

R3G355-RG71-21 ebmpapst Datasheet

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Nominal data

Type	R3G355-RG71-21	
Motor	M3G112-EA	
Phase		1~
Nominal voltage	VAC	230
Nominal voltage range	VAC	200 .. 277
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min ⁻¹	1955
Power consumption	W	640
Current draw	A	2.8
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	50

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to Commission Regulation (EU) 327/2011

		Actual	Req. 2015
01 Overall efficiency η_{es}	%	64.2	49.5
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		76.7	62
05 Variable speed drive		Yes	

Data obtained at optimum efficiency level.

The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

09 Power consumption P_{ed}	kW	0.64
09 Air flow q_v	m ³ /h	2805
09 Pressure increase p_{fs}	Pa	484
10 Speed (rpm) n	min ⁻¹	1965
11 Specific ratio*		1.01

* Specific ratio = $1 + p_{fs} / 100\,000\text{ Pa}$

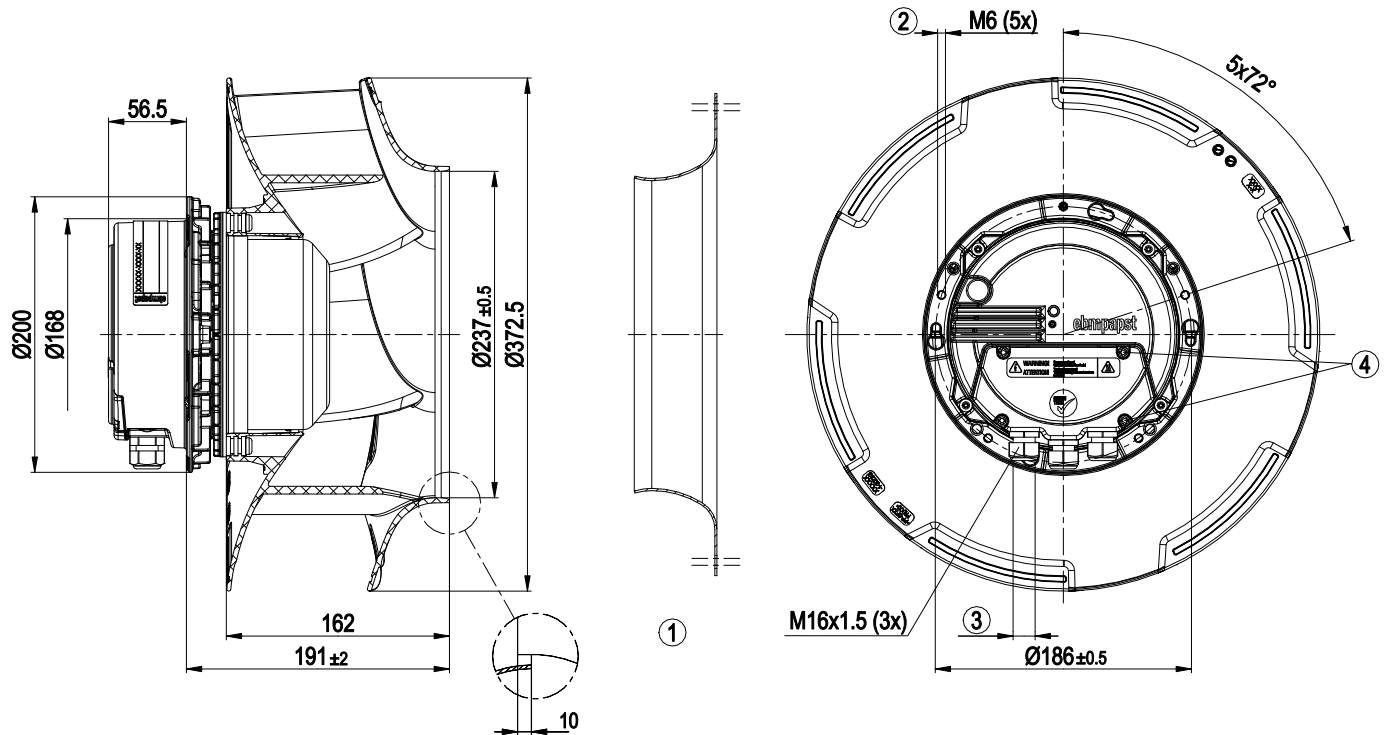
LU-183867



Technical description

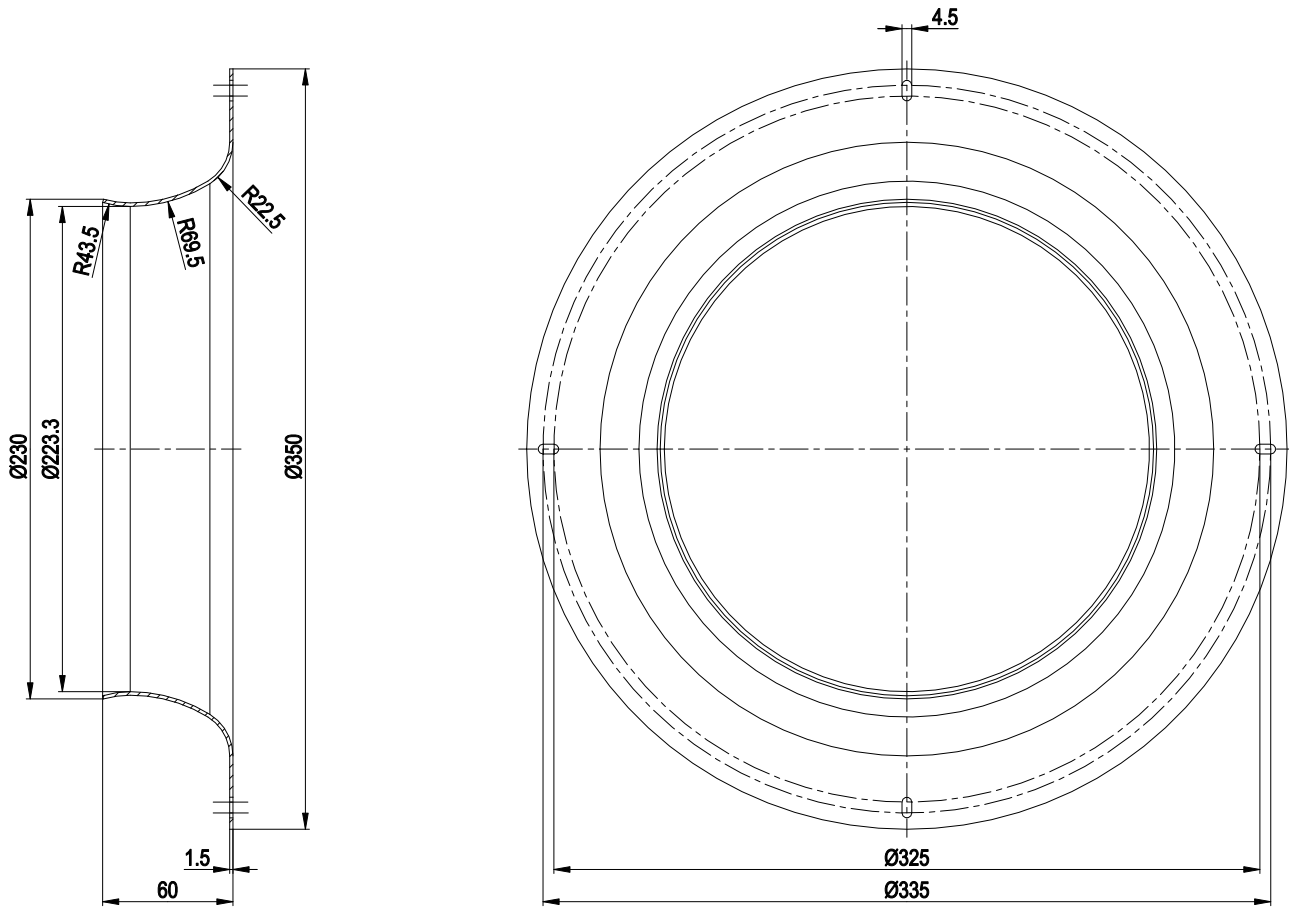
Weight	8.2 kg
Fan size	355 mm
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum
Impeller material	PP plastic
Number of blades	6
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP54
Insulation class	"B"
Moisture (F) / Environmental (H) protection class	F4-1
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Operation and alarm display - Selection of direction of rotation left/right - Input for sensor 0-10 V or 4-20 mA - External 24 V input (parameter setting) - Alarm relay - Integrated PID controller - Motor current limitation - PFC, active - RS-485 MODBUS-RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from supply - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC circuit feedback	According to EN 61000-3-2/3
EMC interference emission	According to EN 55022 (Class A, industrial environment)
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Via terminal box
Motor protection	Thermal overload protector (TOP) internally connected
With cable	Variable
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approval	EAC; CCC

