

EC centrifugal fan

backward curved, single inlet

R3G400-AK57-16 ebmpapst Datasheet

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Nominal data

| | | |
|--------------------------|-------------------|------------|
| Type | R3G400-AK57-16 | |
| Motor | M3G112-EA | |
| Phase | | 3~ |
| Nominal voltage | VAC | 200 |
| Nominal voltage range | VAC | 200 .. 240 |
| Frequency | Hz | 50/60 |
| Type of data definition | | ml |
| Speed | min ⁻¹ | 1880 |
| Power input | W | 1000 |
| Current draw | A | 2.9 |
| Min. ambient temperature | °C | -25 |
| Max. ambient temperature | °C | 60 |

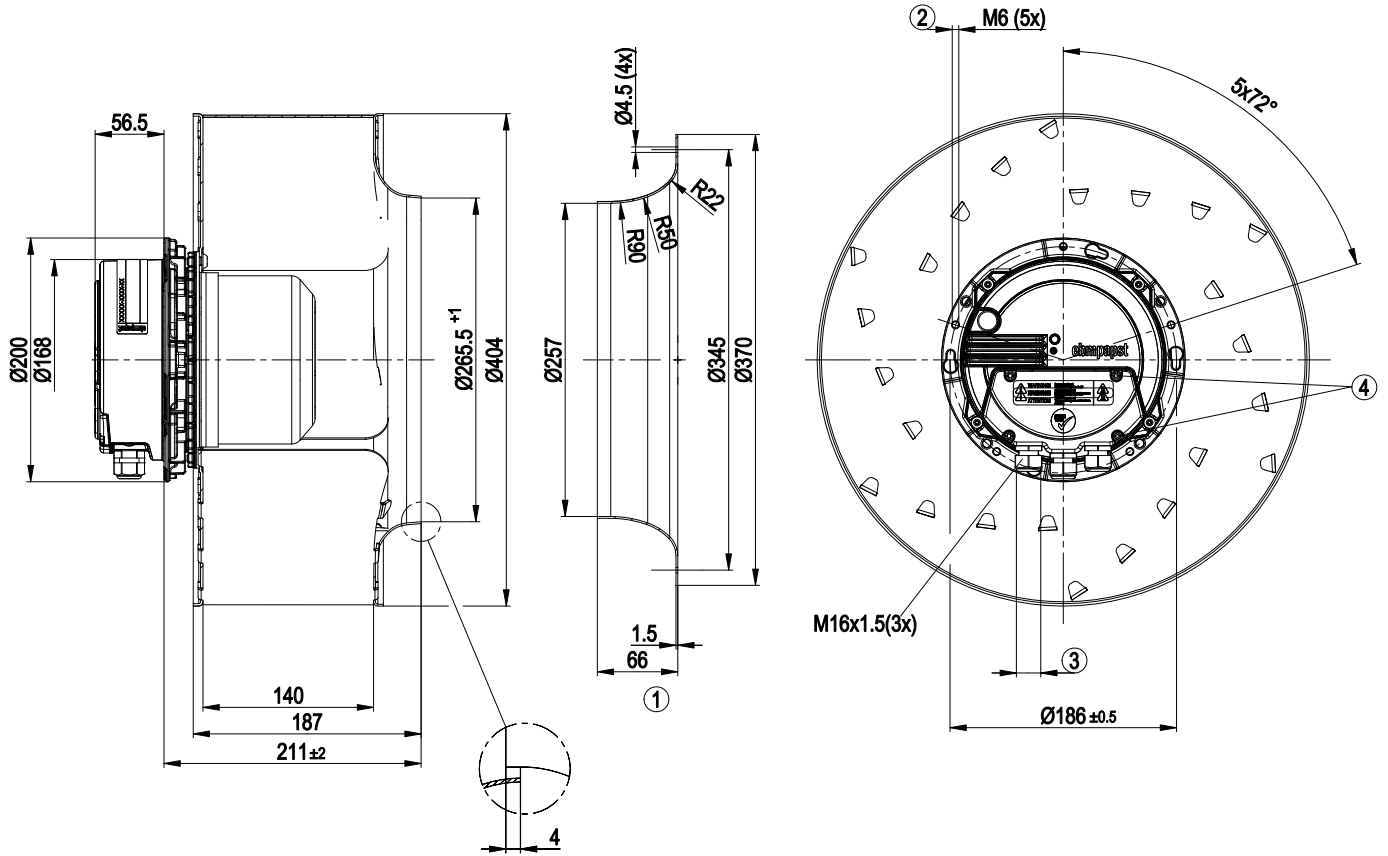
ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations



