

EC axial fan

sickled blades (S series)
with guard grille for full nozzle

S3G800-AG02-06 ebmpapst Datasheet
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Nominal data

Type	S3G800-AG02-06	
Motor	M3G150-FF	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
Speed	min ⁻¹	830
Power input	W	1350
Current draw	A	2.2
Max. back pressure	Pa	155
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	60

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations

Data according to ErP directive

Installation category	A
Efficiency category	Static
Variable speed drive	Yes
Specific ratio*	1.00

* Specific ratio = $1 + p_b / 100\,000\text{ Pa}$

		Actual	Request 2013	Request 2015
Overall efficiency η_{es}	%	45.9	30.3	34.3
Efficiency grade N		51.6	36	40
Power input P_{ed}	kW	1.24		
Air flow q_v	m ³ /h	14305		
Pressure increase p_{fs}	Pa	133		
Speed n	min ⁻¹	835		

Data definition with optimum efficiency. LU-110473
The ErP data is determined using a motor-impeller combination in a standardised measurement configuration.



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Technical features

Mass	30.95 kg
Size	800 mm
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium, coated in black
Material of blades	Die-cast aluminium
Material of guard grille	Steel, phosphated and coated in black plastic
Number of blades	5
Blade angle	0°
Direction of air flow	"V"
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP 54
Insulation class	"F"
Humidity class	F4-1
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Shaft horizontal or rotor on bottom
Condensate discharge holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- PFC, passive - Control input 0-10 VDC / PWM - Over-temperature protected electronics / motor - Alarm relay - Integrated PID controller - Input for sensor 0-10 V or 4-20 mA - Output for slave 0-10 V - RS485 ebmBUS - Motor current limit - Soft start - Line undervoltage / phase failure detection - Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA
EMC interference immunity	Acc. to EN 61000-6-2 (industrial environment)
EMC interference emission	Acc. to EN 61000-6-3 (household environment)
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical leads	Via terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE
Approval	CSA; EAC; UL; VDE

