R3G400-AQ12-03

EC centrifugal fan - Plug fan

backward-curved, single-intake

R3G400-AQ12-03 ebmpapst Datasheet
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ErP2015 EXCEEDS THE NORM

Nominal data

Type	**R3G400-AQ12-03**	
Motor	**M3G150-FF**	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Method of obtaining data		ml
Speed	min^{-1}	2500
Power consumption	W	2950
Current draw	A	4.6
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	40

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to ErP Directive

		Actual	Req. 2015
01 Overall efficiency η_{es}	%	64.4	56.4
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		70	62
05 Variable speed drive		Yes	

09 Power consumption P_{ed}	kW	2.95
09 Air flow q_v	m^3/h	6255
09 Pressure increase p_{fs}	Pa	1037
10 Speed n	min^{-1}	2515
11 Specific ratio*		1.01

Data obtained at optimum efficiency level.
The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

* Specific ratio = 1 + p_{fs} / 100 000 Pa

LU-106278

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Technical description

Weight	21.3 kg
Fan size	400 mm
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum
Impeller material	Sheet aluminum, welded
Number of blades	7
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP54
Insulation class	"F"
Moisture (F) / Environmental (H) protection class	F4-1
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal or rotor on bottom
Condensation drainage holes	On rotor side
Mode	S1
Motor storage	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - RS-485 ebmBUS - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from supply - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC interference emission	According to EN 61000-6-4 (industrial environment)
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Via terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (with customer connection of protective earth)
Conformity with standards	CE
Approval	CSA C22.2 No. 77; EAC; UL 2111; VDE

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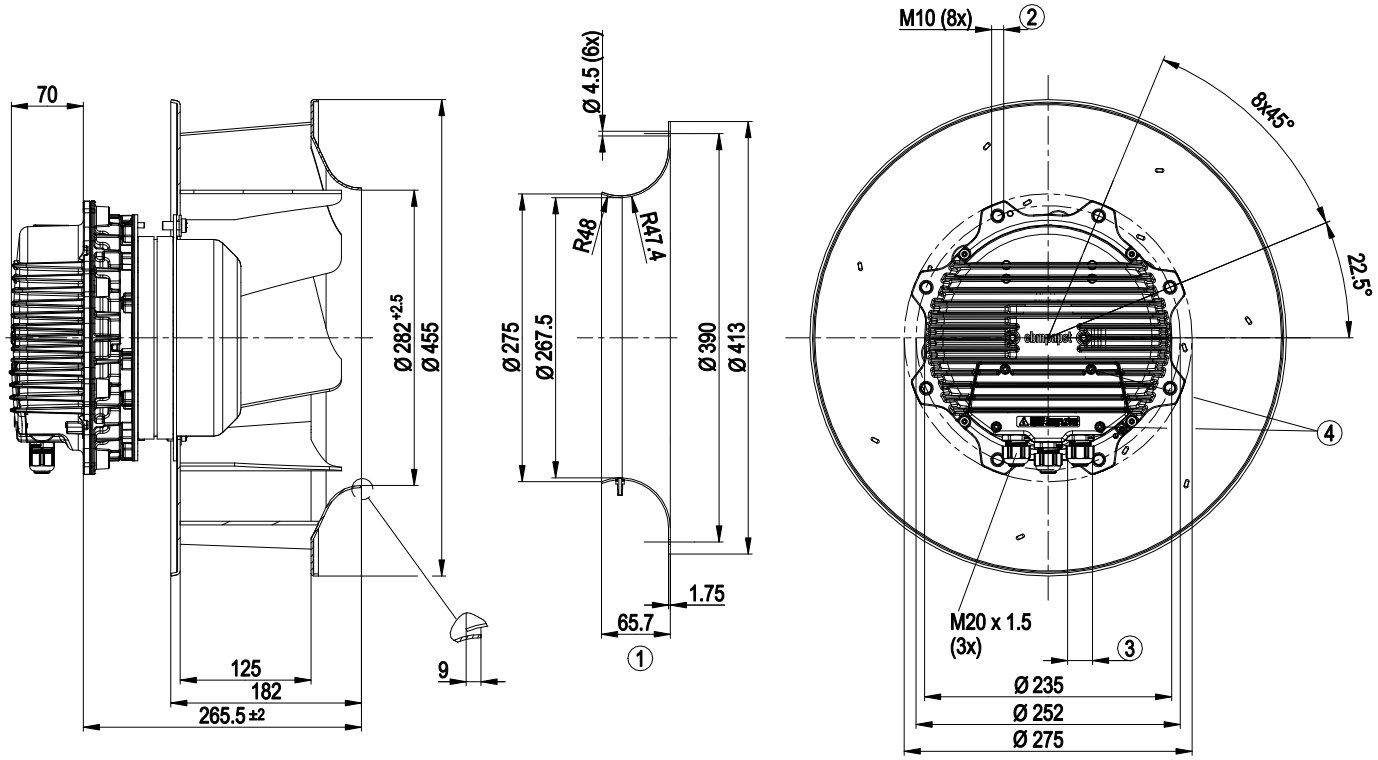
Product drawing



