

R3G630-RB23-63

Emerson

# EC centrifugal fan - RadiCal

backward-curved, single-intake

ebm-papst ventilator (Shanghai)Co.,Ltd.

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R3G630-RB23-63 ebmpapst Datasheet

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## Nominal data

Type	R3G630-RB23-63	
Motor	M3G150-IF	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Method of obtaining data		ml
Status		prelim.
Speed (rpm)	min <sup>-1</sup>	1400
Power consumption	W	3550
Current draw	A	5.4
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	40

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment  
Subject to change

## Data according to ErP Directive

		Actual	Req. 2015			
01 Overall efficiency $\eta_{es}$	%	64.6	57.3	09 Power consumption $P_{ed}$	kW	3.56
02 Measurement category		A		09 Air flow $q_v$	m <sup>3</sup> /h	11985
03 Efficiency category		Static		09 Pressure increase $p_{fs}$	Pa	656
04 Efficiency grade N		69.3	62	10 Speed (rpm) n	min <sup>-1</sup>	1405
05 Variable speed drive		Yes		11 Specific ratio*		1.01

Data obtained at optimum efficiency level.

The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

\* Specific ratio =  $1 + p_{fs} / 100\,000\text{ Pa}$



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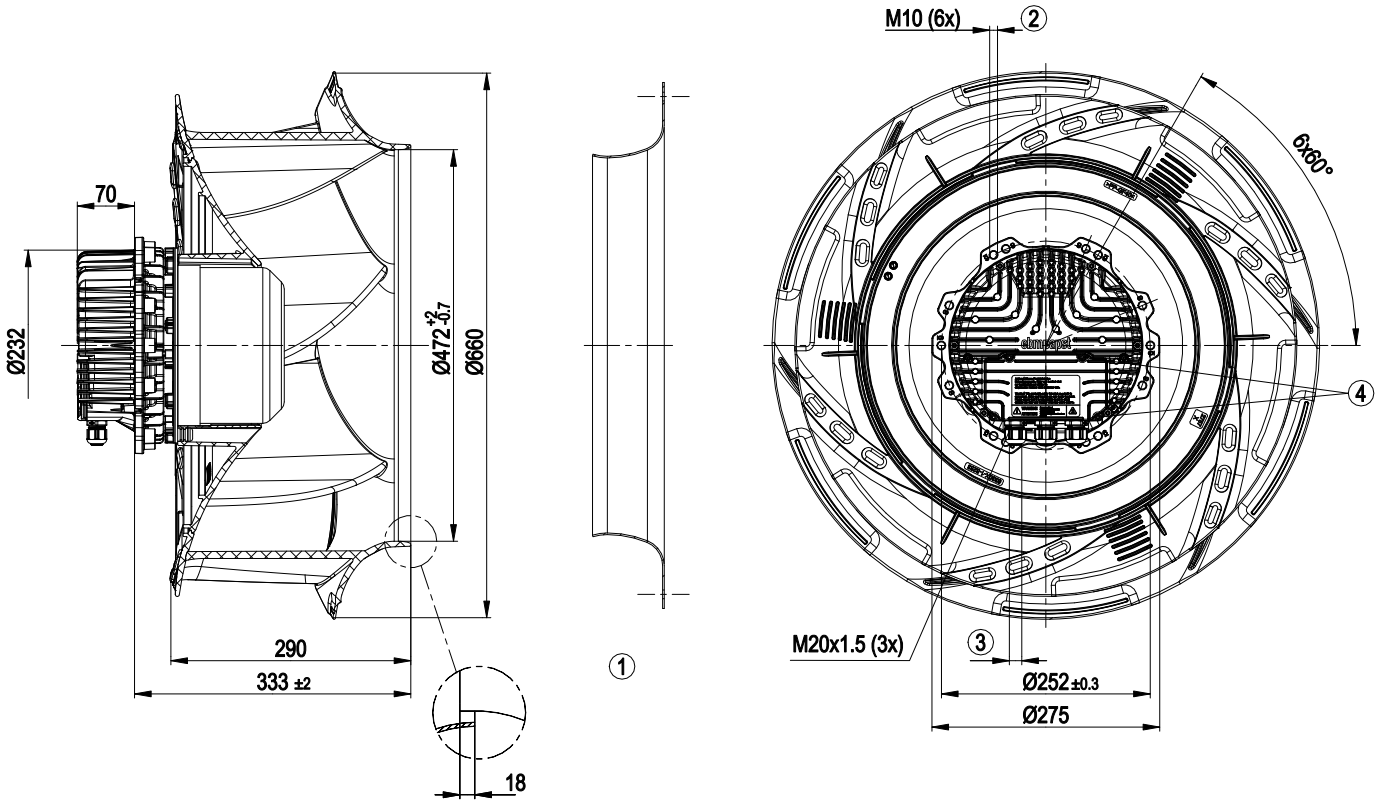
backward-curved, single-intake

