

R3G500-AG34-20 ebmpapst Datasheet

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Nominal data

Type	R3G500-AG34-20	
Motor	M3G150-FF	
Phase		3
Nominal voltage	VAC	200
Nominal voltage range	VAC	200 .. 240
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min ⁻¹	1700
Power consumption	W	2700
Current draw	A	8.3
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	55

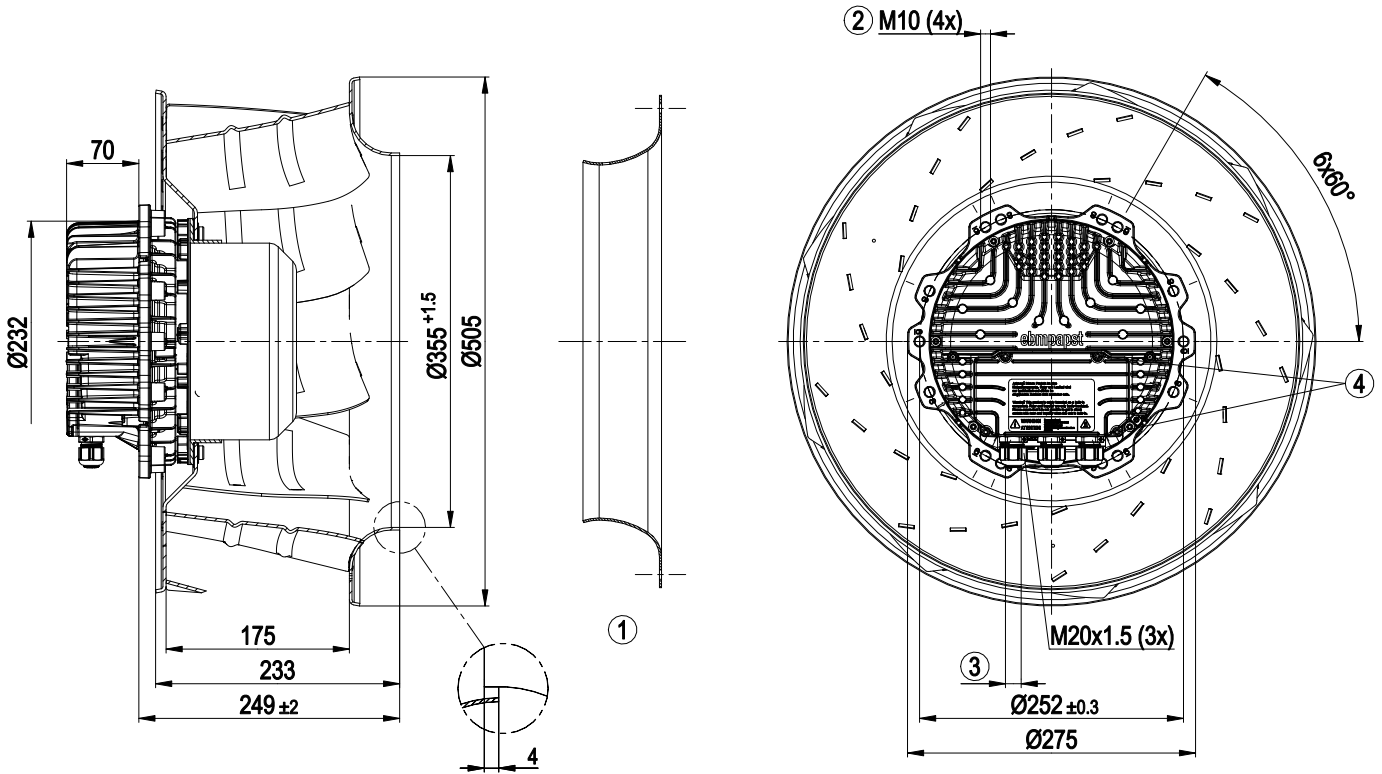
ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change



Technical description

Weight	22.7 kg
Size	500 mm
Motor size	150
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum
Impeller material	Sheet aluminum
Number of blades	9
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	"F"
Moisture (F) / Environmental (H) protection class	H1
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	<ul style="list-style-type: none"> - Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - External 24 V input (parameter setting) - External release input - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1
Approval	EAC; UL 1004-7 + 60730; CSA C22.2 No. 77 + CAN/CSA-E60730-1