1	Accessory part: Inlet ring 40041-2-4013 not included in scope of delivery
2	Max. clearance for screw 25 mm
3	Cable diameter min. 4 mm, max. 10 mm; tightening torque 4±0.4 Nm
4	Tightening torque 2.5±0.4 Nm

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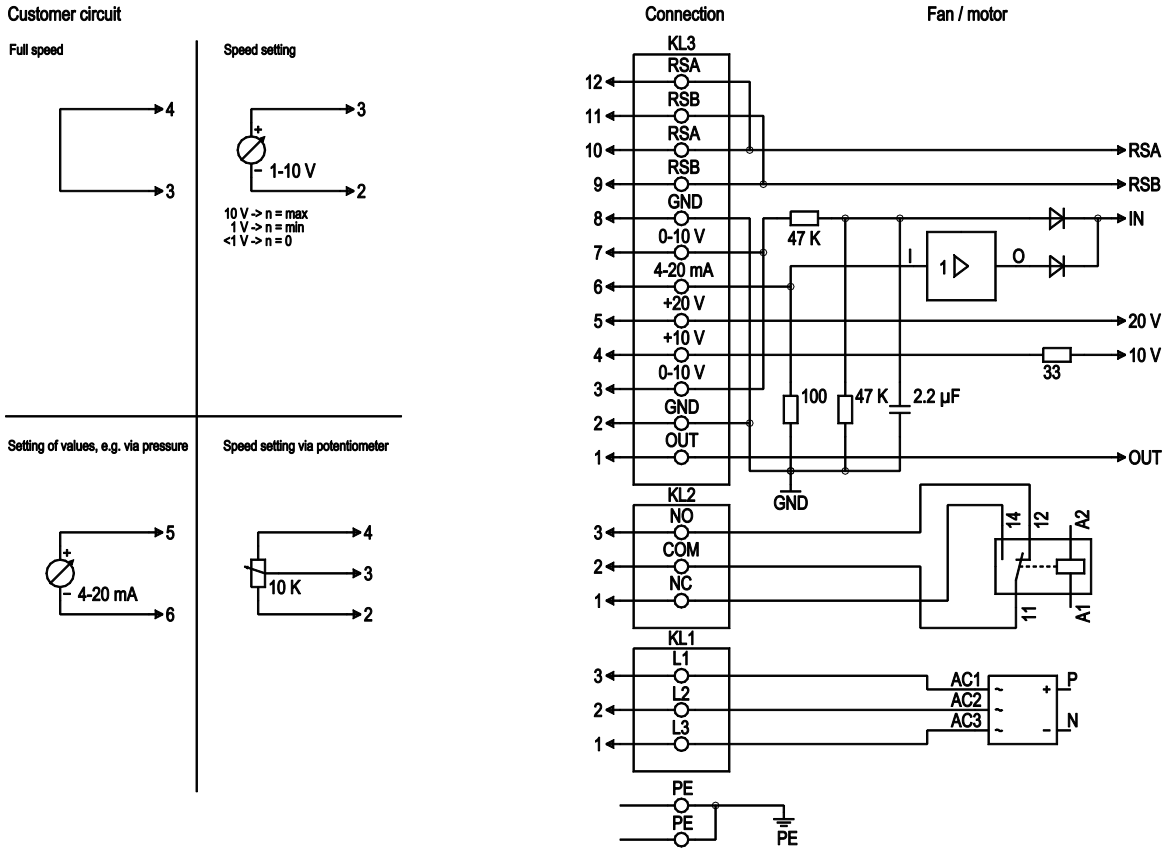
Connection diagram