Technical features

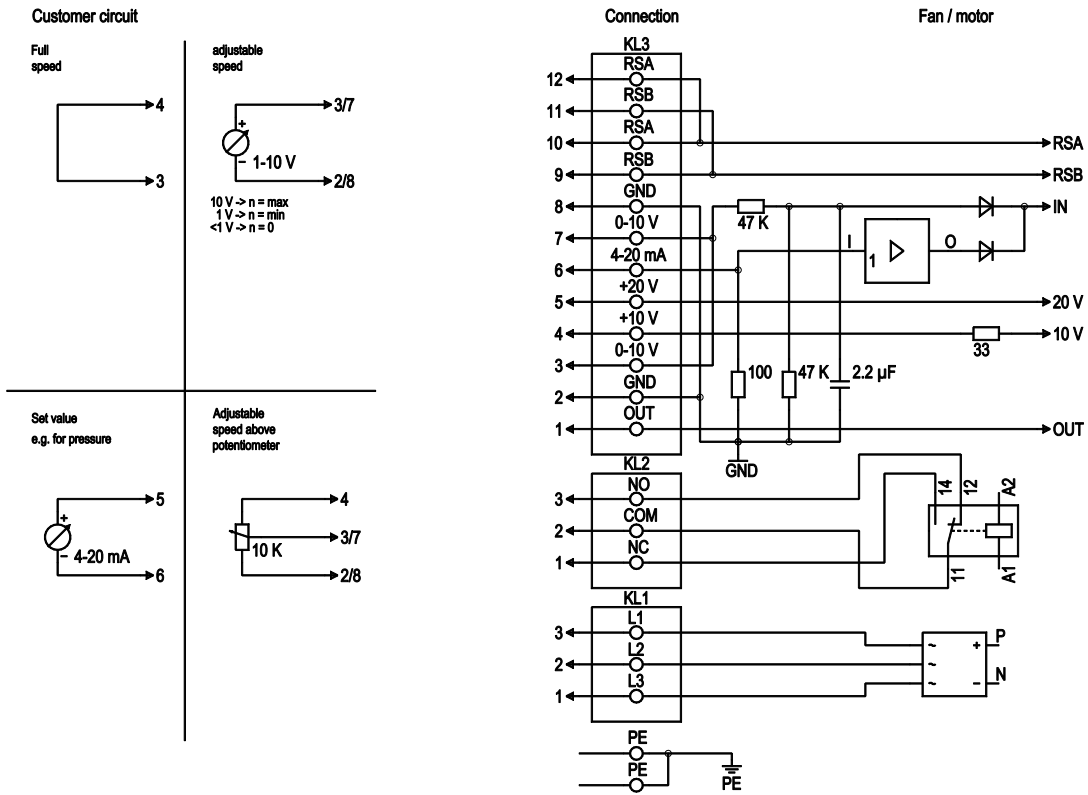
| | |
|--|---|
| Mass | 9 kg |
| Size | 400 mm |
| Surface of rotor | Coated in black |
| Material of electronics housing | Die-cast aluminium |
| Material of impeller | Aluminium sheet |
| Number of blades | 6 |
| Direction of rotation | Clockwise, seen on rotor |
| Type of protection | IP 54 |
| Insulation class | "B" |
| Humidity class | F4-1 |
| Max. permissible ambient motor temp. (transp./ storage) | + 80 °C |
| Min. permissible ambient motor temp. (transp./storage) | - 40 °C |
| Mounting position | Any |
| Condensate discharge holes | On rotor and stator sides |
| Operation mode | S1 |
| Motor bearing | Ball bearing |
| Technical features | <ul style="list-style-type: none"> - Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Operation and alarm display - Input for sensor 0-10 V or 4-20 mA - External 24 V input (programming) - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive - RS485 MODBUS RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection |
| EMC interference immunity | Acc. to EN 61000-6-2 (industrial environment) |
| EMC harmonics | Acc. to EN 61000-3-2/3 |
| EMC interference emission | Acc. to EN 61000-6-4 (industrial environment) |
| Touch current acc. IEC 60990 (measuring network Fig. 4, TN system) | <= 3.5 mA |
| Electrical leads | Via terminal box |
| Motor protection | Thermal overload protector (TOP) wired internally |
| Protection class | I (if protective earth is connected by customer) |
| Product conforming to standard | EN 61800-5-1; CE |
| Approval | UL 1004-7 + 60730 |