## Technical description

<b>Weight</b>	31 kg
<b>Fan size</b>	630 mm
<b>Rotor surface</b>	Painted black
<b>Electronics housing material</b>	Die-cast aluminum
<b>Impeller material</b>	PP plastic
<b>Number of blades</b>	6
<b>Direction of rotation</b>	Clockwise, viewed toward rotor
<b>Degree of protection</b>	IP55
<b>Insulation class</b>	"F"
<b>Moisture (F) / Environmental (H) protection class</b>	H1
<b>Max. permitted ambient temp. for motor (transport/storage)</b>	+80 °C
<b>Min. permitted ambient temp. for motor (transport/storage)</b>	-40 °C
<b>Installation position</b>	Shaft horizontal or rotor on bottom
<b>Condensation drainage holes</b>	On rotor side
<b>Mode</b>	S1
<b>Motor bearing</b>	Ball bearing
<b>Technical features</b>	<ul style="list-style-type: none"> <li>- Output 10 VDC, max. 10 mA</li> <li>- Output 20 VDC, max. 50 mA</li> <li>- Output for slave 0-10 V</li> <li>- Operation and alarm display</li> <li>- Input for sensor 0-10 V or 4-20 mA</li> <li>- External 24 V input (parameter setting)</li> <li>- External release input</li> <li>- Alarm relay</li> <li>- Integrated PID controller</li> <li>- Motor current limitation</li> <li>- PFC, passive</li> <li>- RS-485 MODBUS-RTU</li> <li>- Soft start</li> <li>- Control input 0-10 VDC / PWM</li> <li>- Control interface with SELV potential safely disconnected from the mains</li> <li>- Thermal overload protection for electronics/motor</li> <li>- Line undervoltage / phase failure detection</li> </ul>
<b>Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)</b>	<= 3.5 mA
<b>Electrical hookup</b>	Via terminal box
<b>Motor protection</b>	Reverse polarity and locked-rotor protection
<b>Protection class</b>	I (with customer connection of protective earth)
<b>Conformity with standards</b>	EN 61800-5-1;
<b>Approval</b>	EAC; UL 1004-7 + 60730; C22.2 No.77 + CAN/CSA-E60730-1



