

EC axial fan - HyBlade®

sickled blades (S series)
with guard grille for full nozzle



S3G500-AN33-08 ebmpapst Datasheet
sales@fansco.com
www.fansco.com



Nominal data

Type	S3G500-AN33-08	
Motor	M3G112-GA	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
Speed	min ⁻¹	1600
Power input	W	980
Current draw	A	1.6
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	+60

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations

Data according to ErP directive

Installation category	A
Efficiency category	Static
Variable speed drive	Yes
Specific ratio*	1.00

* Specific ratio = 1 + p_{ts} / 100 000 Pa

	Actual	Request 2013	Request 2015
Overall efficiency η_{es}	43.5	29.7	33.7
Efficiency grade N	49.8	36	40
Power input P _{ed}	kW	1	
Air flow q _v	m ³ /h	6630	
Pressure increase p _{ts}	Pa	218	
Speed n	min ⁻¹	1610	

Data definition with optimum efficiency.
The ErP data is determined using a motor-impeller combination in a standardised measurement configuration.



Technical features

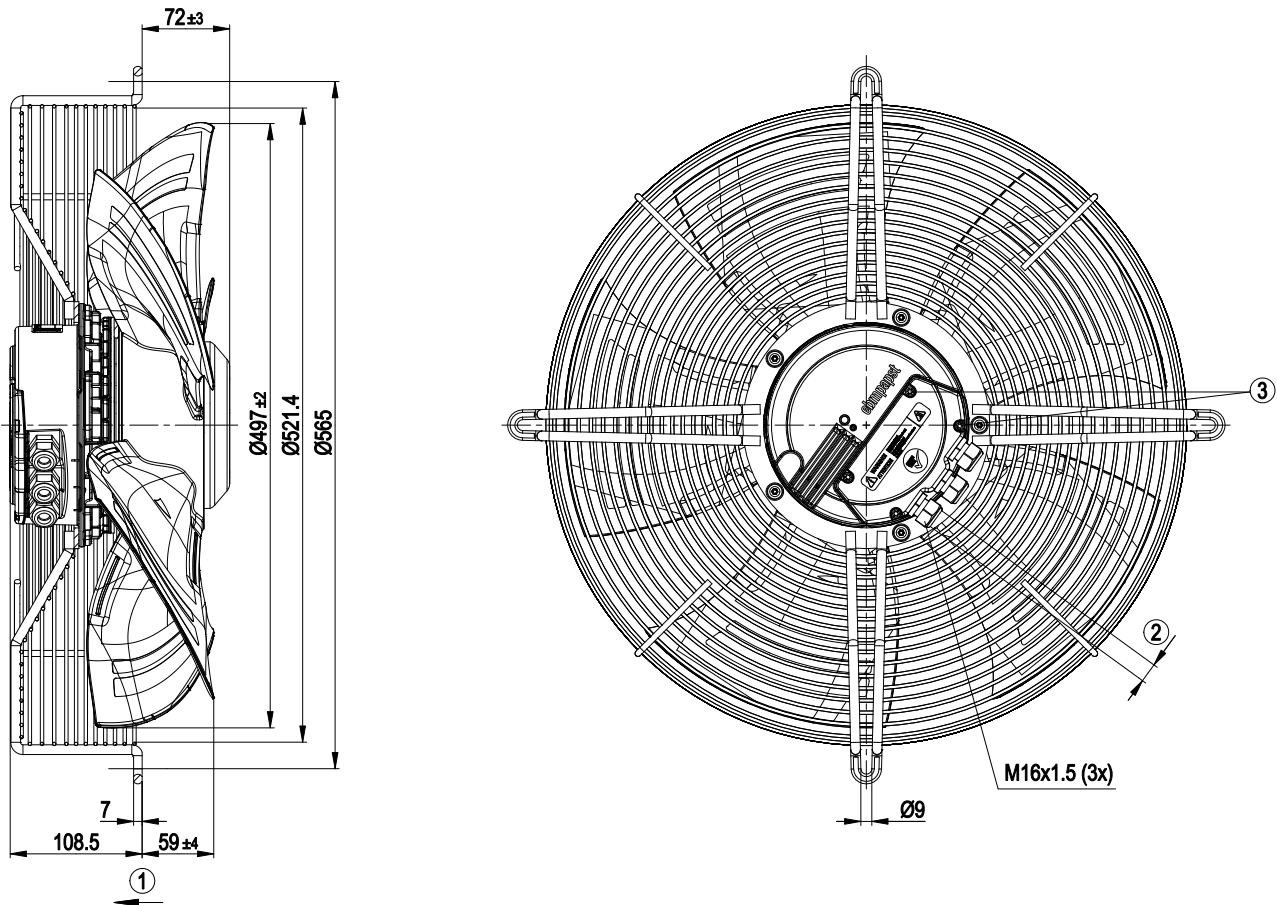
Mass	12.7 kg
Size	500 mm
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium, coated in black
Material of blades	Press-fitted sheet steel blank, sprayed with PP plastic
Material of guard grille	Steel, coated in black plastic (RAL9005)
Number of blades	5
Direction of air flow	"V"
Direction of rotation	Counter-clockwise, seen on rotor
Type of protection	IP 54
Insulation class	"B"
Humidity class	F4-1
Max. permissible ambient motor temp. (transp./ storage)	+ 80 °C
Min. permissible ambient motor temp. (transp./storage)	- 40 °C
Mounting position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensate discharge holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing with anti-freezing grease
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - External 24 V input (programming) - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive - RS485 MODBUS RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection
EMC interference immunity	Acc. to EN 61000-6-2 (industrial environment)
EMC harmonics	Acc. to EN 61000-3-2/3
EMC interference emission	Acc. to EN 61000-6-3 (household environment)
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical leads	Via terminal box
Motor protection	Thermal overload protector (TOP) wired internally
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1

