in black
Material of blades	Aluminium sheet insert, sprayed with PP plastic
Material of guard grille	Steel, coated in black plastic (RAL9005)
Number of blades	5
Blade angle	0°
Direction of air flow	V
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP55
Insulation class	"F"
Humidity (F) / environmental protection class (H)	H2
Max. permissible ambient motor temp. (transp./ storage)	+70 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing with anti-freezing grease
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Operation and alarm display - Input for sensor 0-10 V or 4-20 mA - External 24 V input (programming) - External release input - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive - RS485 MODBUS RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection
EMC interference immunity	Acc. to EN 61000-6-2 (industrial environment)
EMC interference emission	Acc. to EN 61000-6-3 (household environment), except EN 61000-3-2 for professionally used devices with a total rated power greater than 1 kW
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	≤ 3.5 mA
Electrical connection	Terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (if protective earth is connected by customer)



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Product conforming to standard	EN 61800-5-1; CE
Approval	UL 1004-7 + 60730-1; EAC; CSA C22.2 no. 77 + CAN/CSA-E60730-1

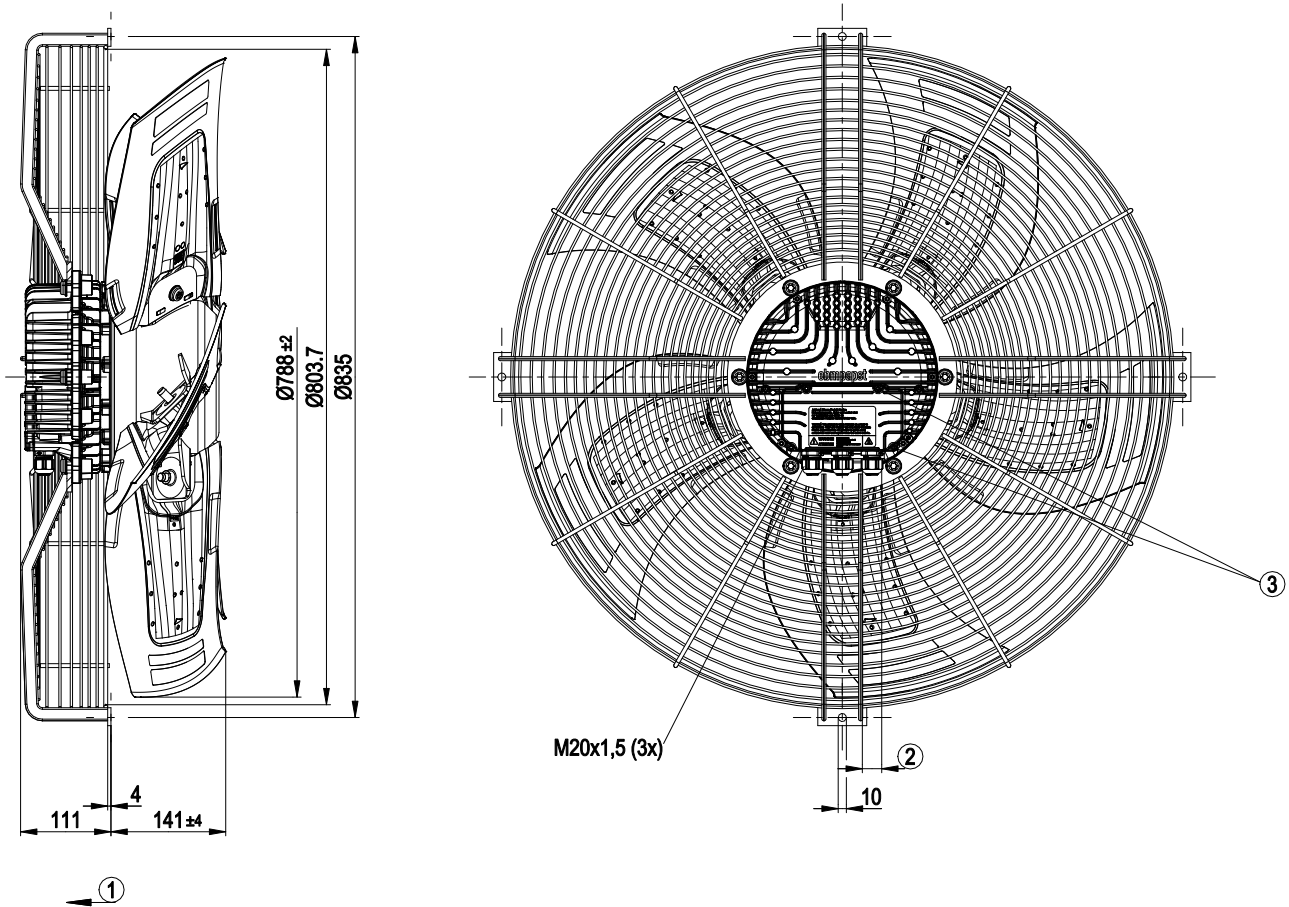


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Product drawing



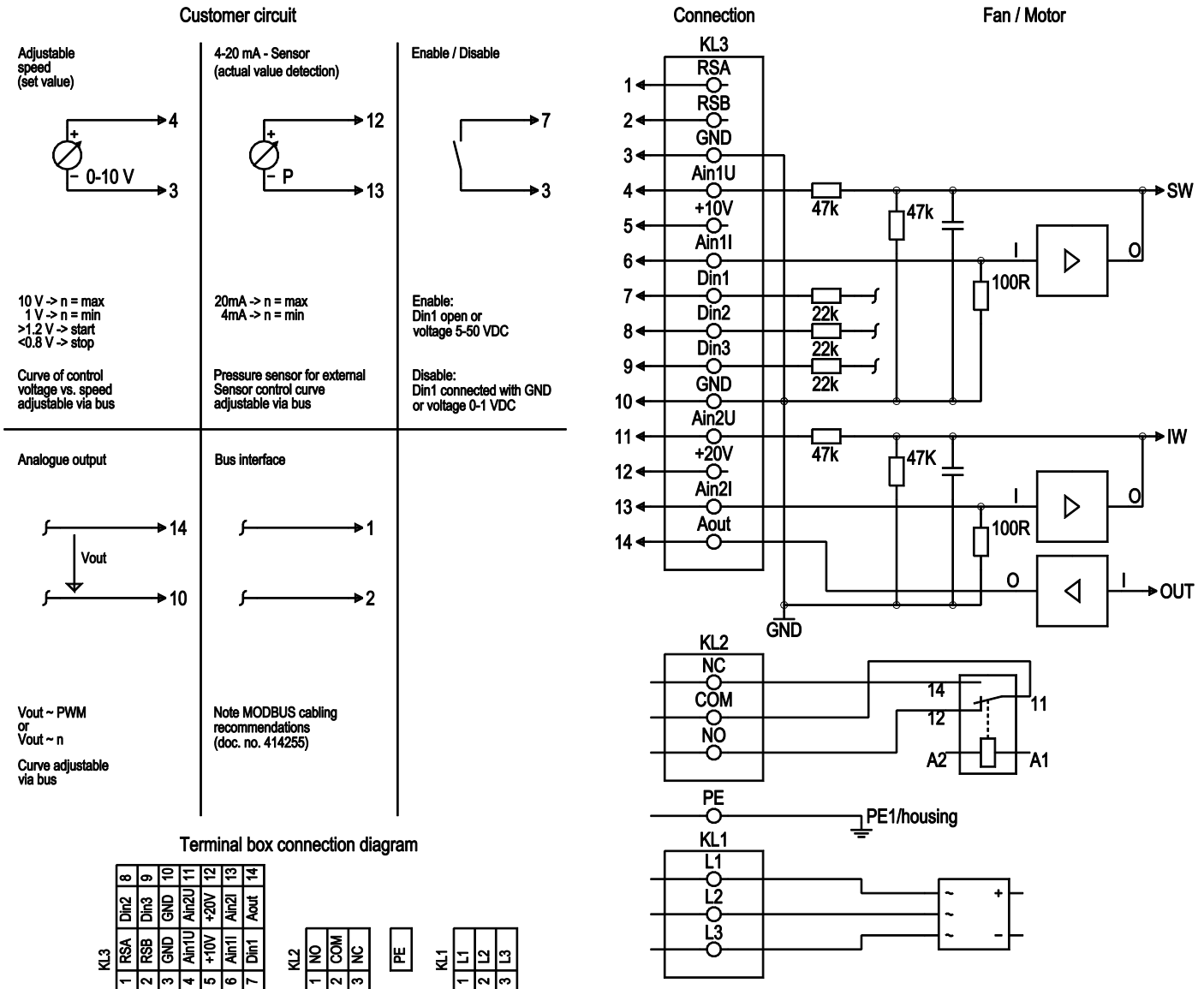
1	Direction of air flow "V"
2	Cable diameter min. 4 mm; max. 10 mm; tightening torque 4 ± 0.6 Nm
3	Tightening torque 3.5 ± 0.5 Nm