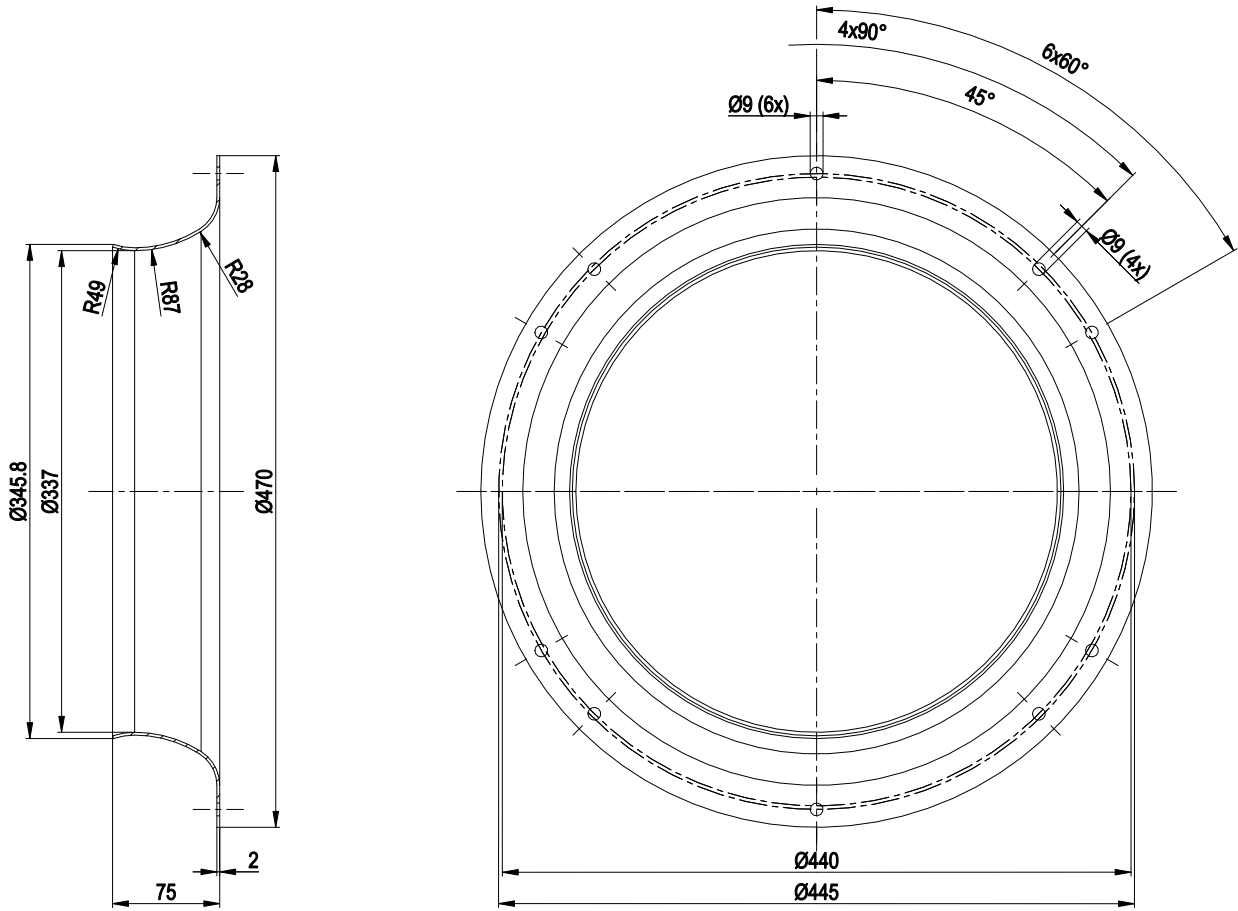
Product drawing



1	Accessory part: inlet ring 63072-2-4013 not included in scope of delivery
2	Max. clearance for screw 25 mm
3	Cable diameter min. 4 mm, max. 10 mm, tightening torque 4 ± 0.6 Nm
4	Tightening torque 3.5 ± 0.5 Nm

