

R3G500-RH34-05 ebmpapst Datasheet
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Nominal data

| | | |
|--------------------------|-------------------|------------|
| Type | R3G500-RH34-05 | |
| Motor | M3G112-GA | |
| Phase | | 3~ |
| Nominal voltage | VAC | 400 |
| Nominal voltage range | VAC | 380 .. 480 |
| Frequency | Hz | 50/60 |
| Method of obtaining data | | ml |
| Speed (rpm) | min ⁻¹ | 1160 |
| Power consumption | W | 860 |
| Current draw | A | 1.5 |
| Min. ambient temperature | °C | -25 |
| Max. ambient temperature | °C | 60 |

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
 Subject to change

Data according to ErP Directive

| | | Actual | Req. 2015 | | | |
|-----------------------------------|---|--------|-----------|--------------------------------|-------------------|------|
| 01 Overall efficiency η_{es} | % | 65.5 | 50.7 | 09 Power consumption P_{ed} | kW | 0.84 |
| 02 Measurement category | | A | | 09 Air flow q_v | m ³ /h | 5000 |
| 03 Efficiency category | | Static | | 09 Pressure increase p_{fs} | Pa | 367 |
| 04 Efficiency grade N | | 76.8 | 62 | 10 Speed (rpm) n | min ⁻¹ | 1160 |
| 05 Variable speed drive | | Yes | | 11 Specific ratio [*] | | 1.00 |

Data obtained at optimum efficiency level.