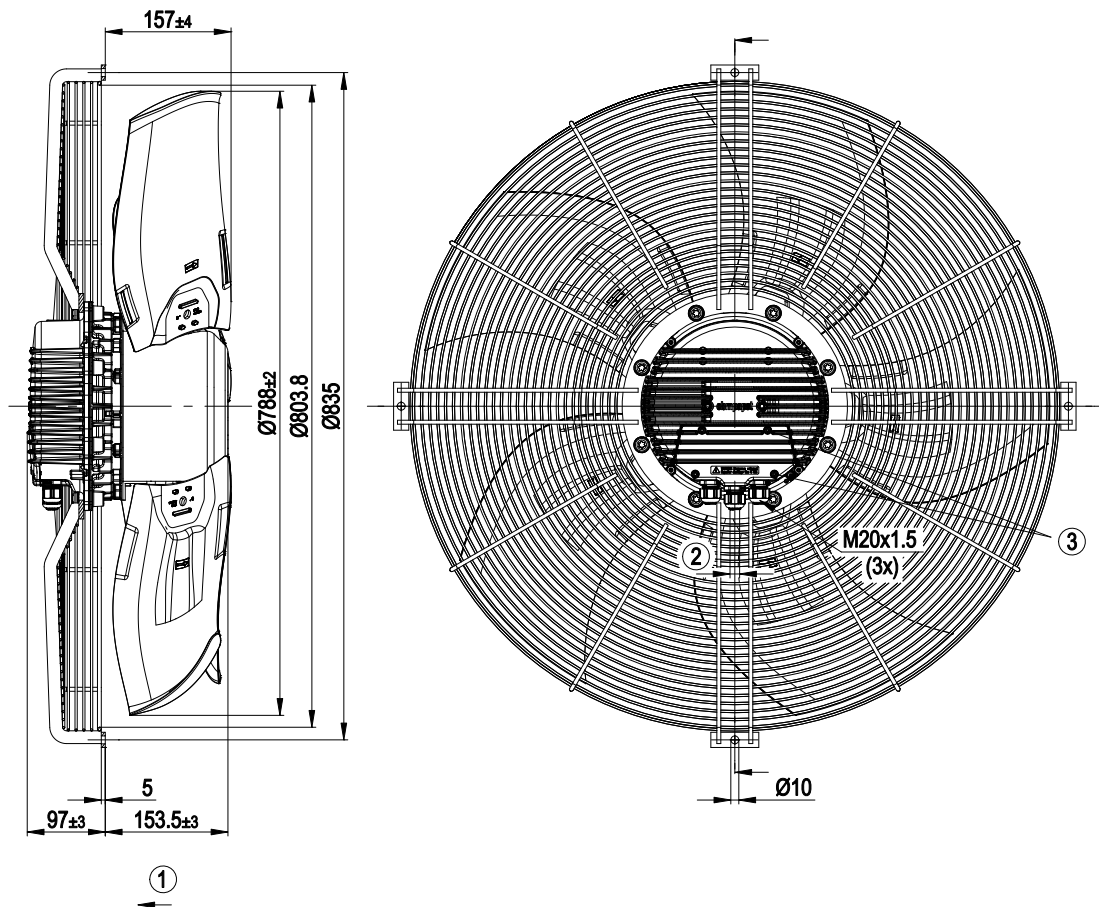


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Product drawing



1	Direction of air flow "V"
2	Cable diameter: min. 4 mm; max. 10 mm; tightening torque: 4 ± 0.6 Nm
3	Tightening torque 3.5 ± 0.5 Nm

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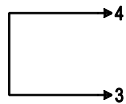
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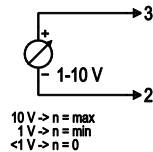
Connection screen

Customer circuit

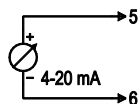
Full speed



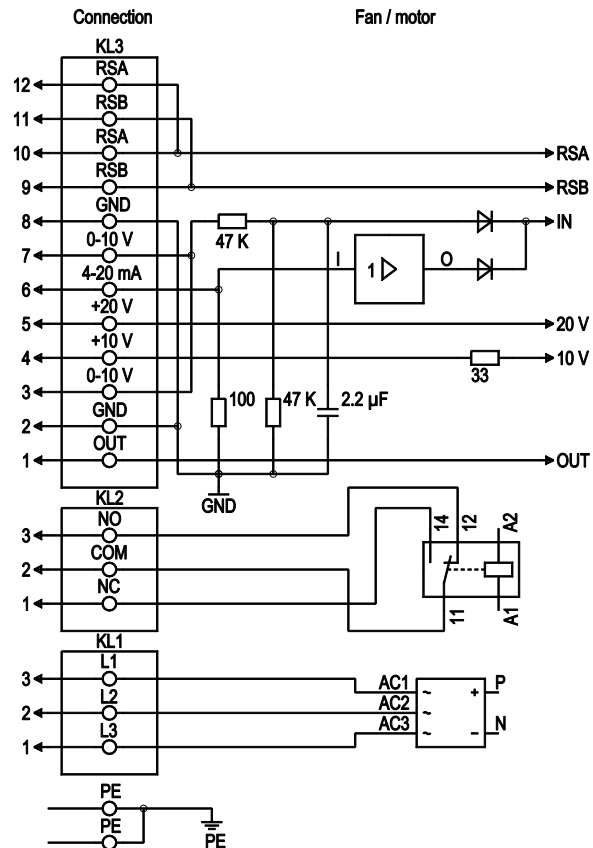
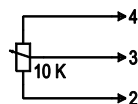
Speed setting