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Connection screen



No.	Conn.	Designation	Function / assignment
KL 1	1	L1	Mains connection, power supply; see technical data for nominal voltage range
KL 1	2	L2	Mains connection, power supply; see technical data for nominal voltage range
KL 1	3	L3	Mains connection, power supply; see technical data for nominal voltage range
PE		PE	Earth connection, PE connection
KL 2	1	NO	Status relay, floating status contact, make for failure
KL2	2	COM	Status relay, floating status contact, changeover contact, common connection, contact rating 250 VAC / max. 2 A (AC1) / min. 10 mA
KL2	3	NC	Status relay, floating status contact, break for failure
KL 3	1	RSA	Bus connection RS-485, RSA, MODBUS RTU; SELV
KL 3	2	RSB	Bus connection RS-485, RSB, MODBUS RTU; SELV
KL 3	3 / 10	GND	Signal ground for control interface; SELV
KL 3	4	Ain1 U	Analogue input 1, set value: 0-10 V, Ri = 100 kΩ, parametrisable curve, only usable as alternative to input Ain1; SELV

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No.	Conn.	Designation	Function / assignment
KL 3	5	+ 10 V	Fixed voltage output 10 VDC, +10 V $\pm$ 3%, max. 10 mA, short-circuit-proof, power supply for external devices (e.g. potentiometer); SELV
KL 3	6	Ain1 I	Analogue input 1, set value: 4-20 mA; Ri = 100 Ω , parametrisable curve, only usable as alternative to input Ain1 U; SELV
KL 3	7	Din1	Digital input 1: enabling of electronics, enabling: open pin or applied voltage 5-50 VDC disabling: bridge to GND or applied voltage <1 VDC reset function: triggers software reset after a level change to <1 VDC; SELV
KL 3	8	Din2	Digital input 2: parameter set switch 1/2, according to EEPROM setting, the valid/used parameter set can be selected via bus or via digital input DIN2. Parameter set 1: open pin or applied voltage 5-50 VDC Parameter set 2: bridge to GND or applied voltage <1 VDC; SELV
KL 3	9	Din3	Digital input 3: controller function of integrated controller, according to EEPROM setting, the controller function of the integrated controller is normally/inversely selectable per bus or per digital input Din 3 normal: open pin or applied voltage 5-50 VDC inverse: bridge to GND or applied voltage <1 VDC; SELV
KL 3	11	Ain2 U	Analogue input 2, actual value: 0-10 V, Ri = 100 k Ω , parametrisable curve, only usable as alternative to input Ain2; SELV
KL 3	12	+ 20 V	Fixed voltage output 20 VDC; +20 V $\pm$ 25/-10%, max. 50 mA; short-circuit-proof; supply voltage for external devices (e.g. sensors); SELV Alternatively: +24 VDC input for parametrization without mains power
KL 3	13	Ain2 I	Analogue input 2, actual value: 4-20 mA, Ri = 100 Ω , parametrisable curve, only usable as alternative to input Ain2 U; SELV
KL 3	14	Aout	Analogue output 0-10 VDC, max. 5 mA, output of the current motor level control coefficient / motor speed parametrisable curve; SELV

