



R3G400-AQ29-16 ebmpapst Datasheet

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Nominal data

Type	R3G400-AQ29-16	
Motor	M3G150-FF	
Phase		3~
Nominal voltage	VAC	208
Nominal voltage range	VAC	200 .. 240
Frequency	Hz	50/60
Method of obtaining data		cs
Speed (rpm)	min ⁻¹	2550
Power consumption	W	3000
Current draw	A	8.8
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	50

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to Commission Regulation (EU) 327/2011 (EN 17166)

		Actual	Req. 2015			
01 Overall efficiency η_{es}	%	62.5	56.7	09 Power consumption P_{ed}	kW	3.1
02 Measurement category		A		09 Air flow q_v	m ³ /h	5520
03 Efficiency category		Static		09 Pressure increase p_{fs}	Pa	1194
04 Efficiency grade N		67.8	62	10 Speed (rpm) n	min ⁻¹	2550
05 Variable speed drive		Yes		11 Specific ratio*		1.01

Data obtained at optimum efficiency level.

The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

* Specific ratio = $1 + p_{fs} / 100\,000\text{ Pa}$

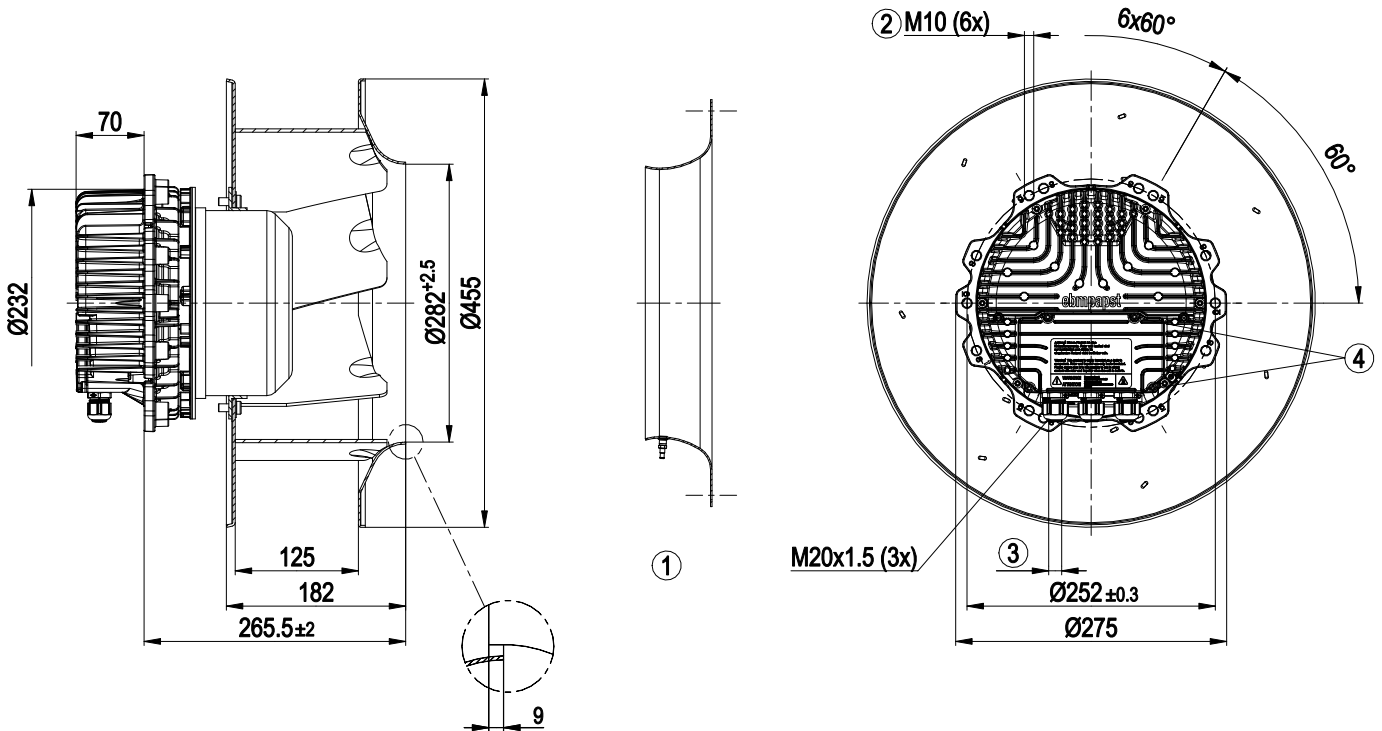
LU-125165



Technical description

Weight	21.6 kg
Size	400 mm
Motor size	150
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum
Impeller material	Sheet aluminum
Number of blades	7
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	"F"
Moisture (F) / Environmental (H) protection class	H1
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	<ul style="list-style-type: none"> - Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - External 24 V input (parameter setting) - External release input - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC interference emission	According to EN 61000-6-4 (industrial environment)
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approval	CSA C22.2 No. 77 + CAN/CSA-E60730-1; UL 1004-7 + 60730-1

