

EC centrifugal fan

backward curved, single inlet



R3G500-AC09-05 ebmpapst Datasheet
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Nominal data

Type	R3G500-AC09-05	
Motor	M3G150-FF	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
Speed	min ⁻¹	2020
Power input	W	2400
Current draw	A	3.7
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	60

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations

Data according to ErP directive

Installation category	A
Efficiency category	Static
Variable speed drive	Yes
Specific ratio*	1.01

* Specific ratio = $1 + p_{fs} / 100\,000\text{ Pa}$

		Actual	Request 2013	Request 2015
Overall efficiency η_{es}	%	59.1	51.4	55.4
Efficiency grade N		65.7	58	62
Power input P_{ed}	kW	2.35		
Air flow q_v	m ³ /h	5410		
Pressure increase p_{fs}	Pa	873		
Speed n	min ⁻¹	2030		

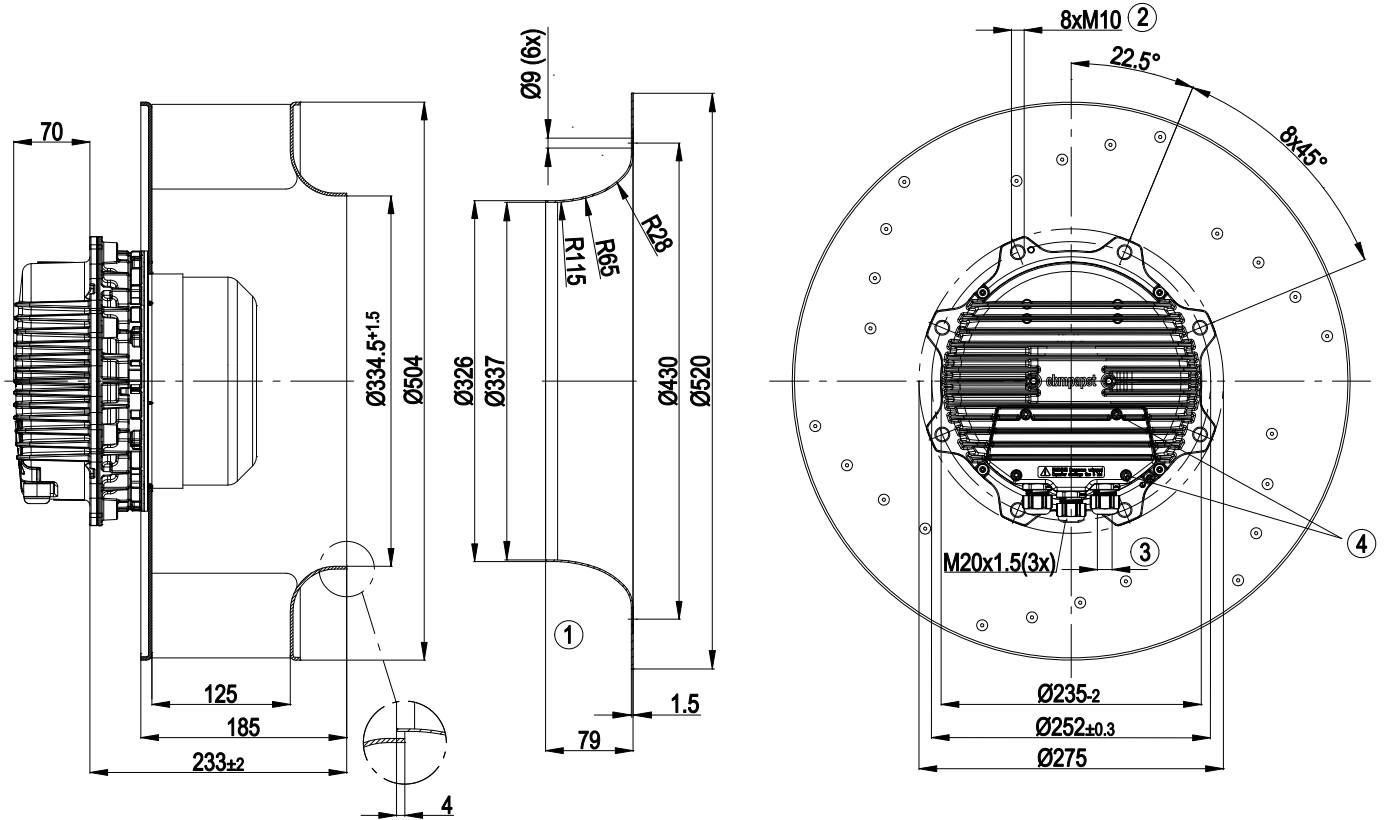
Data definition with optimum efficiency. LU-109664
The ErP data is determined using a motor-impeller combination in a standardised measurement configuration.