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Product drawing



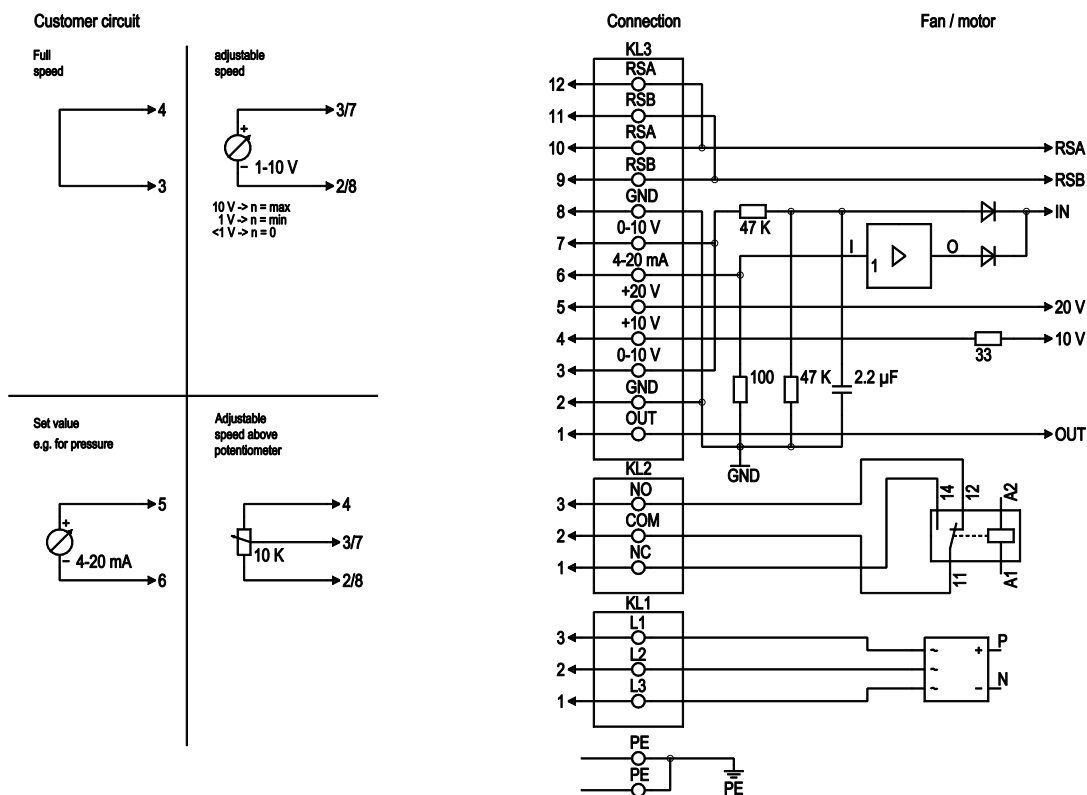
1	Direction of air flow "V"
2	Cable diameter min. 4 mm, max. 10 mm; tightening torque 2.5 ± 0.4 Nm
3	Tightening torque 3.5 ± 0.5 Nm