Product drawing



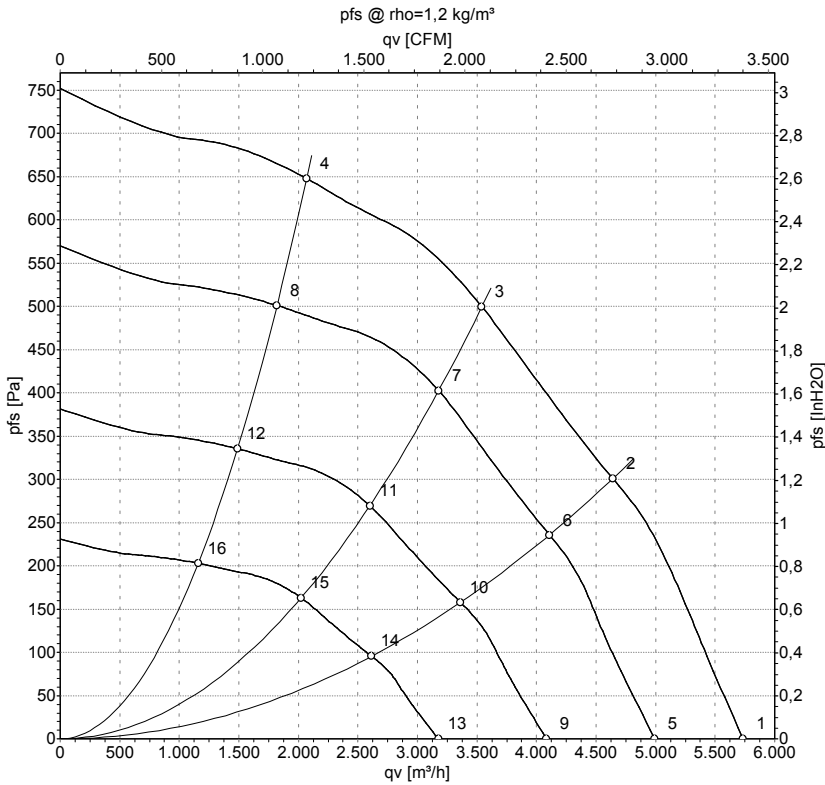
| | |
|---|---|
| 1 | Accessory part: inlet nozzle 54476-2-4013 not included in scope of delivery |
| 2 | Depth of screw max. 16 mm |
| 3 | Cable diameter min. 4 mm, max. 10 mm; tightening torque 2.5 ± 0.4 Nm |
| 4 | Tightening torque 3.5 ± 0.5 Nm |

