

R3G630-RI85-21 ebmpapst Datasheet

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## Nominal data

Type	R3G630-RI85-21	
Motor	M3G112-IA	
Phase		1~
Nominal voltage	VAC	230
Nominal voltage range	VAC	200 .. 277
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min <sup>-1</sup>	725
Power consumption	W	500
Current draw	A	2.2
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	40

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment  
Subject to change

## Data according to ErP Directive

		Actual	Req. 2015			
01 Overall efficiency $\eta_{es}$	%	64.9	48.3	09 Power consumption $P_{ed}$	kW	0.5
02 Measurement category		A		09 Air flow $q_v$	m <sup>3</sup> /h	6170
03 Efficiency category		Static		09 Pressure increase $p_{fs}$	Pa	171
04 Efficiency grade N		78.6	62	10 Speed (rpm) n	min <sup>-1</sup>	725
05 Variable speed drive		Yes		11 Specific ratio*		1.00

Data obtained at optimum efficiency level.

The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

\* Specific ratio =  $1 + p_{fs} / 100\,000\text{ Pa}$

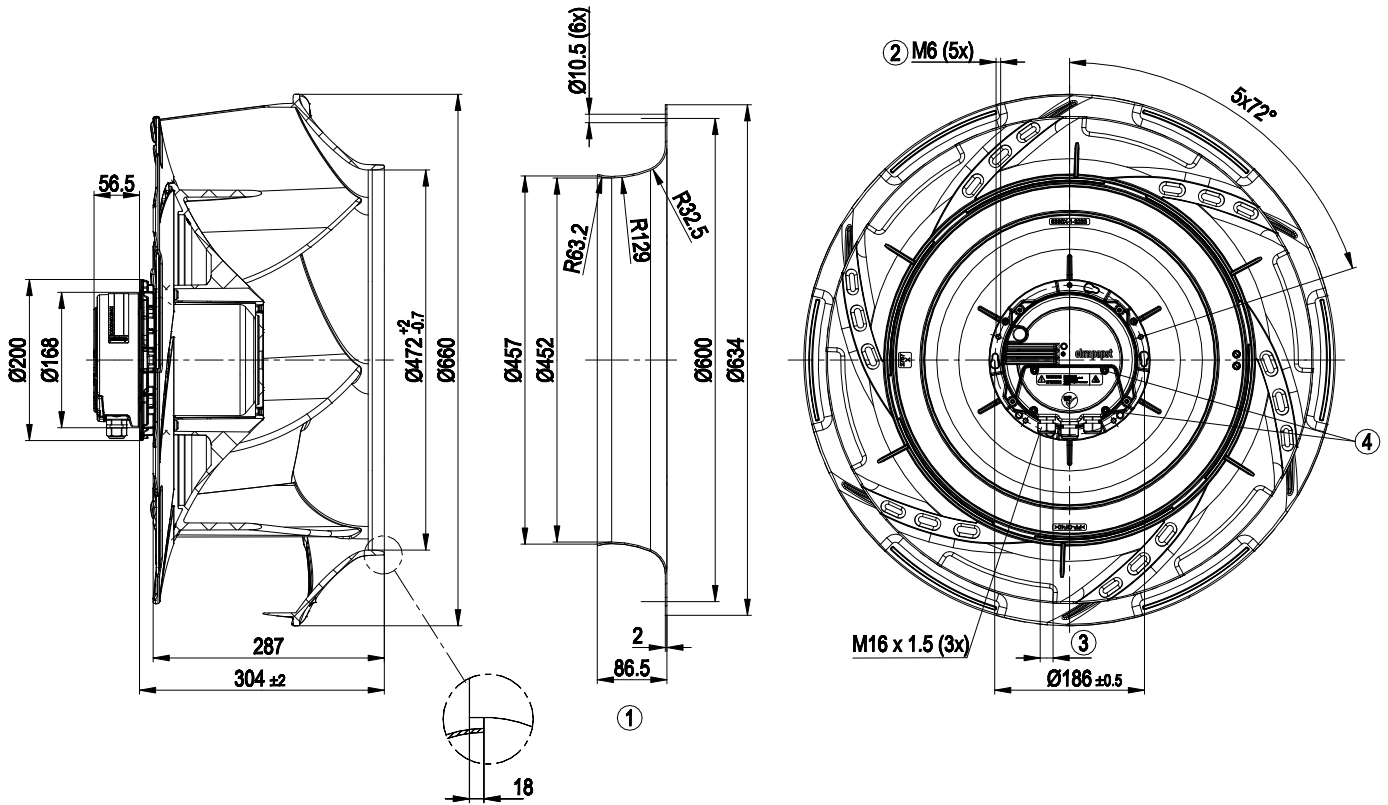
LU-166573



## Technical description

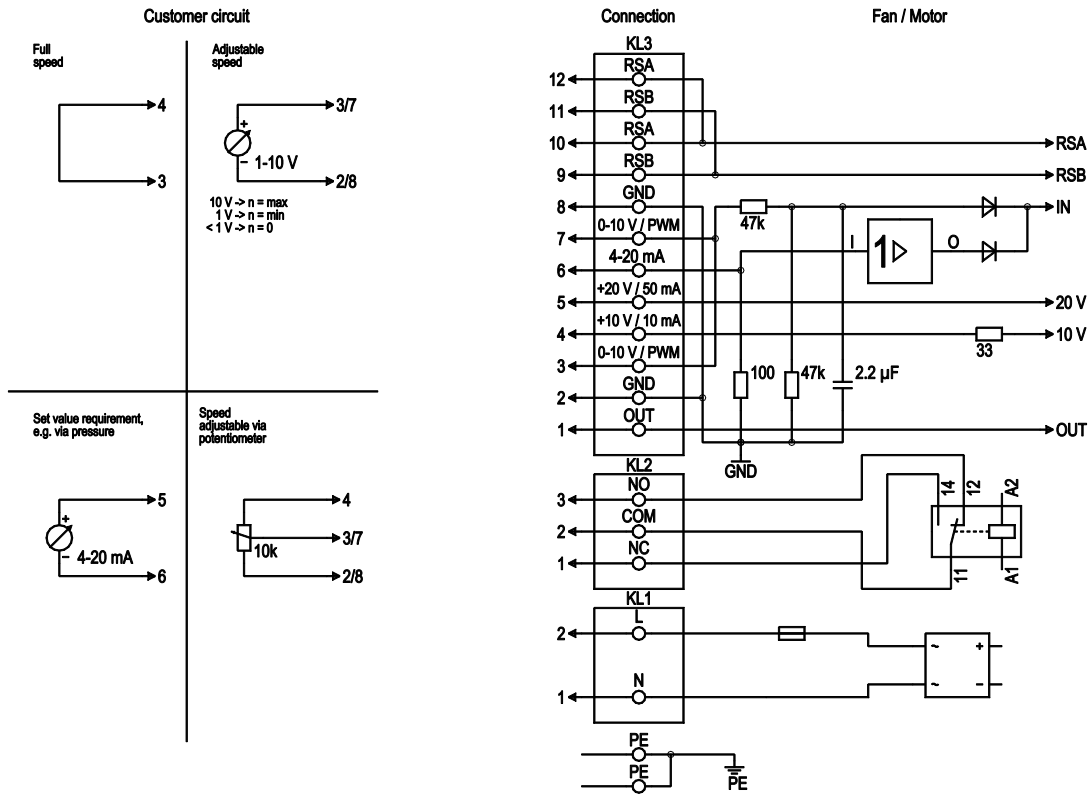
Weight	18 kg
Fan size	630 mm
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum
Impeller material	PP plastic
Number of blades	6
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP54
Insulation class	"B"