Technical features

Mass	21 kg
Size	500 mm
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium
Material of impeller	Aluminium sheet
Number of blades	6
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP 54
Insulation class	"F"
Humidity class	F4-1
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Shaft horizontal or rotor on bottom
Condensate discharge holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive - RS485 ebmBUS - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection
EMC interference immunity	Acc. to EN 61000-6-2
EMC interference emission	Acc. to EN 61000-6-3
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical leads	Via terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE
Approval	UL 2111; VDE; EAC; CSA C22.2 Nr.77

Product drawing

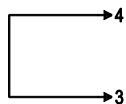


1	Accessory part: Inlet nozzle 54480-2-4013, not included in the standard scope of delivery.
2	Depth of screw max. 25 mm
3	Cable diameter: min. 4 mm, max. 10 mm, tightening torque: 4±0.6 Nm
4	Tightening torque 3.5±0.5 Nm

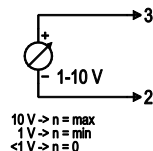
Connection screen

Customer circuit

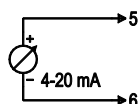
Full speed



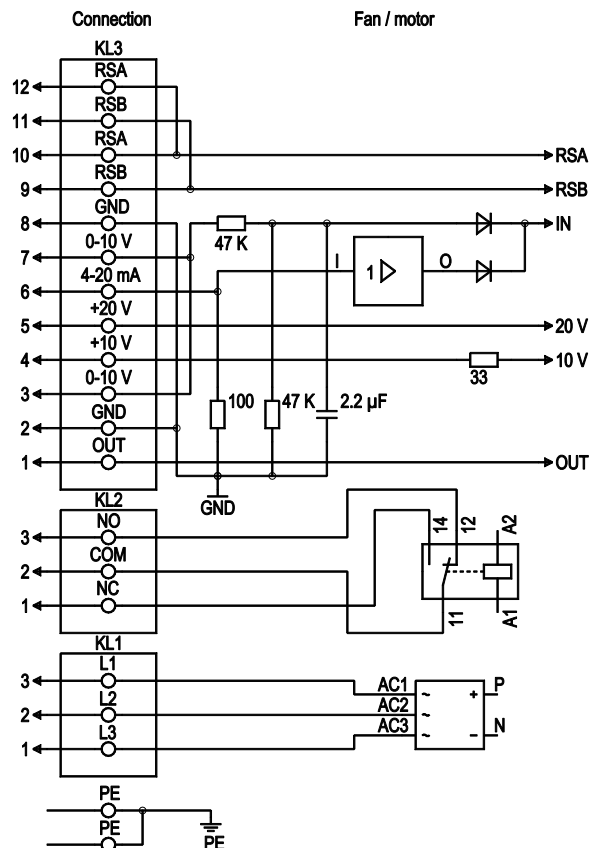
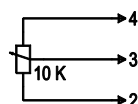
Speed setting