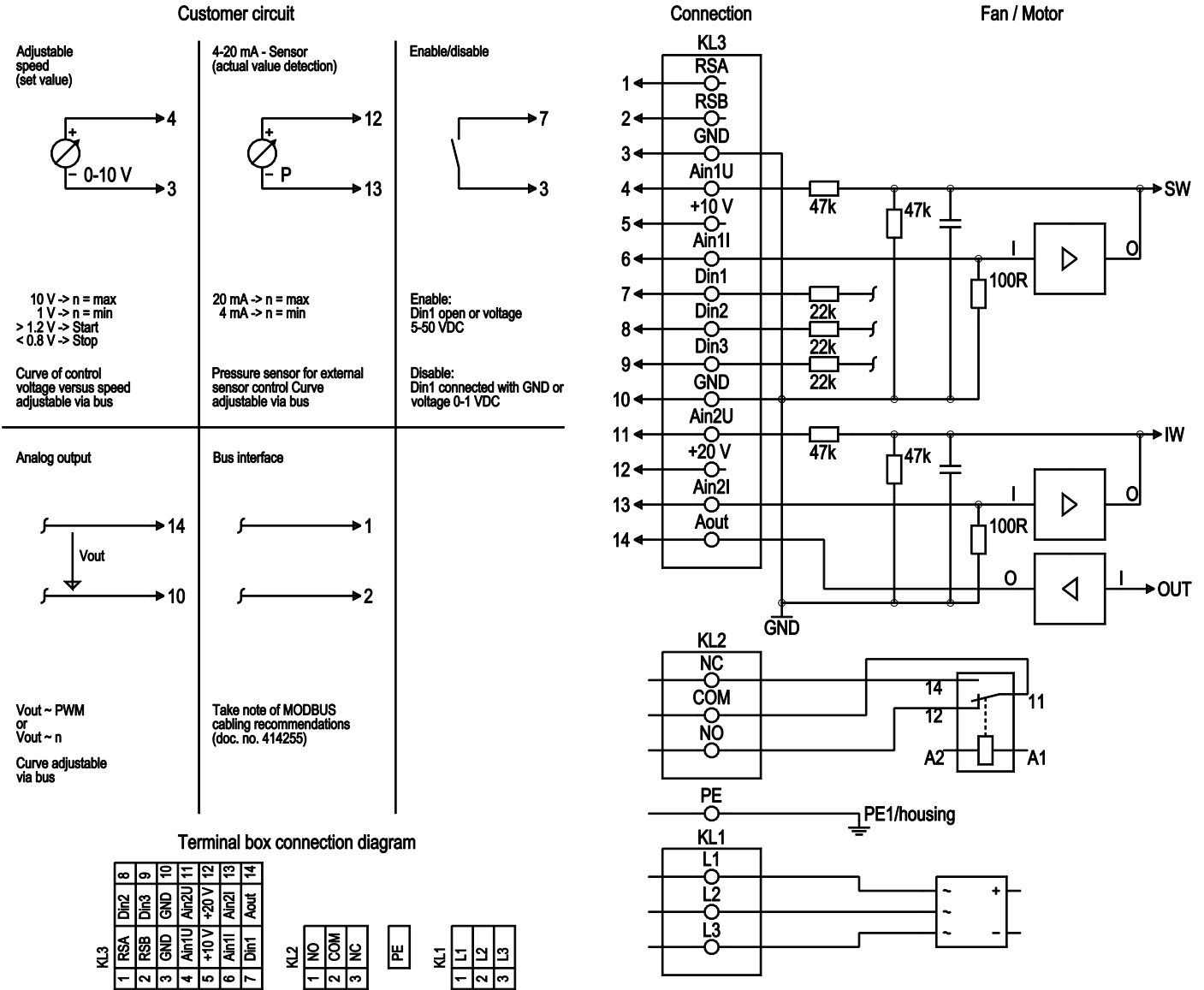


Accessory part



inlet ring 63072-2-4013 not included in scope of delivery

Connection diagram

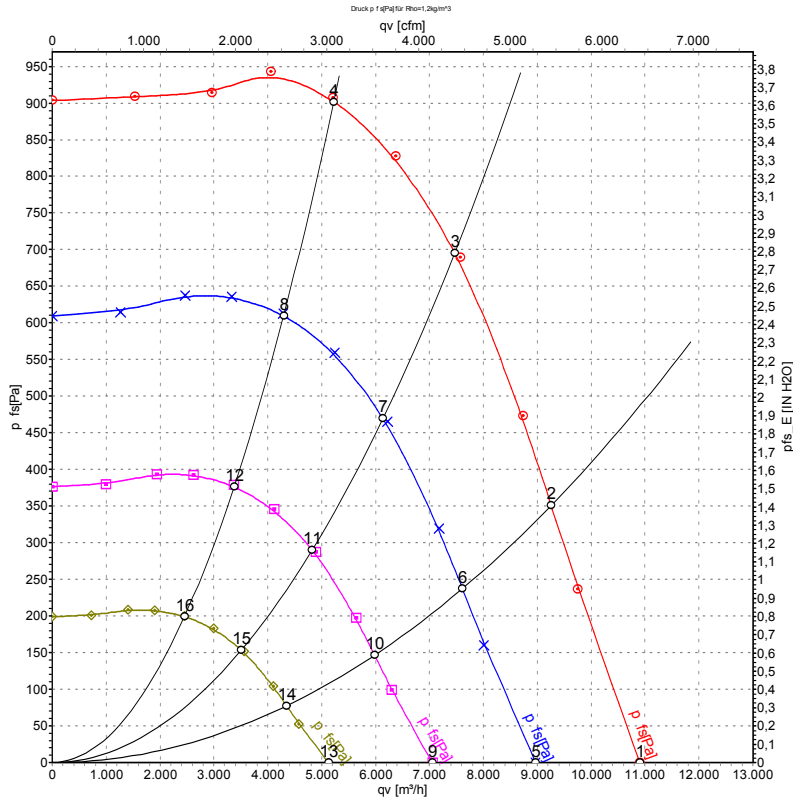


No.	Conn.	Designation	Function/assignment
KL 1	1	L1	Supply connection, power supply; for nominal voltage range see technical data
KL 1	2	L2	Supply connection, power supply; for nominal voltage range see technical data
KL 1	3	L3	Supply connection, power supply; for nominal voltage range see technical data
PE		PE	Ground connection, PE connection
KL 2	1	NO	Status relay, floating status contact, make for failure
KL2	2	COM	Status relay, floating status contact, changeover contact, common connection, contact rating 250 VAC / max. 2 A (AC1) / min. 10 mA
KL2	3	NC	Status relay, floating status contact, break for failure
KL 3	1	RSA	Bus connection RS485, RSA, MODBUS-RTU; SELV
KL 3	2	RSB	Bus connection RS485, RSB, MODBUS-RTU; SELV
KL 3	3 / 10	GND	Reference ground for control interface; SELV
KL 3	4	Ain1 U	Analog input 1, set value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain1I; SELV



No.	Conn.	Designation	Function/assignment
KL 3	5	+ 10 V	Fixed voltage output 10 VDC, +10 V \pm 3%, max. 10 mA, short-circuit-proof power supply for external devices (e.g. pot); SELV
KL 3	6	Ain1 I	Analog input 1, set value: 4-20 mA, $R_i = 100 \Omega$, adjustable curve, only usable as alternative to input Ain1U; SELV
KL 3	7	Din1	Digital input 1: enable electronics, enable: pin open or applied voltage 5-50 VDC disable: bridge to GND or applied voltage < 1 VDC reset function: triggers software reset after a level change to < 1 VDC; SELV
KL 3	8	Din2	Digital input 2: Switching parameter sets 1/2, according to EEPROM setting, the valid or used parameter set can be selected via bus or via digital input DIN2. Parameter set 1: pin open or applied voltage 5-50 VDC Parameter set 2: bridge to GND or applied voltage < 1 VDC; SELV
KL 3	9	Din3	Digital input 3: according to EEPROM setting, the integrated controller's direction of action can be selected via bus or digital input Din3; normal: pin open or applied voltage 5-50 VDC inverse: bridge to GND or applied voltage < 1 VDC; SELV