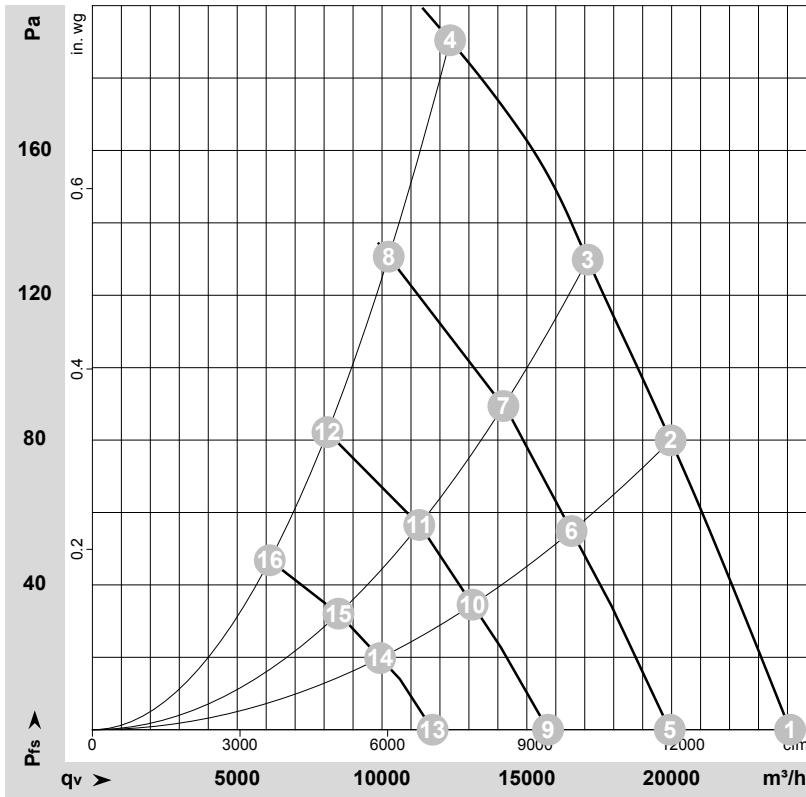


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Charts: Air flow 50 Hz



$$\rho = 1.15 \text{ kg/m}^3 \pm 2 \%$$

Measurement: LU-121612-1
 Measurement: LU-121639-1
 Measurement: LU-121640-1
 Measurement: LU-121641-1

Air performance measured as per ISO 5801
 Installation category A. For detailed
 information on the measuring set-up, please
 contact ebm-papst. Suction-side noise
 levels: LwA measured as per ISO 13347 /
 LpA measured with 1m distance to fan axis.
 The values given are valid under the
 measuring conditions mentioned above and
 may vary according to the actual installation
 situation. With any deviation from the
 standard set-up, the specific values have to
 be checked and reviewed with the unit
 installed.

Measured values

	Conn.	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	LwA _{out}	q _v	p _{fs}	q _v	p _{fs}
		V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m ³ /h	Pa	cfm	in. wg
1	3~	400	50	925	1220	1.85	65	72	73	24090	0	14180	0.00
2	3~	400	50	925	1468	2.23	66	73	72	19970	80	11755	0.32
3	3~	400	50	925	1626	2.47	68	75	74	17100	130	10065	0.52
4	3~	400	50	925	1850	2.85	74	81	81	12350	190	7270	0.76
5	3~	400	50	770	669	1.04	61	68	67	19935	0	11735	0.00
6	3~	400	50	770	827	1.27	62	68	68	16545	55	9740	0.22
7	3~	400	50	770	920	1.41	63	70	69	14190	89	8355	0.36
8	3~	400	50	770	1086	1.66	69	77	76	10230	131	6020	0.53
9	3~	400	50	610	355	0.60	56	62	62	15735	0	9260	0.00
10	3~	400	50	610	428	0.71	56	63	62	13125	35	7725	0.14
11	3~	400	50	610	470	0.76	57	64	63	11285	57	6645	0.23
12	3~	400	50	610	555	0.88	63	70	70	8115	82	4775	0.33
13	3~	400	50	460	169	0.37	50	56	55	11745	0	6915	0.00
14	3~	400	50	460	196	0.41	50	56	56	9935	20	5850	0.08
15	3~	400	50	460	217	0.44	50	57	56	8495	32	5000	0.13
16	3~	400	50	460	250	0.49	55	63	63	6125	47	3605	0.19

Conn. = Connection · U = Supply voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power input · I = Current draw · LpA_{in} = Sound pressure level inlet side · LwA_{in} = Sound power level inlet side
 LwA_{out} = Sound power level outlet side · q_v = Air flow · p_{fs} = Pressure increase