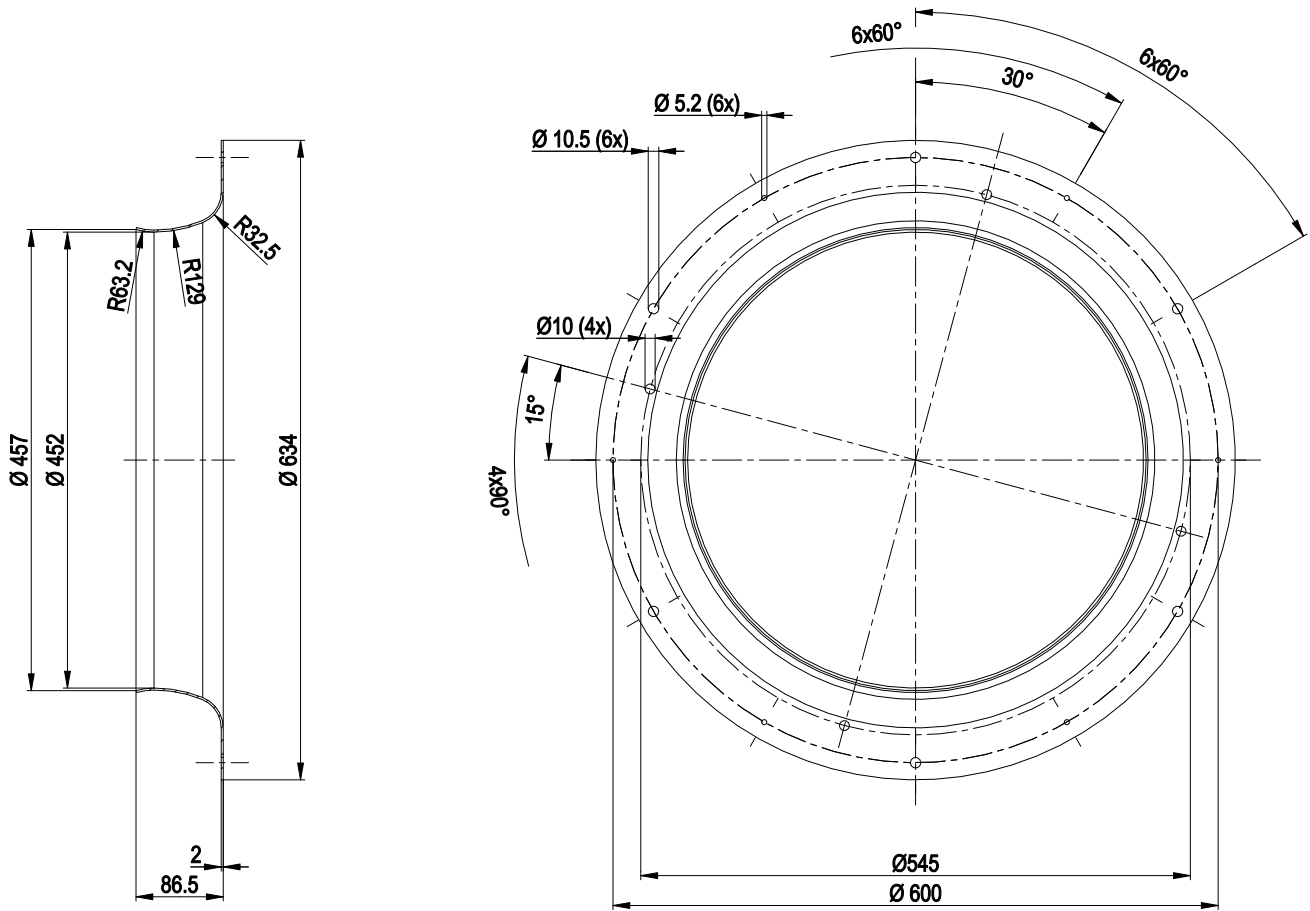
Product drawing



1	Accessory part: inlet ring 63300-2-4013 not included in scope of delivery
2	Max. clearance for screw 25 mm
3	Cable diameter min. 4 mm, max. 10 mm, tightening torque $4 \pm 0.6$ Nm
4	Tightening torque $3.5 \pm 0.5$ Nm