The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

^{*} Specific ratio = $1 + p_{fs} / 100\,000\text{ Pa}$

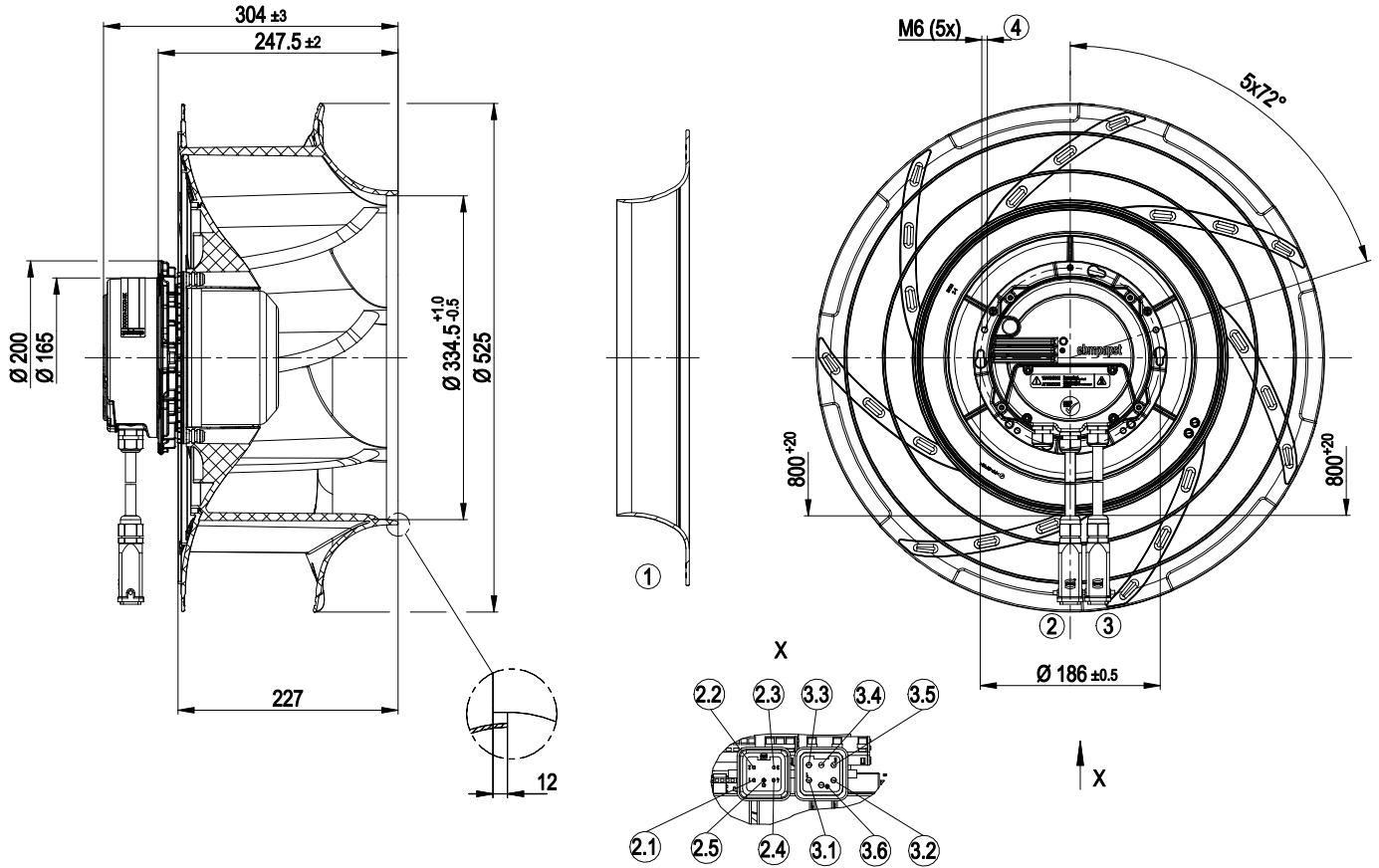
LU-125039



Technical description

| | |
|--|--|
| Weight | 13.1 kg |
| Fan size | 500 mm |
| Rotor surface | Painted black |
| Electronics housing material | Die-cast aluminum |
| Impeller material | PP plastic |
| Number of blades | 7 |
| Direction of rotation | Clockwise, viewed toward rotor |
| Degree of protection | IP54 |
| Insulation class | "B" |
| Moisture (F) / Environmental (H) protection class | F4-1 |
| Max. permitted ambient temp. for motor (transport/storage) | +80 °C |
| Min. permitted ambient temp. for motor (transport/storage) | -40 °C |
| Installation position | Shaft horizontal or rotor on bottom; rotor on top on request |
| Condensation drainage holes | On rotor side |
| Mode | S1 |
| Motor bearing | Ball bearing |
| Technical features | <ul style="list-style-type: none"> - Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - External 24 V input (parameter setting) - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from supply - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection |
| EMC immunity to interference | According to EN 61000-6-2 (industrial environment) |
| EMC circuit feedback | According to EN 61000-3-2/3 |
| EMC interference emission | According to EN 61000-6-3 (household environment) |
| Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system) | <= 3.5 mA |
| Electrical hookup | With plug |
| Motor protection | Thermal overload protector (TOP) internally connected |
| With cable | Variable |
| Protection class | I (with customer connection of protective earth) |
| Conformity with standards | EN 61800-5-1; CE |
| Approval | CCC |