Connection screen



| No. | Conn. | Designation | Function / assignment |
|-----|---------|-------------|---|
| PE | | PE | Protective earth connection |
| KL1 | 1, 2, 3 | L1, L2, L3 | Supply voltage, voltage range (see type plate), 50/60 Hz |
| KL2 | 1 | NC | Floating status contact, break with error |
| KL2 | 2 | COM | Floating status contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1) |
| KL2 | 3 | NO | Floating status contact, close with error |
| KL3 | 1 | OUT | Analogue output, 0-10 VDC, max. 3 mA, SELV, Output of the actual motor duty cycle (PWM): 1 V corresponds to 10% PWM, 10 V correspond to 100% PWM. |
| KL3 | 2, 8 | GND | Signal ground for control interface, SELV |
| KL3 | 3, 7 | 0-10 V | Set value / actual sensor value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV |
| KL3 | 4 | +10 V | Voltage output 10 VDC (+/-3%), max. 10 mA, power supply for external devices (e.g. potentiometer), SELV |
| KL3 | 5 | +20 V | Voltage output 20 VDC (+25%/-10%), max. 50 mA, supply voltage for external devices (e.g. sensors), SELV |
| KL3 | 6 | 4-20 mA | Set value / actual sensor value input 4-20 mA, impedance 100 Ω, only as alternative to 0-10 V input, SELV |
| KL3 | 9, 11 | RSB | RS485 interface for MODBUS, RSB |
| KL3 | 10, 12 | RSA | RS485 interface for MODBUS, RSA |

Charts: Air flow 50 Hz



Measurement: LU-107848

Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebm-papst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

Measured values

| | U | f | n | P _{ed} | I | LpA _{in} | LwA _{in} | LwA _{out} | qv | p _{fs} |
|----|-----|----|-------------------|-----------------|------|-------------------|-------------------|--------------------|-------------------|-----------------|
| | V | Hz | min ⁻¹ | W | A | dB(A) | dB(A) | dB(A) | m ³ /h | Pa |
| 1 | 200 | 50 | 1880 | 749 | 2.33 | 76 | 82 | 88 | 5735 | 0 |
| 2 | 200 | 50 | 1880 | 855 | 2.68 | 73 | 80 | 85 | 4640 | 300 |
| 3 | 200 | 50 | 1880 | 1000 | 2.90 | 70 | 77 | 82 | 3540 | 500 |
| 4 | 200 | 50 | 1880 | 847 | 2.68 | 74 | 81 | 86 | 2070 | 650 |
| 5 | 200 | 50 | 1650 | 493 | 1.54 | 72 | 79 | 84 | 4990 | 0 |
| 6 | 200 | 50 | 1650 | 593 | 1.86 | 70 | 76 | 82 | 4110 | 236 |
| 7 | 200 | 50 | 1650 | 665 | 2.09 | 68 | 74 | 80 | 3180 | 406 |
| 8 | 200 | 50 | 1650 | 576 | 1.83 | 71 | 78 | 82 | 1820 | 502 |
| 9 | 200 | 50 | 1350 | 270 | 0.84 | 67 | 74 | 79 | 4085 | 0 |
| 10 | 200 | 50 | 1350 | 325 | 1.02 | 65 | 71 | 77 | 3360 | 158 |
| 11 | 200 | 50 | 1350 | 364 | 1.14 | 63 | 69 | 75 | 2600 | 272 |
| 12 | 200 | 50 | 1350 | 316 | 1.00 | 66 | 73 | 77 | 1490 | 336 |
| 13 | 200 | 50 | 1050 | 127 | 0.40 | 61 | 67 | 73 | 3175 | 0 |
| 14 | 200 | 50 | 1050 | 153 | 0.48 | 58 | 65 | 71 | 2615 | 95 |
| 15 | 200 | 50 | 1050 | 171 | 0.54 | 56 | 63 | 68 | 2020 | 164 |
| 16 | 200 | 50 | 1050 | 149 | 0.47 | 59 | 66 | 71 | 1160 | 203 |

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Power input · I = Current draw · LpA_{in} = Sound pressure level inlet side · LwA_{in} = Sound power level inlet side · LwA_{out} = Sound power level outlet side
 qv = Air flow · p_{fs} = Pressure increase

