R3G560-RB31-71/F01
(exclusive type for Huawei)

EC centrifugal fan - RadiCal

backward-curved, single-intake

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R3G560-RB31-71/F01 ebmpapst Datasheet
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ErP2015 EXCEEDS THE NORM

Nominal data

Type	**R3G560-RB31-71/F01**
Motor	**M3G150-IF**

Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min^{-1}	1650
Power consumption	W	2900
Current draw	A	4.43
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	55

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to ErP Directive

		Actual	Req. 2015
01 Overall efficiency η_{es}	%	66.5	56.3
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		72.2	62
05 Variable speed drive		Yes	

09 Power consumption P_{ed}	kW	2.85
09 Air flow q_v	m^3/h	9375
09 Pressure increase p_{fs}	Pa	690
10 Speed (rpm) n	min^{-1}	1650
11 Specific ratio*		1.01

Data obtained at optimum efficiency level.
The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

* Specific ratio = 1 + p_{fs} / 100 000 Pa

LU-147559

ebmpapst

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Technical description

Weight	22.7 kg
Fan size	560 mm
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum
Impeller material	PP plastic
Number of blades	6
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	"F"
Moisture (F) / Environmental (H) protection class	F4-1
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (parameter setting) - External release input - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from supply - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC interference emission	According to EN 55022 (Class B, household environment)
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Via terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (if protective earth is connected by customer to the housing's connection point)
Conformity with standards	EN 61800-5-1
Approval	EAC

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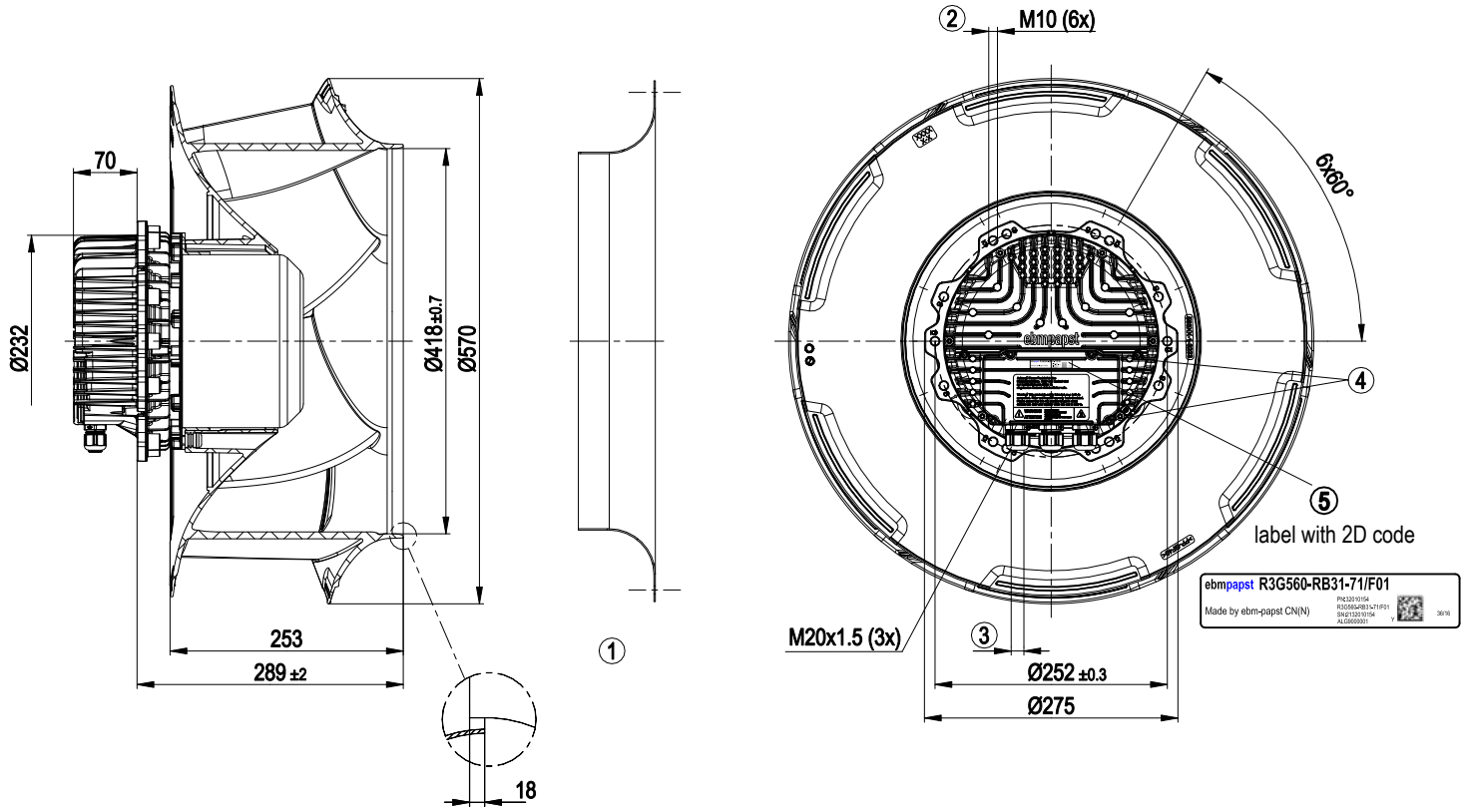
Product drawing