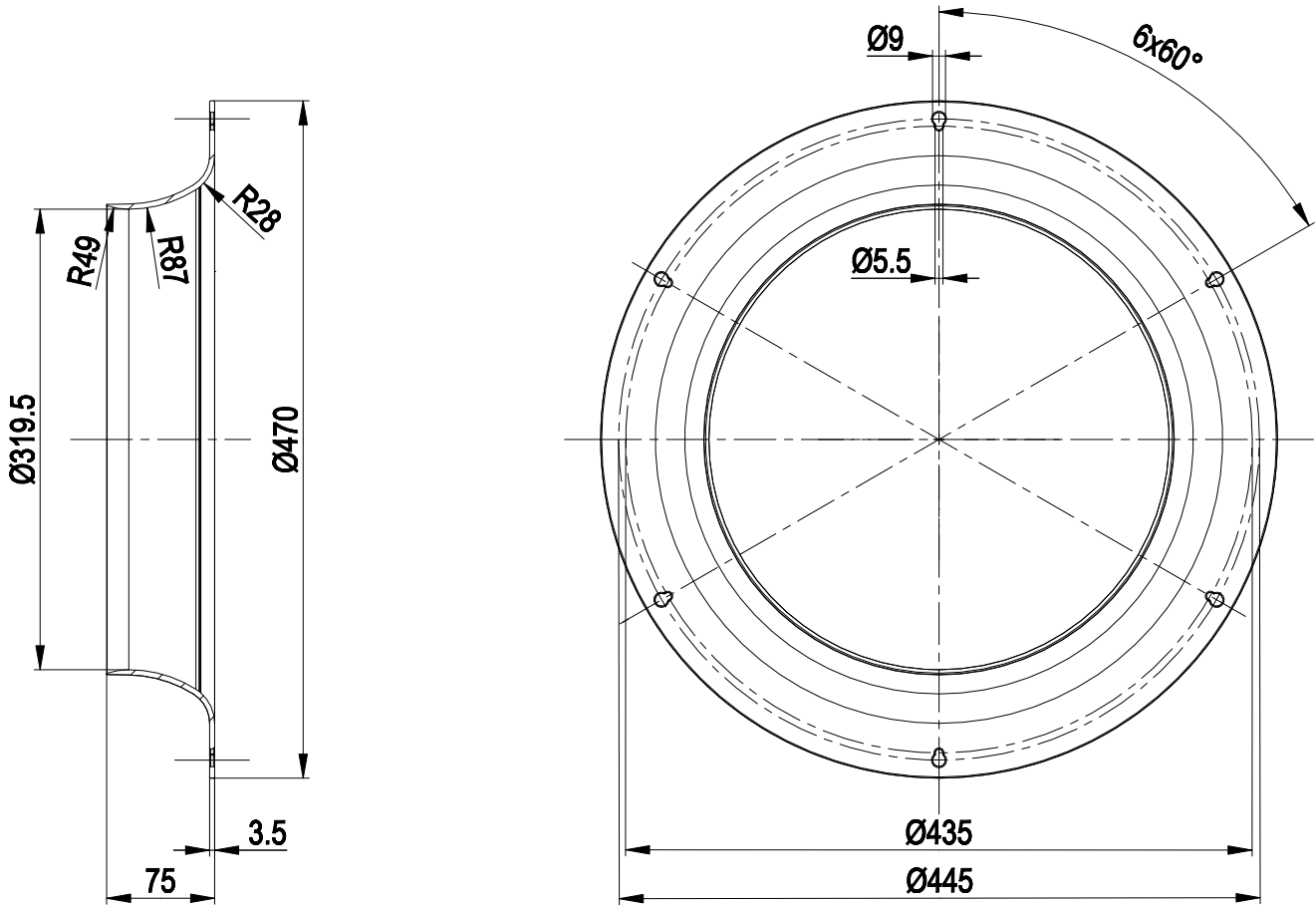
Product drawing



| | |
|-----|--|
| 1 | Accessory part: inlet ring 50901-2-2943, not included in scope of delivery |
| 2 | Control wire with connector housing Harting 19 20 003 0420 and pin insert Harting 09 20 004 2611 |
| 2.1 | NC (black1) |
| 2.2 | COM (black2) |
| 2.3 | GND (black3) |
| 2.4 | 0-10 V (black4) |
| 2.5 | PE (not used) |
| 3 | Supply line with connector housing Harting 19 20 003 0420 and pin insert Harting 09 12 005 3001 |
| 3.1 | L1 (black1) |
| 3.2 | L2 (black2) |
| 3.3 | L3 (black3) |
| 3.4 | not used |
| 3.5 | not used |
| 3.6 | PE (green/yellow) |
| 4 | Clearance for screw 12-16 mm |