Setting of values, e.g. via pressure

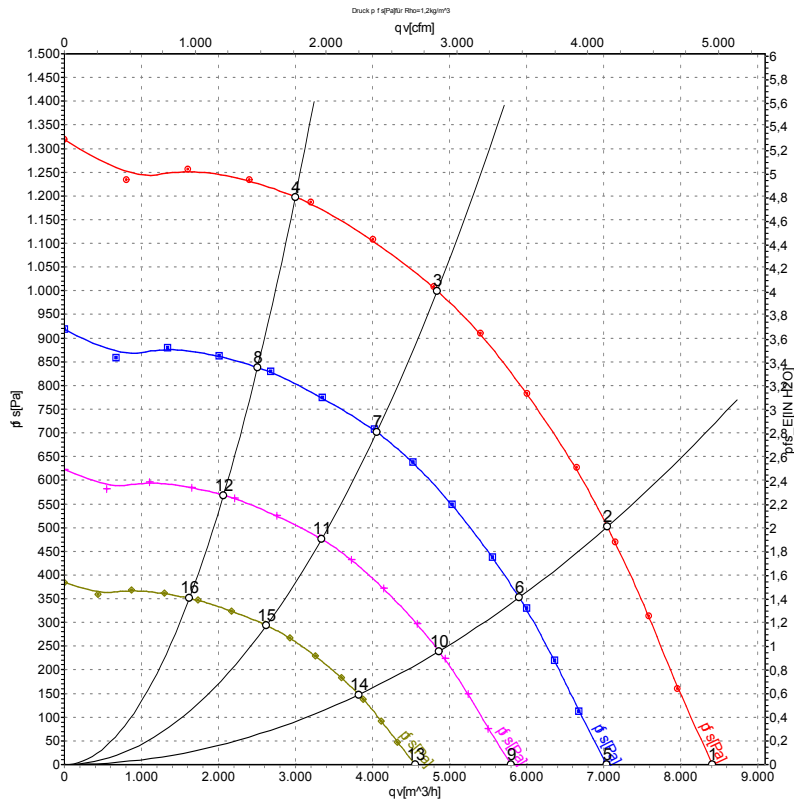


Speed setting via potentiometer



No.	Conn.	Designation	Function / assignment
PE		PE	Protective earth connection
KL1	1, 2, 3	L1, L2, L3	Supply voltage, 50/60 Hz
KL2	1	NC	Floating status message contact, normally closed connection
KL2	2	COM	Floating status message contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status message contact, normally open connection
KL3	1	OUT	Analog output, 0-10 VDC, max. 3 mA, SELV, output of the current level control coefficient: 1 V equates to 10 % level control coefficient. 10 V equate to 100 % level control coefficient.
KL3	2, 8	GND	Reference mass for control interface, SELV
KL3	3, 7	0-10 V	Use control / actual value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (+/-3 %), max. 10 mA, supply voltage for ext. devices (e.g. potentiometers), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25 %/-10 %), max. 50 mA, supply voltage for ext. devices (e.g. sensors), SELV
KL3	6	4-20 mA	Use control / actual value input 4-20 mA, impedance 100 Ω, only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for ebmBus, RSB, SELV
KL3	10, 12	RSA	RS485 interface for ebmBus, RSA, SELV

Charts: Air flow 50 Hz



Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebm-papst. Suction-side noise levels: L_{wA} measured as per ISO 13347 / L_{pA} measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

Measured values

	U	f	n	P _{ed}	I	L _{pA_{in}}	L _{wA_{in}}	L _{wA_{out}}	qv	p _{fs}
	V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m³/h	Pa
1	400	50	2020	1284	1.98	86	93	98	8415	0
2	400	50	2020	2059	3.14	80	87	94	7050	500
3	400	50	2020	2420	3.70	78	85	90	4840	1000
4	400	50	2020	2144	3.24	81	88	92	3000	1200
5	400	50	1700	752	1.16	82	89	94	7040	0
6	400	50	1700	1211	1.85	76	83	90	5905	353
7	400	50	1700	1423	2.16	74	81	87	4055	703
8	400	50	1700	1255	1.90	77	84	88	2510	839
9	400	50	1400	420	0.65	78	85	90	5800	0
10	400	50	1400	676	1.03	72	79	86	4865	240
11	400	50	1400	795	1.20	70	76	82	3340	477
12	400	50	1400	701	1.06	73	80	84	2065	569
13	400	50	1100	204	0.31	72	80	85	4555	0
14	400	50	1100	328	0.50	67	74	81	3820	148
15	400	50	1100	386	0.58	64	71	77	2625	294
16	400	50	1100	340	0.51	67	75	79	1625	351

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Power input · I = Current draw · L_{pA_{in}} = Sound pressure level inlet side · L_{wA_{in}} = Sound power level inlet side · L_{wA_{out}} = Sound power level outlet side

qv = Air flow · p_{fs} = Pressure increase