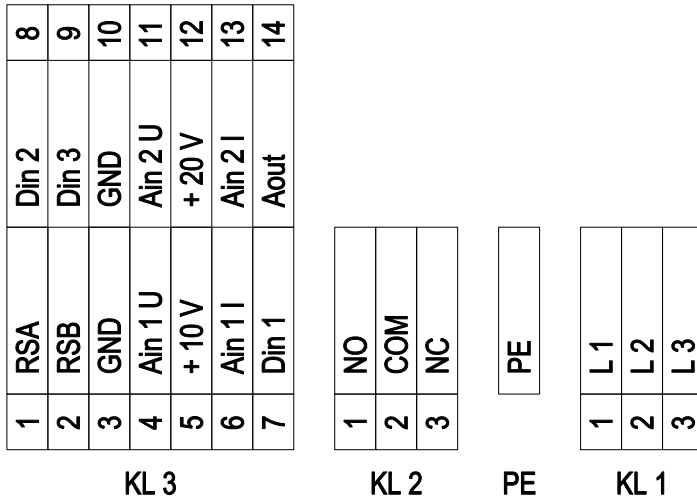


## Accessory part



Accessory part: inlet ring 63300-2-4013 not included in scope of delivery

## Connection diagram



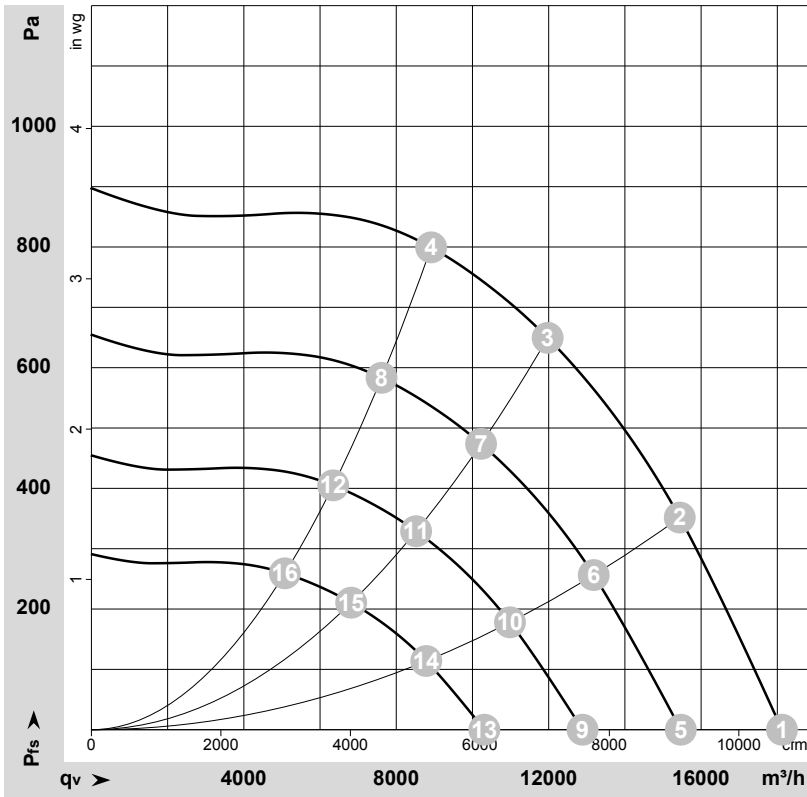
No.	Conn.	Designation	Function/assignment
KL 1	1	L1	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
KL 1	2	L2	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
KL 1	3	L3	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
PE		PE	Ground connection, PE connection
KL 2	1	NO	Status relay, floating status contact; make for failure
KL2	2	COM	Status relay, floating status contact; changeover contact; common connection; contact rating 250 VAC / max. 2 A (AC1) / min. 10 mA
KL2	3	NC	Status relay, floating status contact; break for failure
KL 3	1	RSA	Bus connection RS485, RSA, MODBUS-RTU; SELV
KL 3	2	RSB	Bus connection RS485, RSB, MODBUS-RTU; SELV
KL 3	3 / 10	GND	Reference ground for control interface; SELV
KL 3	4	Ain1 U	Analog input 1, set value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain1 I; SELV
KL 3	5	+ 10 V	Fixed voltage output 10 VDC, +10 V ±3%, max. 10 mA, short-circuit-proof power supply for external devices (e.g. pot); SELV
KL 3	6	Ain1 I	Analog input 1, set value: 4-20 mA, Ri = 100 Ω, adjustable curve, only usable as alternative to input Ain1U; SELV
KL 3	7	Din1	Digital input 1: enable electronics, enable: pin open or applied voltage 5-50 VDC disable: bridge to GND or applied voltage < 1 VDC reset function: triggers software reset after a level change to < 1 VDC; SELV
KL 3	8	Din2	Digital input 2: Switching parameter sets 1/2, according to EEPROM setting, the valid or used parameter set can be selected via bus or via digital input DIN2. Parameter set 1: pin open or applied voltage 5-50 VDC Parameter set 2: bridge to GND or applied voltage < 1 VDC; SELV
KL 3	9	Din3	Digital input 3: according to EEPROM setting, the integrated controller's direction of action can be selected as normal/inverse via bus or digital input normal: pin open or applied voltage 5-50 VDC inverse: bridge to GND or applied voltage < 1 VDC; SELV
KL 3	11	Ain2 U	Analog input 2, measured value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain2I; SELV
KL 3	12	+ 20 V	Fixed voltage output 20 VDC, +20 V ±5/-10%, max. 50 mA, short-circuit-proof power supply for external devices (e.g. sensors); SELV