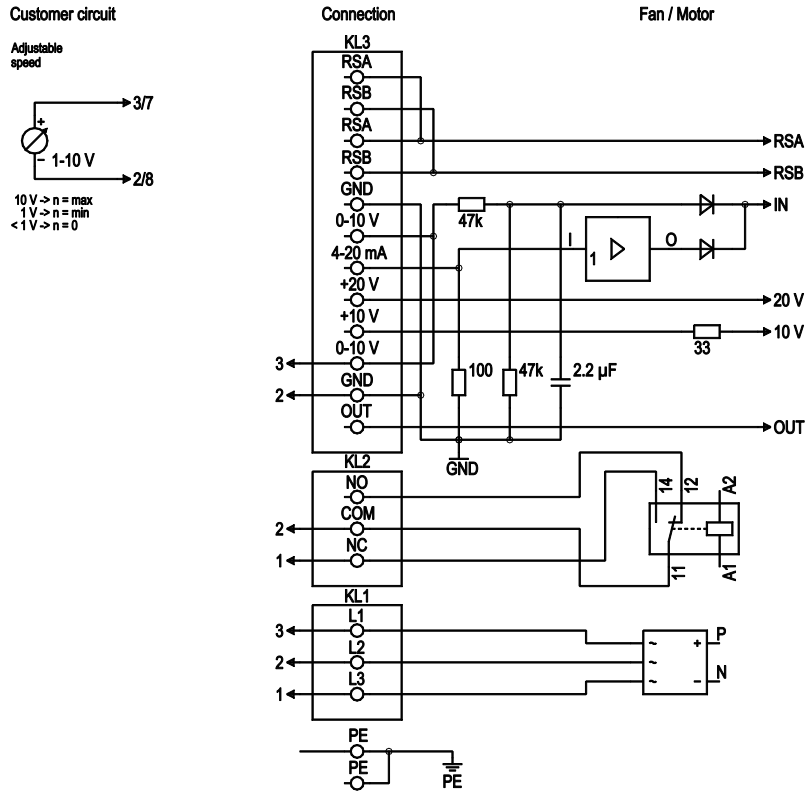
Accessory part



1 Accessory part: inlet ring 50901-2-2943



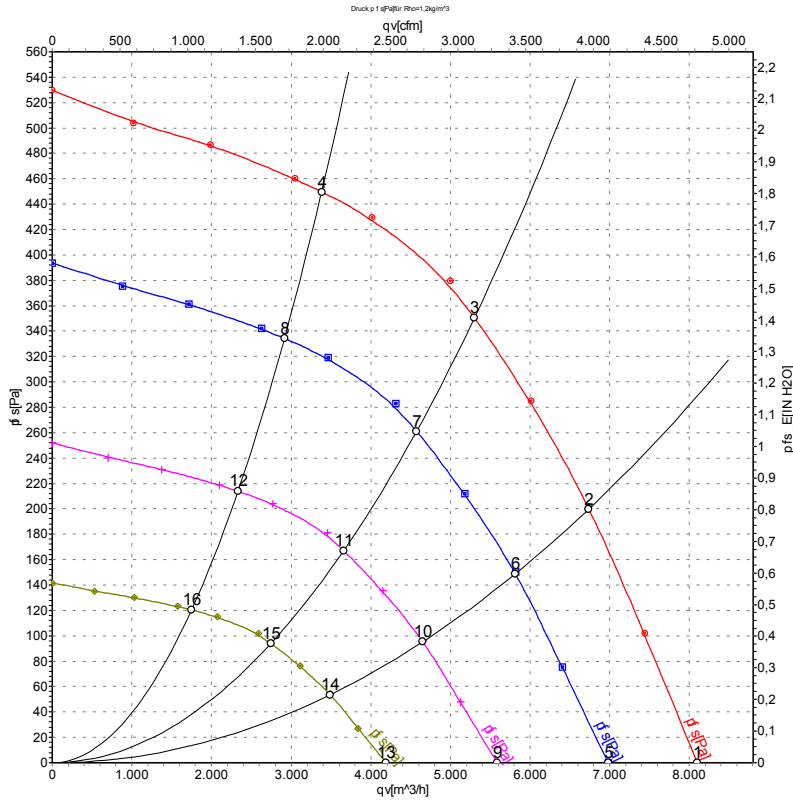
Connection diagram



| No. | Conn. | Designation | Function/assignment |
|-----|---------|-------------|---|
| PE | | PE | Protective earth terminal |
| KL1 | 1, 2, 3 | L1, L2, L3 | Power supply, voltage range (see nameplate), 50/60 Hz |
| KL2 | 1 | NC | Floating status contact, break for failure |
| KL2 | 2 | COM | floating status contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1) |
| KL2 | 3 | NO | Floating status contact, make for failure |
| KL3 | 1 | OUT | Analog output, 0-10 VDC, max. 3 mA, SELV, output of current motor modulation level: 1 V corresponds to 10% modulation level. 10 V corresponds to 100% modulation level. |
| KL3 | 2, 8 | GND | Reference ground for control interface, SELV |
| KL3 | 3, 7 | 0-10 V | Use control / current sensor value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV |
| KL3 | 4 | +10 V | Voltage output 10 VDC (±3%), max. 10 mA, power supply for external devices (e.g. potentiometer), SELV |
| KL3 | 5 | +20 V | Voltage output 20 VDC (+25%/-10%), max. 50 mA, power supply for external devices (e.g. sensors), SELV |
| KL3 | 6 | 4-20 mA | Use control / current sensor value input 4-20 mA, impedance 100 Ω only as alternative to 0-10 V input, SELV |
| KL3 | 9, 11 | RSB | RS485 interface for MODBUS, RSB |
| KL3 | 10, 12 | RSA | RS485 interface for MODBUS, RSA |



Curves: Air performance 50 Hz



Measurement: LU-125039-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebmpapst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

| | U | f | n | P _{ed} | I | LpA _{in} | LwA _{in} | LwA _{out} | qv | P _{fs} | qv | P _{fs} |