Moisture (F) / Environmental (H) protection class	F4-1
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	<ul style="list-style-type: none"> <li>- Output 10 VDC, max. 10 mA</li> <li>- Output 20 VDC, max. 50 mA</li> <li>- Output for slave 0-10 V</li> <li>- Operation and alarm display</li> <li>- Selection of direction of rotation left/right</li> <li>- Input for sensor 0-10 V or 4-20 mA</li> <li>- External 24 V input (parameter setting)</li> <li>- Alarm relay</li> <li>- Integrated PID controller</li> <li>- Motor current limitation</li> <li>- PFC, active</li> <li>- RS-485 MODBUS-RTU</li> <li>- Soft start</li> <li>- Control input 0-10 VDC / PWM</li> <li>- Control interface with SELV potential safely disconnected from supply</li> <li>- Thermal overload protection for electronics/motor</li> <li>- Line undervoltage / phase failure detection</li> </ul>
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Via terminal box
Motor protection	Thermal overload protector (TOP) internally connected
With cable	Variable
Protection class	I (if protective earth is connected by customer to the housing's connection point)
Conformity with standards	EN 61800-5-1; CE

Product drawing



1	Accessory part: inlet ring 63300-2-4013 not included in scope of delivery
2	Max. clearance for screw 16 mm
3	Cable diameter min. 4 mm, max. 10 mm; tightening torque $2.5 \pm 0.4$ Nm
4	Tightening torque $3.5 \pm 0.5$ Nm