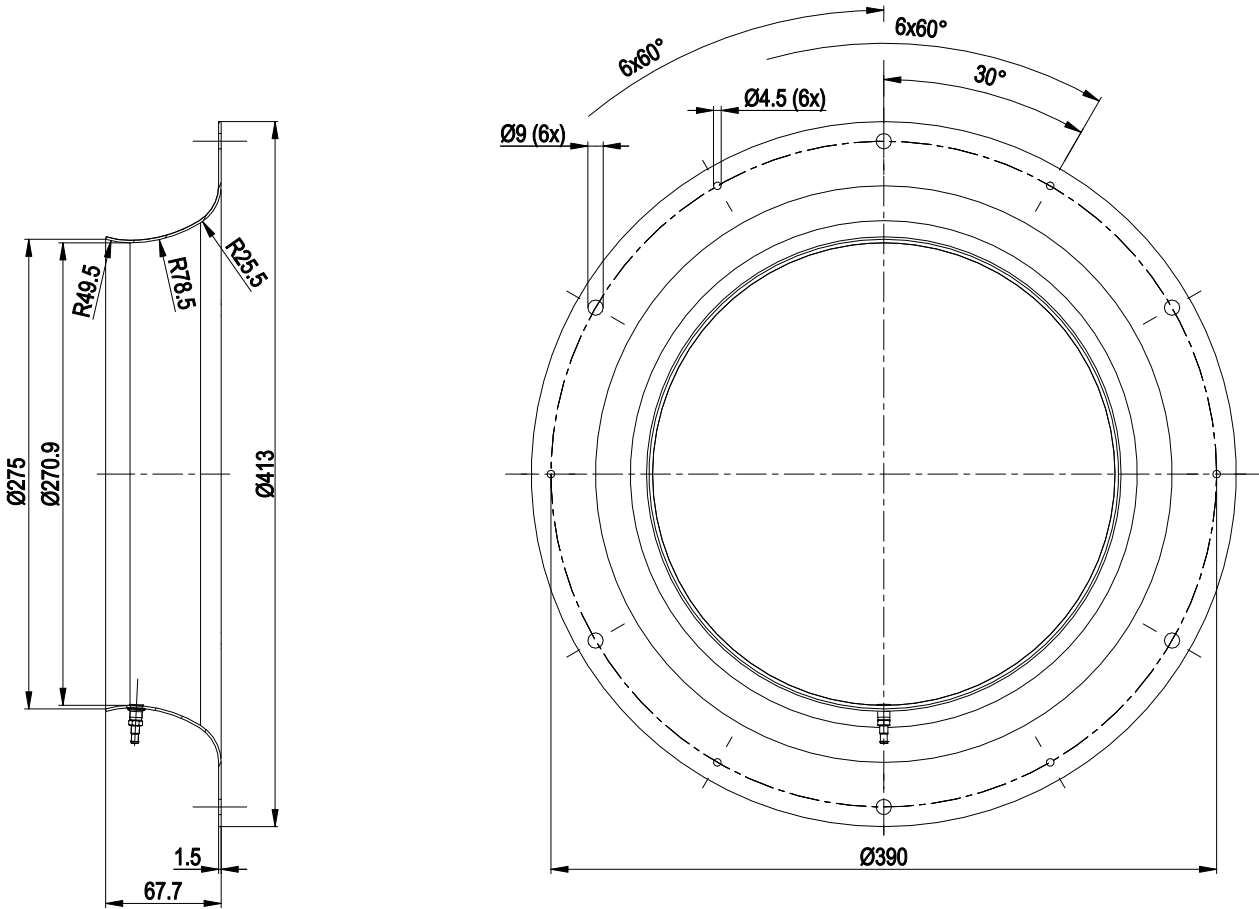
Product drawing



1	Accessory part: Inlet ring 40075-2-4013 with pressure tap (k-factor: 188) not included in scope of delivery
2	Max. clearance for screw 25 mm
3	Cable diameter min. 4 mm, max. 10 mm, tightening torque 4 ± 0.6 Nm
4	Tightening torque 3.5 ± 0.5 Nm