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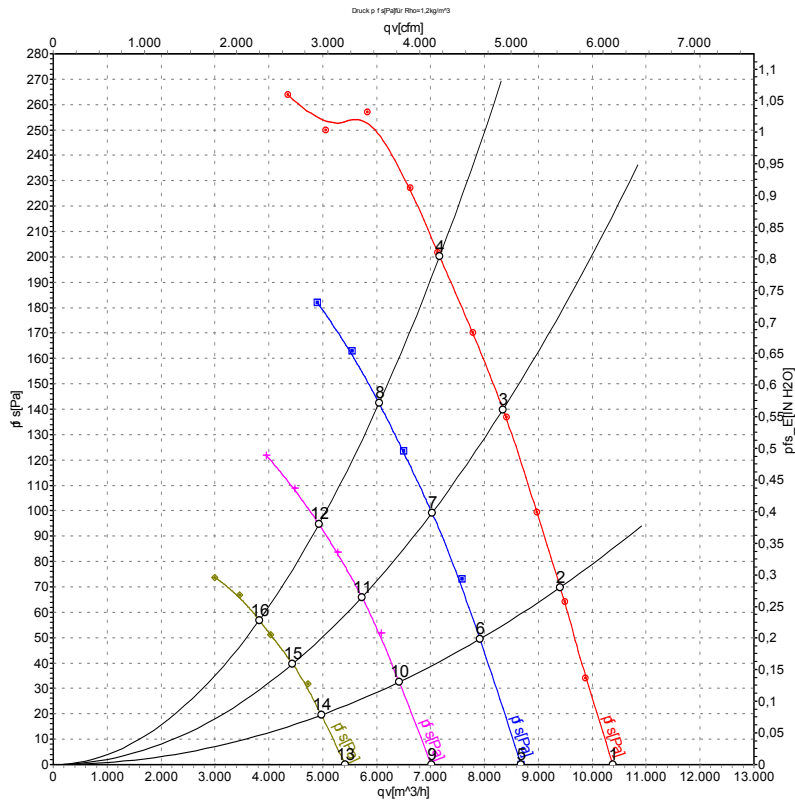
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Connection screen



No.	Pin	Signal	Function / assignment
PE		PE	Protective earth connection
KL1	1, 2, 3	L1, L2, L3	Supply voltage, voltage range (see type plate), 50/60 Hz
KL2	1	NC	Floating status contact, break with error
KL2	2	COM	Floating status contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status contact, close with error
KL3	1	OUT	Analogue output, 0-10 VDC, max. 3 mA, SELV, Output of the actual motor duty cycle (PWM): 1 V corresponds to 10% PWM, 10 V correspond to 100% PWM.
KL3	2, 8	GND	Signal ground for control interface, SELV
KL3	3, 7	0-10 V	Set value / actual sensor value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (+/-3%), max. 10 mA, power supply for external devices (e.g. potentiometer), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25%/-10%), max. 50 mA, supply voltage for external devices (e.g. sensors), SELV
KL3	6	4-20 mA	Set value / actual sensor value input 4-20 mA, impedance 100 Ω, only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for MODBUS, RSB
KL3	10, 12	RSA	RS485 interface for MODBUS, RSA

Charts: Air flow 50 Hz



Measurement: LU-121588
Measurement: LU-125150
Measurement: LU-125151
Measurement: LU-125149

Air performance measured as per ISO 5801
Installation category A. For detailed
information on the measuring set-up, please
contact ebm-papst. Suction-side noise
levels: LwA measured as per ISO 13347 /
LpA measured with 1m distance to fan axis.
The values given are valid under the
measuring conditions mentioned above and
may vary according to the actual installation
situation. With any deviation from the
standard set-up, the specific values have to
be checked and reviewed with the unit
installed.

Measured values

	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	LwA _{out}	qv	p _{fs}
	V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m ³ /h	Pa
1	400	50	1600	734	1.16	72	80	80	10390	0
2	400	50	1600	827	1.33	70	77	77	9405	70
3	400	50	1600	907	1.41	68	75	75	8345	140
4	400	50	1600	980	1.60	68	76	75	7170	200
5	400	50	1350	434	0.78	69	76	76	8680	0
6	400	50	1350	489	0.85	66	73	73	7915	51
7	400	50	1350	538	0.91	64	71	71	7025	99
8	400	50	1350	577	0.95	64	71	71	6045	142
9	400	50	1100	256	0.51	64	72	71	7015	0
10	400	50	1100	282	0.55	62	69	68	6420	33
11	400	50	1100	308	0.60	59	67	66	5730	66
12	400	50	1100	329	0.64	59	66	65	4930	95
13	400	50	850	133	0.31	60	67	66	5415	0
14	400	50	850	145	0.32	57	64	63	4975	20
15	400	50	850	155	0.34	55	62	61	4445	40
16	400	50	850	163	0.36	53	60	60	3820	57

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Power input · I = Current draw · LpA_{in} = Sound pressure level inlet side · LwA_{in} = Sound power level inlet side · LwA_{out} = Sound power level outlet side
qv = Air flow · p_{fs} = Pressure increase

