



Nominal data

Type	S3G630-CR85-06	
Motor	M3G112-IA	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
Speed	min ⁻¹	1140
Power input	W	970
Current draw	A	1.6
Max. back pressure	Pa	170
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	+60

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations

Data according to ErP directive

Installation category	A
Efficiency category	Static
Variable speed drive	Yes
Specific ratio*	1.00

* Specific ratio = $1 + p_b / 100\,000\text{ Pa}$

	Actual	Request 2013	Request 2015
Overall efficiency η_{es}	45.1	29.6	33.6
Efficiency grade N	51.5	36	40
Power input P_{ed}	kW	0.97	
Air flow q_v	m ³ /h	8935	
Pressure increase p_{fs}	Pa	163	
Speed n	min ⁻¹	1155	

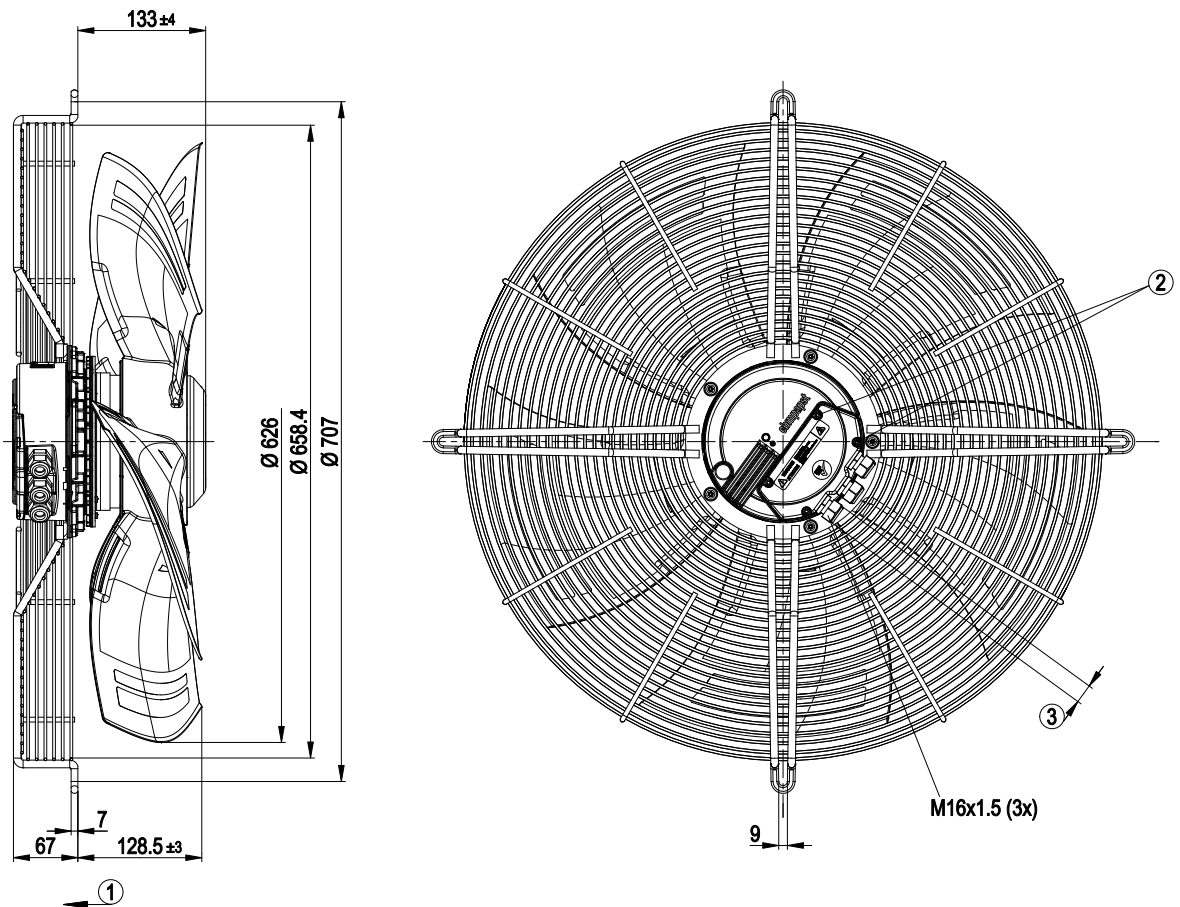
Data definition with optimum efficiency.
The ErP data is determined using a motor-impeller combination in a standardised measurement configuration.