Accessory part



1 Inlet ring with pressure tap 40075-2-4013 (k-factor: 188) not included in scope of delivery



Connection diagram

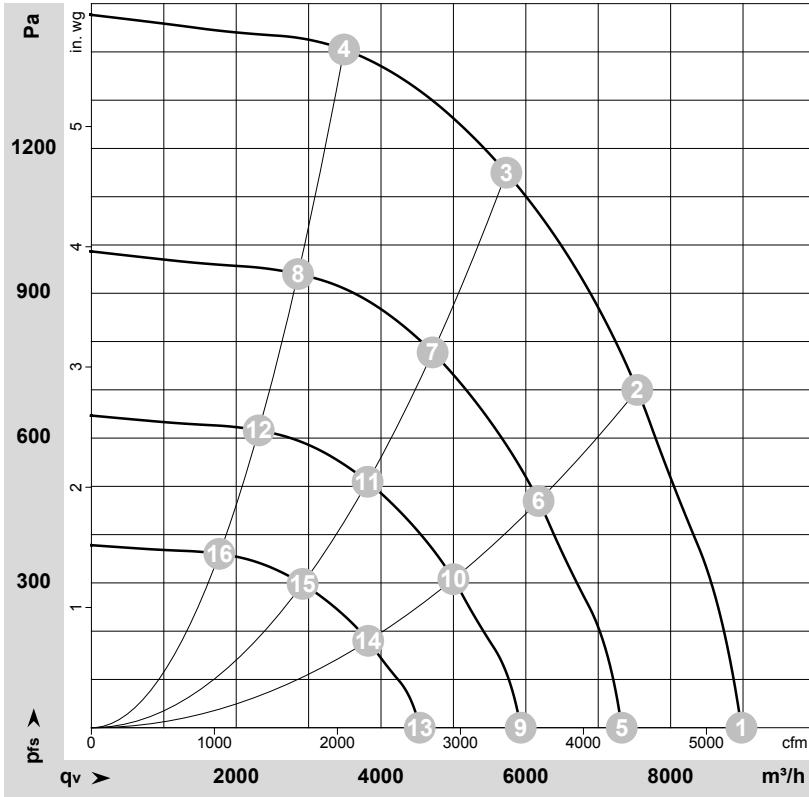


No.	Conn.	Designation	Function/assignment
KL 1	1	L1	Supply connection, power supply 3-phase 200-240 VAC, 50/60 Hz
KL 1	2	L2	Supply connection, power supply 3-phase 200-240 VAC, 50/60 Hz
KL 1	3	L3	Supply connection, power supply 3-phase 200-240 VAC, 50/60 Hz
PE		PE	Ground connection, PE connection
KL 2	1	NO	Status relay, floating status contact, make for failure
KL2	2	COM	Status relay, floating status contact; changeover contact; common connection; contact rating 250 VAC / max. 2 A (AC1) / min. 10 mA
KL2	3	NC	Status relay, floating status contact, break for failure
KL 3	1	RSA	Bus connection RS485, RSA, MODBUS-RTU; SELV
KL 3	2	RSB	Bus connection RS485, RSB, MODBUS-RTU; SELV
KL 3	3 / 10	GND	Reference ground for control interface; SELV
KL 3	4	Ain1 U	Analog input 1, set value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain1I; SELV
KL 3	5	+ 10 V	Fixed voltage output 10 VDC, +10 V ±3%, max. 10 mA, short-circuit-proof power supply for external devices (e.g. pot); SELV
KL 3	6	Ain1 I	Analog input 1, set value: 4-20 mA, Ri = 100 Ω, adjustable curve, only usable as alternative to input Ain1U; SELV
KL 3	7	Din1	Digital input 1: enable electronics, enable: pin open or applied voltage 5-50 VDC disable: bridge to GND or applied voltage < 1 VDC reset function: triggers software reset after a level change to < 1 VDC; SELV
KL 3	8	Din2	Digital input 2: Switching parameter sets 1/2, according to EEPROM setting, the valid or used parameter set can be selected via bus or via digital input DIN2. Parameter set 1: pin open or applied voltage 5-50 VDC Parameter set 2: bridge to GND or applied voltage < 1 VDC; SELV
KL 3	9	Din3	Digital input 3: according to EEPROM setting, the integrated controller's direction of action can be selected as normal/inverse via bus or digital input normal: pin open or applied voltage 5-50 VDC inverse: bridge to GND or applied voltage < 1 VDC; SELV