|----|-----|----|-------------------|-----------------|------|-------------------|-------------------|--------------------|-------------------|-----------------|------|--------------------|
| | V | Hz | min ⁻¹ | W | A | dB(A) | dB(A) | dB(A) | m ³ /h | Pa | CFM | inH ₂ O |
| 1 | 400 | 50 | 1160 | 588 | 0.99 | 68 | 75 | 82 | 8095 | 0 | 4765 | 0.00 |
| 2 | 400 | 50 | 1160 | 766 | 1.22 | 64 | 71 | 77 | 6735 | 200 | 3965 | 0.80 |
| 3 | 400 | 50 | 1160 | 860 | 1.50 | 60 | 67 | 72 | 5300 | 350 | 3120 | 1.41 |
| 4 | 400 | 50 | 1160 | 777 | 1.25 | 61 | 68 | 73 | 3385 | 450 | 1990 | 1.81 |
| 5 | 400 | 50 | 1000 | 377 | 0.64 | 65 | 72 | 78 | 6980 | 0 | 4110 | 0.00 |
| 6 | 400 | 50 | 1000 | 493 | 0.78 | 61 | 68 | 74 | 5815 | 151 | 3420 | 0.61 |
| 7 | 400 | 50 | 1000 | 540 | 0.89 | 56 | 63 | 69 | 4575 | 262 | 2695 | 1.05 |
| 8 | 400 | 50 | 1000 | 498 | 0.80 | 58 | 65 | 69 | 2915 | 334 | 1715 | 1.34 |
| 9 | 400 | 50 | 800 | 193 | 0.33 | 60 | 67 | 73 | 5585 | 0 | 3285 | 0.00 |
| 10 | 400 | 50 | 800 | 252 | 0.40 | 56 | 63 | 69 | 4650 | 97 | 2735 | 0.39 |
| 11 | 400 | 50 | 800 | 276 | 0.45 | 52 | 59 | 64 | 3660 | 168 | 2155 | 0.67 |
| 12 | 400 | 50 | 800 | 255 | 0.41 | 53 | 60 | 65 | 2335 | 214 | 1375 | 0.86 |
| 13 | 400 | 50 | 600 | 81 | 0.14 | 54 | 61 | 67 | 4190 | 0 | 2465 | 0.00 |
| 14 | 400 | 50 | 600 | 106 | 0.17 | 50 | 56 | 63 | 3490 | 54 | 2055 | 0.22 |
| 15 | 400 | 50 | 600 | 117 | 0.19 | 45 | 52 | 58 | 2745 | 94 | 1615 | 0.38 |
| 16 | 400 | 50 | 600 | 108 | 0.17 | 46 | 54 | 58 | 1750 | 120 | 1030 | 0.48 |

U = Power supply · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
 LwA_{out} = Sound power level outlet side · qv = Air flow · P_{fs} = Pressure increase