1	Accessory part: inlet ring 54482-2-4013 included in scope of delivery
2	Max. clearance for screw 25 mm
3	Cable diameter min. 4 mm, max. 10 mm, tightening torque 4±0.6 Nm
4	Tightening torque 3.5 ± 0.5 Nm
5	label with 2D code

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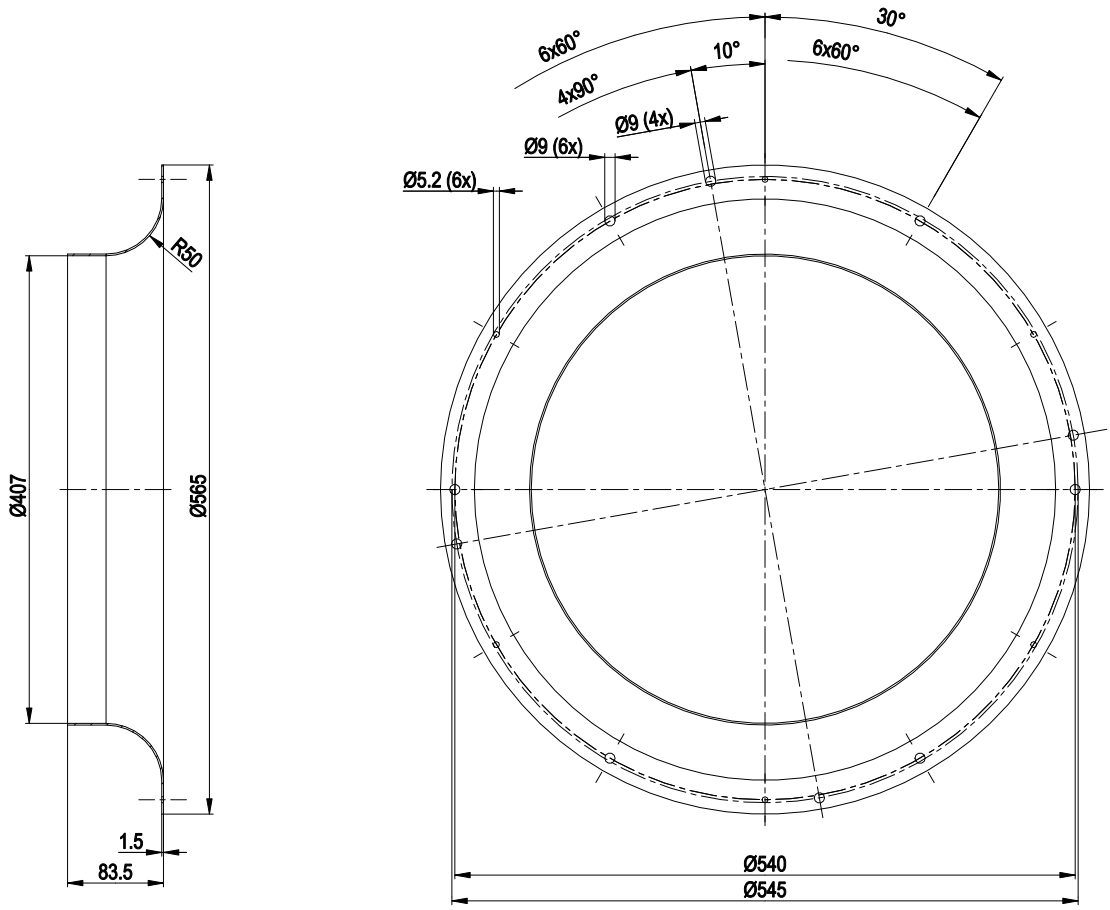
Accessory part



Accessory part: inlet ring 54482-2-4013 included in scope of delivery

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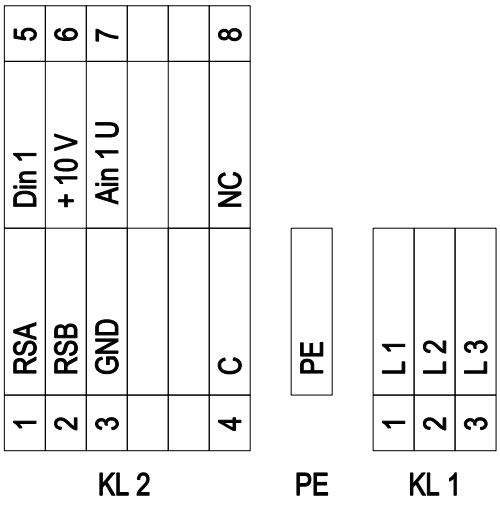
Connection diagram