KL 3	11	Ain2 U	Analog input 2, measured value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain2I; SELV
KL 3	12	+ 20 V	Fixed voltage output 20 VDC, +20 V ±5/-10%, max. 50 mA, short-circuit-proof power supply for external devices (e.g. sensors); SELV

No.	Conn.	Designation	Function/assignment
KL 3	13	Ain2 I	Analog input 2, measured value: 4-20 mA, Ri = 100 Ω , adjustable curve, only usable as alternative to input Ain2U; SELV
KL 3	14	Aout	Analog output 0-10 VDC, max. 5 mA, output of current motor modulation level / motor speed adjustable curve; SELV



Curves: Air performance 50 Hz



$\rho = 1.178 \text{ kg/m}^3 \pm 2 \%$

Measurement: LU-125165-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebmpapst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	Wired	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	LwA _{out}	q _v	p _{fs}	q _v	p _{fs}
		V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m ³ /h	Pa	cfm	in. wg
1	3~	200	50	2575	2139	6.52	86	93	98	8980	0	5285	0.00
2	3~	200	50	2565	2837	8.76	79	87	94	7540	700	4435	2.81
3	3~	200	50	2550	3100	9.70	79	86	93	5730	1150	3375	4.62
4	3~	200	50	2570	2832	8.71	81	89	96	3490	1400	2055	5.62
5	3~	200	50	2100	1161	3.54	81	88	93	7325	0	4310	0.00
6	3~	200	50	2100	1560	4.82	74	82	89	6175	473	3635	1.90
7	3~	200	50	2100	1729	5.35	74	81	88	4715	780	2775	3.13
8	3~	200	50	2100	1549	4.76	76	84	91	2855	941	1680	3.78
9	3~	200	50	1700	616	1.88	76	82	87	5930	0	3490	0.00
10	3~	200	50	1700	828	2.55	69	77	84	5000	310	2945	1.24
11	3~	200	50	1700	917	2.84	68	76	83	3815	511	2245	2.05
12	3~	200	50	1700	822	2.53	71	79	86	2310	617	1360	2.48
13	3~	200	50	1300	276	0.84	69	76	81	4535	0	2670	0.00
14	3~	200	50	1300	370	1.14	62	70	77	3825	181	2250	0.73
15	3~	200	50	1300	410	1.27	62	69	76	2915	299	1715	1.20
16	3~	200	50	1300	367	1.13	64	72	79	1765	361	1040	1.45

Wired = Wiring · U = Voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side · LwA_{out} = Sound power level outlet side · q_v = Air flow · p_{fs} = Pressure increase