Technical features

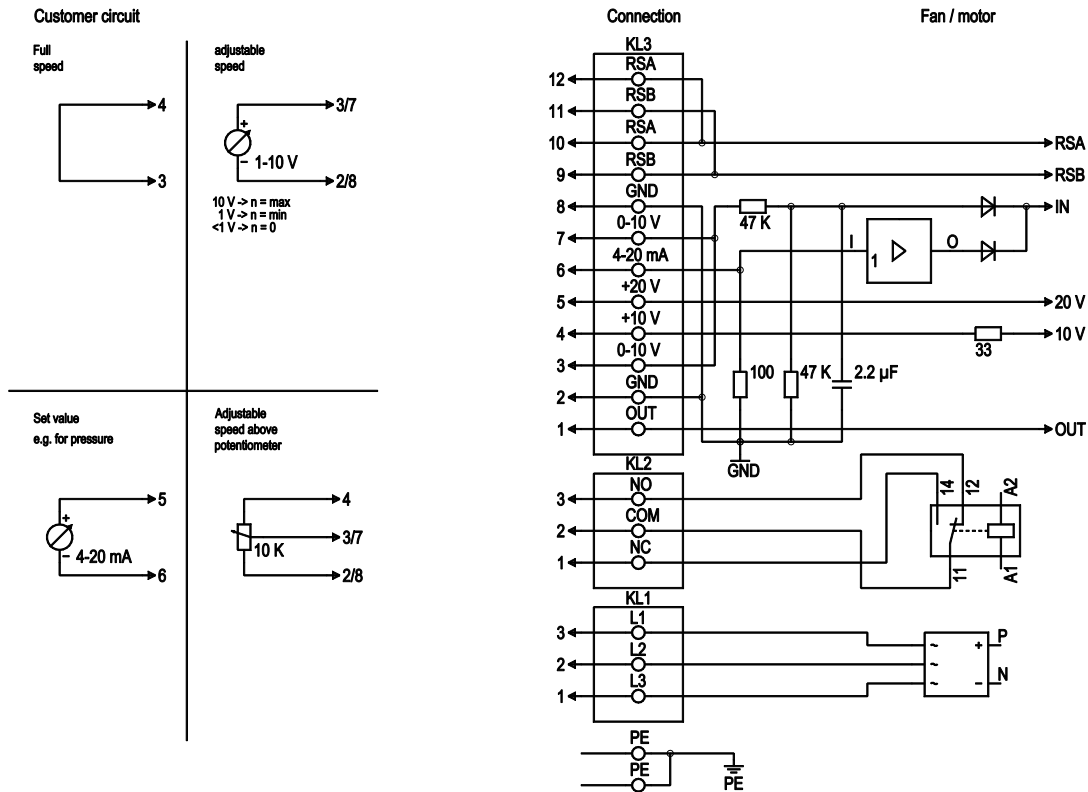
Mass	15.4 kg
Size	630 mm
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium, coated in black
Material of blades	Press-fitted sheet steel blank, sprayed with PP plastic
Material of guard grille	Steel, coated in black plastic (RAL9005)
Number of blades	5
Blade angle	-5°
Direction of air flow	"V"
Direction of rotation	Counter-clockwise, seen on rotor
Type of protection	IP 54
Insulation class	"B"
Humidity class	F4-1
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensate discharge holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - External 24 V input (programming) - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive - RS485 MODBUS RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection
EMC interference immunity	Acc. to EN 61000-6-2 (industrial environment)
EMC harmonics	Acc. to EN 61000-3-2/3
EMC interference emission	Acc. to EN 61000-6-3 (household environment)
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical leads	Via terminal box
Motor protection	Thermal overload protector (TOP) wired internally
Cable exit	Variable
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE
Approval	UL 1004-7 + 60730