KL 3	11	Ain2 U	Analog input 2, measured value: 0-10 V, $R_i = 100 \text{ k}\Omega$, adjustable curve, only usable as alternative to input Ain2I; SELV
KL 3	12	+ 20 V	Fixed voltage output 20 VDC, +20 V +25/-10%, max. 50 mA, short-circuit-proof power supply for external devices (e.g. sensors); SELV or: +24 VDC input for parameter setting without line voltage
KL 3	13	Ain2 I	Analog input 2, measured value: 4-20 mA, $R_i = 100 \Omega$, adjustable curve, only usable as alternative to input Ain2U; SELV
KL 3	14	Aout	Analog output 0-10 VDC, max. 5 mA, output of current motor modulation level / motor speed adjustable curve; SELV

Curves: Air performance 50 Hz



Measurement: LU-134784-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebmpapst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	Wired	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	LwA _{out}	q _v	P _{fs}	q _v	P _{fs}
		V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m ³ /h	Pa	cfm	in. wg
1	Y	200	50	1700	1909	6.59	84	91	96	10900	0	6415	0.00
2	Y	200	50	1700	2329	7.88	79	86	92	9260	350	5450	1.41
3	Y	200	50	1700	2700	8.30	75	82	89	7465	700	4395	2.81
4	Y	200	50	1700	2382	8.00	74	81	88	5220	900	3075	3.61
5	Y	200	50	1400	1065	3.67	80	87	91	8970	0	5280	0.00
6	Y	200	50	1400	1294	4.38	75	82	88	7610	237	4480	0.95
7	Y	200	50	1400	1436	4.83	71	78	85	6135	474	3610	1.90
8	Y	200	50	1400	1323	4.44	70	77	83	4295	613	2525	2.46
9	Y	200	50	1100	516	1.78	74	82	86	7050	0	4150	0.00
10	Y	200	50	1100	628	2.12	70	77	83	5980	146	3520	0.59
11	Y	200	50	1100	697	2.34	66	73	79	4820	293	2840	1.18
12	Y	200	50	1100	642	2.16	65	72	78	3375	378	1985	1.52
13	Y	200	50	800	199	0.69	67	75	79	5125	0	3020	0.00
14	Y	200	50	800	241	0.82	63	70	76	4350	77	2560	0.31
15	Y	200	50	800	268	0.90	59	66	72	3505	155	2065	0.62
16	Y	200	50	800	247	0.83	58	65	71	2455	200	1445	0.80

Wired = Wiring · U = Voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
 LwA_{out} = Sound power level outlet side · q_v = Air flow · P_{fs} = Pressure increase