Setting of values, e.g. via pressure



Speed setting via potentiometer



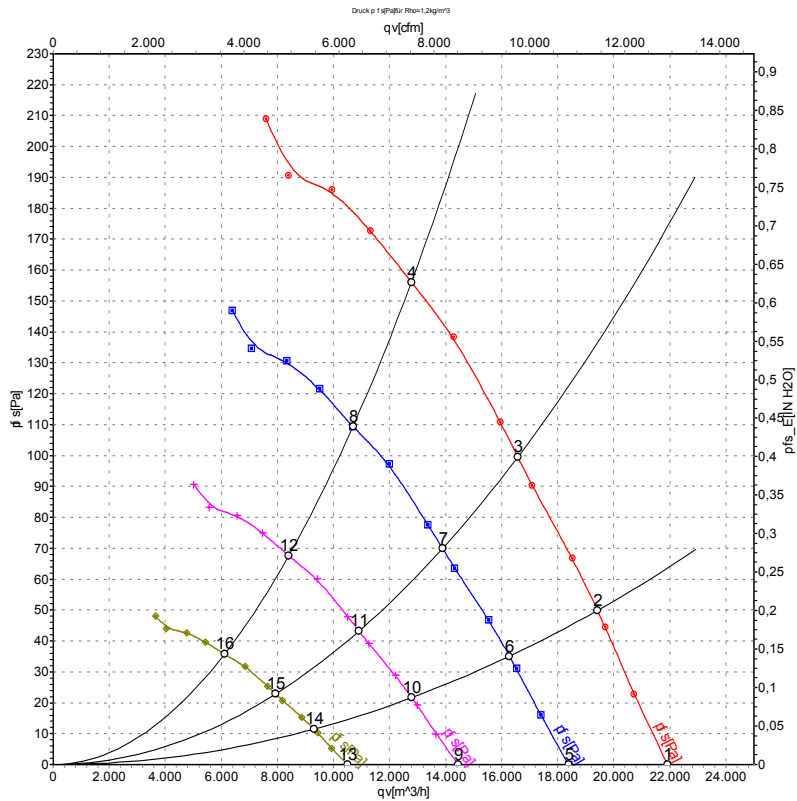
No.	Conn.	Designation	Function / assignment
PE		PE	Protective earth connection
KL1	1, 2, 3	L1, L2, L3	Supply voltage, 50/60 Hz
KL2	1	NC	Floating status message contact, normally closed connection
KL2	2	COM	Floating status message contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status message contact, normally open connection
KL3	1	OUT	Analog output, 0-10 VDC, max. 3 mA, SELV, output of the current level control coefficient: 1 V equates to 10 % level control coefficient. 10 V equate to 100 % level control coefficient.
KL3	2, 8	GND	Reference mass for control interface, SELV
KL3	3, 7	0-10 V	Use control / actual value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (+/-3 %), max. 10 mA, supply voltage for ext. devices (e.g. potentiometers), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25 %/-10 %), max. 50 mA, supply voltage for ext. devices (e.g. sensors), SELV
KL3	6	4-20 mA	Use control / actual value input 4-20 mA, impedance 100 Ω, only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for ebmBus, RSB, SELV
KL3	10, 12	RSA	RS485 interface for ebmBus, RSA, SELV



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Charts: Air flow 50 Hz



Air performance measured as per ISO 5801
Installation category A. For detailed
information on the measuring set-up, please
contact ebm-papst. Suction-side noise
levels: LwA measured as per ISO 13347 /
LpA measured with 1m distance to fan axis.
The values given are valid under the
measuring conditions mentioned above and
may vary according to the actual installation
situation. With any deviation from the
standard set-up, the specific values have to
be checked and reviewed with the unit
installed.

Measured values

	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	LwA _{out}	qv	p _{fs}
	V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m³/h	Pa
1	400	50	830	859	1.32	64	71	71	21910	0
2	400	50	830	1025	1.56	63	69	68	19410	50
3	400	50	830	1176	1.79	63	69	69	16570	100
4	400	50	830	1350	2.20	68	75	75	12780	155
5	400	50	700	508	0.78	61	67	67	18390	0
6	400	50	700	604	0.92	59	65	65	16280	35
7	400	50	700	692	1.05	60	66	65	13890	70
8	400	50	700	782	1.20	65	71	71	10700	109
9	400	50	550	246	0.38	55	62	62	14450	0
10	400	50	550	293	0.45	54	60	59	12790	22
11	400	50	550	336	0.51	54	60	60	10910	43
12	400	50	550	379	0.58	59	66	66	8405	68
13	400	50	400	95	0.15	49	55	55	10510	0
14	400	50	400	113	0.17	47	53	52	9300	12
15	400	50	400	129	0.20	47	53	53	7935	23
16	400	50	400	146	0.22	52	59	59	6115	36

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Power input · I = Current draw · LpA_{in} = Sound pressure level inlet side · LwA_{in} = Sound power level inlet side · LwA_{out} = Sound power level outlet side
qv = Air flow · p_{fs} = Pressure increase