Product drawing



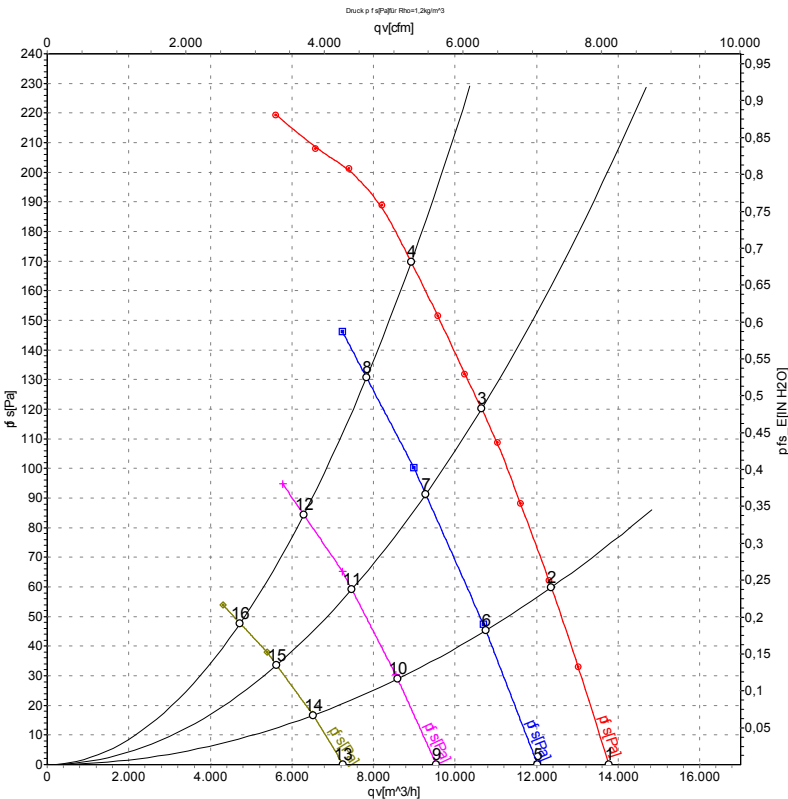
1	Direction of air flow "V"
2	Tightening torque 3.5±0.5 Nm
3	Cable diameter min. 4 mm, max. 10 mm; tightening torque 2±0.3 Nm

Connection screen



No.	Pin	Signal	Function / assignment
PE		PE	Protective earth connection
KL1	1, 2, 3	L1, L2, L3	Supply voltage, voltage range (see type plate), 50/60 Hz
KL2	1	NC	Floating status contact, break with error
KL2	2	COM	Floating status contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status contact, close with error
KL3	1	OUT	Analogue output, 0-10 VDC, max. 3 mA, SELV, Output of the actual motor duty cycle (PWM): 1 V corresponds to 10% PWM, 10 V correspond to 100% PWM.
KL3	2, 8	GND	Signal ground for control interface, SELV
KL3	3, 7	0-10 V	Set value / actual sensor value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (+/-3%), max. 10 mA, power supply for external devices (e.g. potentiometer), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25%/-10%), max. 50 mA, supply voltage for external devices (e.g. sensors), SELV
KL3	6	4-20 mA	Set value / actual sensor value input 4-20 mA, impedance 100 Ω, only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for MODBUS, RSB
KL3	10, 12	RSA	RS485 interface for MODBUS, RSA

Charts: Air flow 50 Hz



Measurement: LU-115687
Measurement: LU-118125
Measurement: LU-118126
Measurement: LU-118127

Air performance measured as per ISO 5801
Installation category A. For detailed
information on the measuring set-up, please
contact ebm-papst. Suction-side noise
levels: L_{wA} measured as per ISO 13347 /
L_{pA} measured with 1m distance to fan axis.
The values given are valid under the
measuring conditions mentioned above and
may vary according to the actual installation
situation. With any deviation from the
standard set-up, the specific values have to
be checked and reviewed with the unit
installed.

Measured values

	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	LwA _{out}	qv	p _{fs}
	V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m ³ /h	Pa
1	400	50	1140	642	1.02	67	74	74	13770	0
2	400	50	1140	775	1.25	64	71	71	12360	60
3	400	50	1140	892	1.42	66	72	71	10650	120
4	400	50	1140	970	1.60	68	74	73	8920	170
5	400	50	1000	406	0.75	64	71	70	12020	0
6	400	50	1000	490	0.86	61	68	67	10750	45
7	400	50	1000	564	0.95	62	69	68	9280	91
8	400	50	1000	626	1.05	63	70	69	7830	131
9	400	50	800	224	0.45	59	65	65	9540	0
10	400	50	800	270	0.53	56	62	62	8595	29
11	400	50	800	300	0.58	56	63	62	7470	59
12	400	50	800	331	0.64	57	64	64	6290	84
13	400	50	600	109	0.25	52	59	58	7255	0
14	400	50	600	124	0.28	50	56	56	6520	17
15	400	50	600	139	0.31	50	56	56	5625	34
16	400	50	600	152	0.33	50	57	57	4730	48

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Power input · I = Current draw · LpA_{in} = Sound pressure level inlet side · LwA_{in} = Sound power level inlet side · LwA_{out} = Sound power level outlet side
qv = Air flow · p_{fs} = Pressure increase