No.	Conn.	Designation	Function/assignment
PE		PE	Protective earth terminal
KL1	1, 2, 3	L1, L2, L3	Power supply 50/60 Hz
KL2	1	NC	Floating status contact, break for failure
KL2	2	COM	floating status contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status contact, make for failure
KL3	1	OUT	Analog output, 0-10 VDC, max. 3 mA, SELV, output of current motor modulation level: 1 V corresponds to 10 % modulation level. 10 V corresponds to 100 % modulation level.
KL3	2, 8	GND	Reference ground for control interface, SELV
KL3	3, 7	0-10 V	Use control / current sensor value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (±3 %), max. 10 mA, power supply for external devices (e.g. potentiometer), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25% / -10%), max. 50 mA, power supply for external devices (e.g. sensors); SELV
KL3	6	4-20 mA	Use control / current sensor value input 4-20 mA, impedance 100 Ω only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for ebmBUS, RSB, SELV
KL3	10, 12	RSA	RS485 interface for ebmBUS, RSA, SELV

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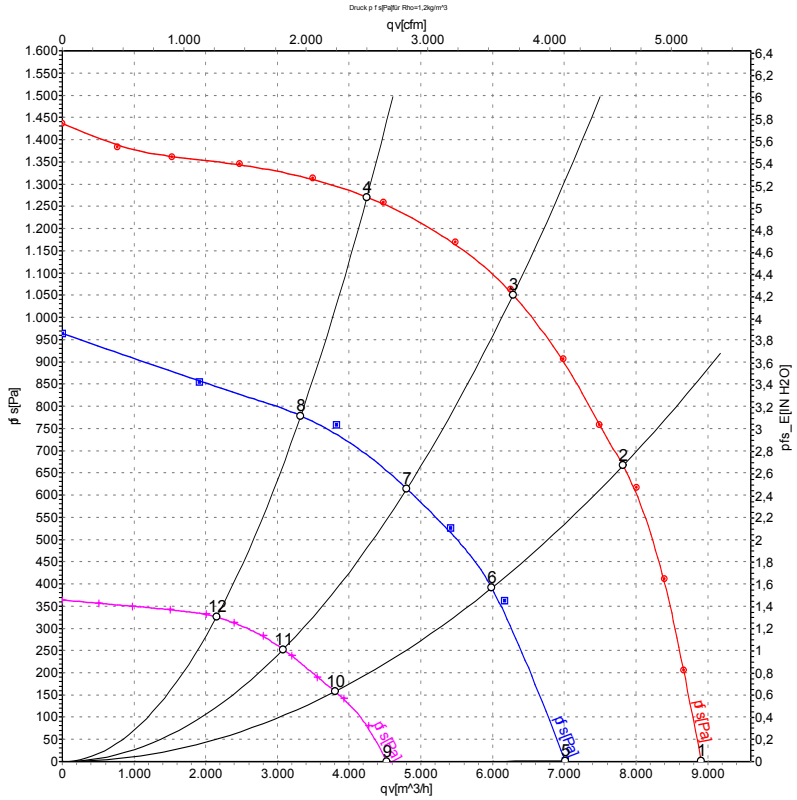
Curves: Air performance 50 Hz



Measurement: LU-106278
Measurement: LU-108550
Measurement: LU-106283

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	qv	p_{fs}
	V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa
1	400	50	2500	2009	3.07	90	96	101	8910	0
2	400	50	2500	2738	4.19	83	89	95	7815	668
3	400	50	2500	2950	4.60	78	85	93	6285	1057
4	400	50	2500	2748	4.20	79	87	95	4250	1272
5	400	50	1945	945	1.48	82	89	93	7015	0
6	400	50	1920	1170	1.80	74	81	86	5990	401
7	400	50	1915	1247	1.91	72	78	84	4800	614
8	400	50	1920	1193	1.84	72	78	85	3325	783
9	400	50	1255	308	0.59	71	77	82	4520	0
10	400	50	1260	416	0.76	65	72	76	3805	158
11	400	50	1255	417	0.77	61	68	73	3080	252
12	400	50	1255	410	0.75	60	67	73	2150	325

U = Power supply · f = Frequency · n = Speed · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
LwA_{out} = Sound power level outlet side · qv = Air flow · p_{fs} = Pressure increase