No.	Conn.	Designation	Function/assignment
KL 1	1	L1	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
KL 1	2	L2	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
KL 1	3	L3	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
PE		PE	Ground connection, PE connection
KL 2	1	RSA	Bus connection RS485, RSA, MODBUS-RTU; SELV
KL 2	2	RSB	Bus connection RS485, RSB, MODBUS-RTU; SELV
KL 2	3	GND	Reference ground for control interface; SELV
KL2	4	C	Status relay, floating status contact, common connection, changeover contact; contact rating 250 VAC / 2 A (AC1)
KL 2	5	Din1	Digital input 1 enable electronics, enable: pin open or applied voltage 5-50 VDC disable: bridge to GND or applied voltage < 1 VDC reset function: triggers software reset after a level change to < 1 V; SELV
KL 2	6	+ 10 V	Fixed voltage output 10 VDC, +10 V ±3%, max. 10 mA, short-circuit-proof, power supply for external devices (e.g. pot); SELV Or: +24 VDC input for parameter setting via MODBUS without line voltage
KL 2	7	Ain1 U	Analog input 1 (set value) 0-10 V, Ri = 100 kΩ, adjustable curve; SELV
KL2	8	NC	Status relay, floating status contact, break for failure

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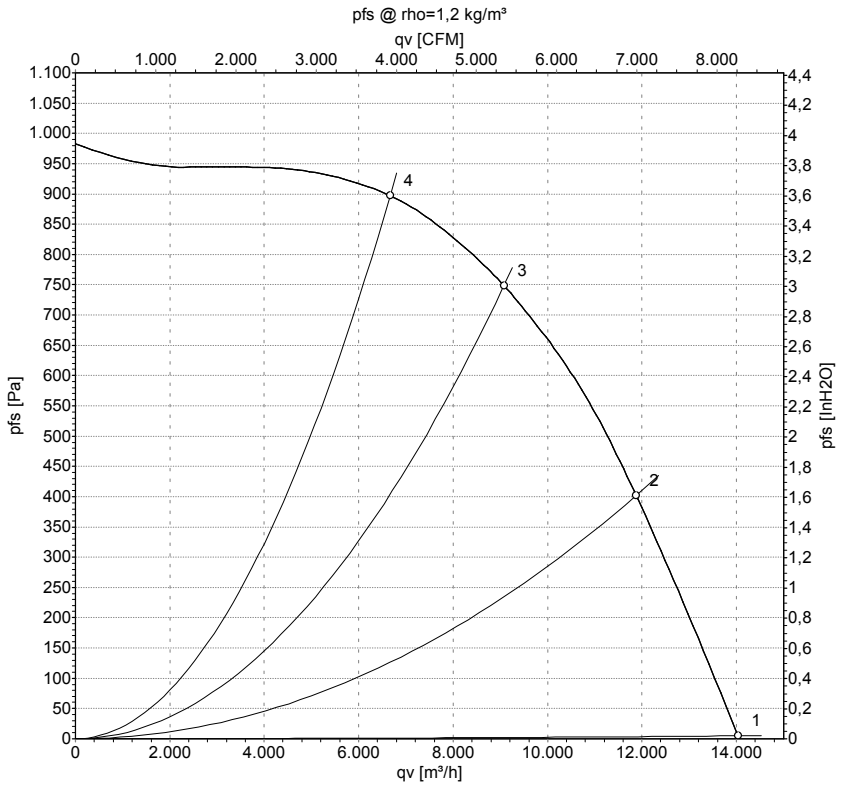
Curves: Air performance 50 Hz



Measurement: LU-147559-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	Wired	U	f	n	P_{ed}	I	LwA_{in}	qv	p_{fs}	qv	p_{fs}
		V	Hz	min^{-1}	W	A	dB(A)	m^3/h	Pa	CFM	inH2O
1	Y	400	50	1650	2010	3.10	87	14040	0	8265	0.00
2	Y	400	50	1650	2630	4.10	81	11900	400	7005	1.61
3	Y	400	50	1650	2900	4.43	77	9100	750	5355	3.01
4	Y	400	50	1650	2770	4.30	80	6670	900	3925	3.61

Wired = Wiring · U = Power supply · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LwA_{in} = Sound power level intake side · qv = Air flow · p_{fs} = Pressure increase