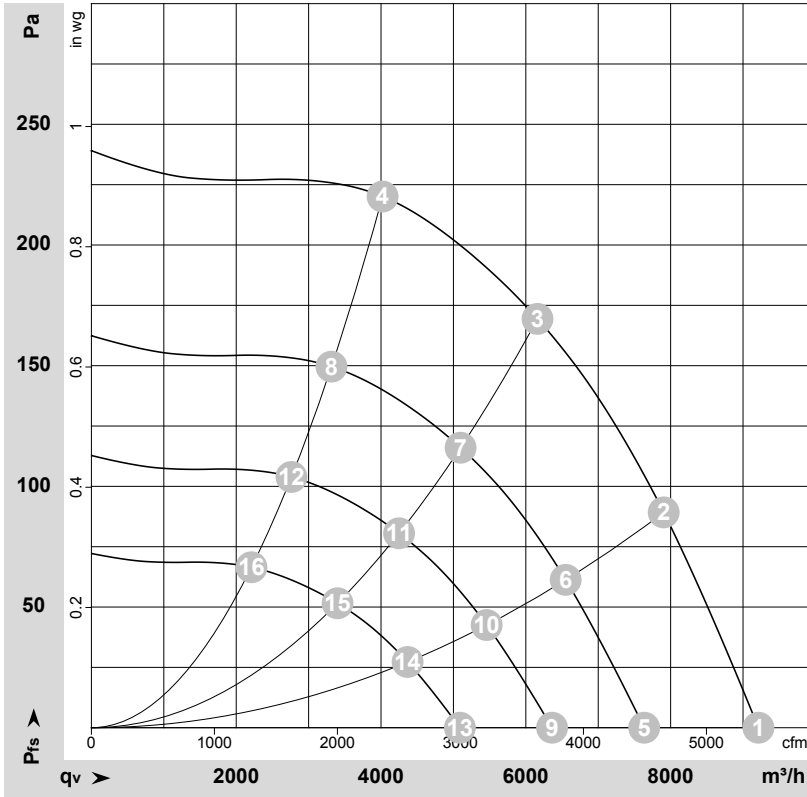
## Connection diagram



No.	Conn.	Designation	Function/assignment
PE	-	PE	Protective earth terminal
KL1	1, 2	N, L	Power supply 50/60 Hz
KL2	1	NC	Floating status contact, break for failure
KL2	2	COM	Floating status contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status contact, make for failure
KL3	1	OUT	Analog output, 0-10 VDC, max. 3 mA, SELV output of current motor modulation level: 1 V corresponds to 10% modulation level. 10 V corresponds to 100% modulation level.
KL3	2, 8	GND	Reference ground for control interface, SELV
KL3	3, 7	0-10 V	Control/current sensor value input 0-10 VDC, impedance 100 kΩ, use only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (+/- 3%), max. 10 mA, power supply for ext. devices (e.g. potentiometer), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25%/-10%), max. 50 mA power supply for ext. devices (e.g. sensors), SELV
KL3	6	4-20 mA	Control/current sensor value input 4-20 mA, impedance 100 Ω, use only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for MODBUS, RSB
KL3	10, 12	RSA	RS485 interface for MODBUS, RSA



## Curves: Air performance 50 Hz



$\rho = 1.15 \text{ kg/m}^3 \pm 2 \%$

Measurement: LU-166573-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebmpapst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

## Measured values

	U	f	n	P <sub>ed</sub>	I	qv	p <sub>fs</sub>	qv	p <sub>fs</sub>
	V	Hz	min <sup>-1</sup>	W	A	m <sup>3</sup> /h	Pa	CFM	inH2O
1	230	50	725	325	1.43	9215	0	5425	0.00
2	230	50	725	437	1.91	7905	90	4650	0.36
3	230	50	725	500	2.20	6160	170	3625	0.68
4	230	50	725	479	2.10	4020	220	2365	0.88
5	230	50	600	185	0.81	7635	0	4495	0.00
6	230	50	600	249	1.09	6550	61	3855	0.24
7	230	50	600	284	1.24	5100	117	3000	0.47
8	230	50	600	268	1.17	3315	151	1950	0.61
9	230	50	500	107	0.47	6360	0	3745	0.00
10	230	50	500	144	0.63	5460	43	3215	0.17
11	230	50	500	164	0.72	4250	81	2500	0.33
12	230	50	500	155	0.68	2765	105	1625	0.42
13	230	50	400	55	0.24	5090	0	2995	0.00
14	230	50	400	74	0.32	4365	27	2570	0.11
15	230	50	400	84	0.37	3400	52	2000	0.21
16	230	50	400	80	0.35	2210	67	1300	0.27

U = Power supply · f = Frequency · n = Speed (rpm) · P<sub>ed</sub> = Power consumption · I = Current draw · qv = Air flow · p<sub>fs</sub> = Pressure increase