No.	Conn.	Designation	Function/assignment
KL 3	13	Ain2 I	Analog input 2, measured value: 4-20 mA, Ri = 100 $\Omega$ , adjustable curve, only usable as alternative to input Ain2U; SELV
KL 3	14	Aout	Analog output 0-10 VDC, max. 5 mA, output of current motor modulation level / motor speed adjustable curve; SELV



## Curves: Air performance 50 Hz



$\rho = 1.15 \text{ kg/m}^3 \pm 2 \%$

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebmpapst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

## Measured values

	U	f	n	P <sub>ed</sub>	I	LpA <sub>in</sub>	LwA <sub>in</sub>	LwA <sub>out</sub>	qv	P <sub>fs</sub>	qv	P <sub>fs</sub>
	V	Hz	min <sup>-1</sup>	W	A	dB(A)	dB(A)	dB(A)	m <sup>3</sup> /h	Pa	CFM	inH <sub>2</sub> O
1	400	50	1400	2257	3.45	82	90	94	18120	0	10665	0.00
2	400	50	1400	3128	4.77	77	85	89	15440	350	9085	1.41
3	400	50	1400	3550	5.40	72	80	85	11970	650	7045	2.61
4	400	50	1400	3472	5.29	74	81	86	8915	800	5245	3.21
5	400	50	1200	1403	2.15	78	86	90	15465	0	9105	0.00
6	400	50	1200	1946	2.97	73	81	85	13180	257	7760	1.03
7	400	50	1200	2218	3.38	68	76	81	10225	479	6020	1.92
8	400	50	1200	2163	3.30	70	77	82	7615	583	4480	2.34
9	400	50	1000	812	1.24	74	81	85	12890	0	7585	0.00
10	400	50	1000	1126	1.72	69	76	81	10985	179	6465	0.72
11	400	50	1000	1284	1.96	64	71	77	8520	332	5015	1.33
12	400	50	1000	1252	1.91	65	73	78	6345	405	3735	1.63
13	400	50	800	416	0.64	68	76	80	10310	0	6070	0.00
14	400	50	800	577	0.88	63	70	75	8785	114	5170	0.46
15	400	50	800	657	1.00	58	65	71	6815	213	4010	0.86
16	400	50	800	641	0.98	60	67	72	5075	259	2990	1.04

U = Power supply · f = Frequency · n = Speed (rpm) · P<sub>ed</sub> = Power consumption · I = Current draw · LpA<sub>in</sub> = Sound pressure level intake side · LwA<sub>in</sub> = Sound power level intake side  
 LwA<sub>out</sub> = Sound power level outlet side · qv = Air flow · P<sub>fs</sub> = Pressure increase