Product drawing



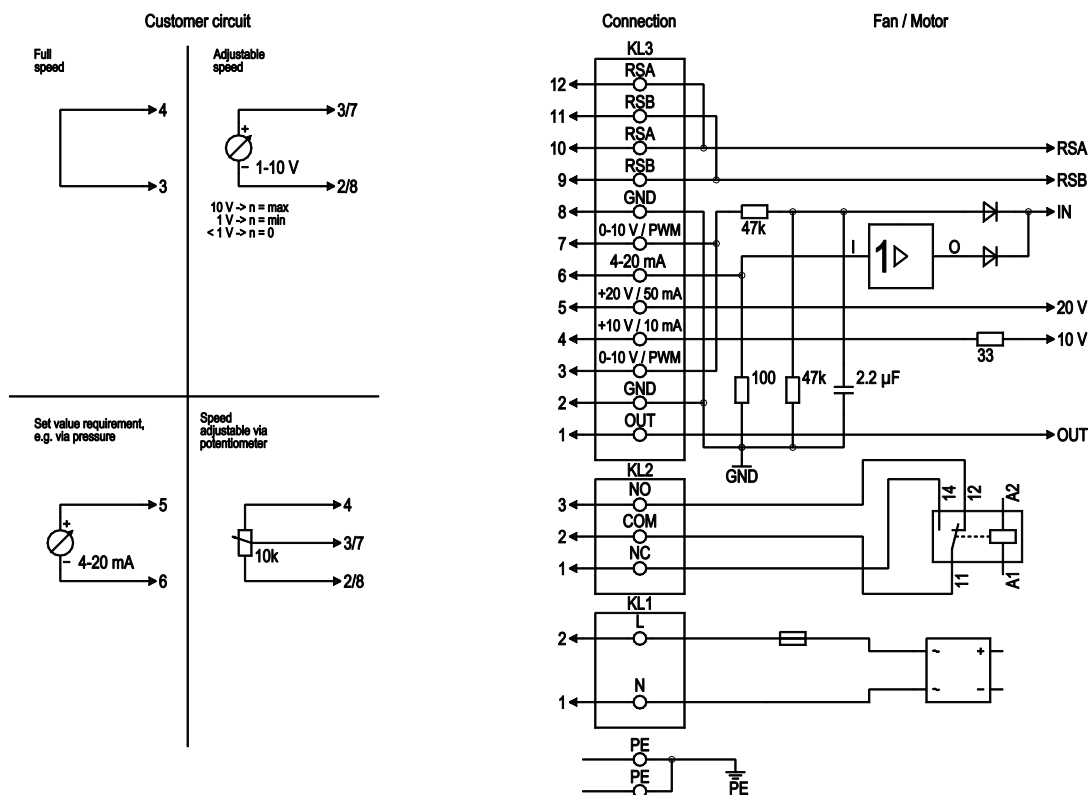
1	Accessory part: Inlet ring 35500-2-4013 not included in scope of delivery
2	Max. clearance for screw 16 mm
3	Cable diameter min. 4 mm, max. 10 mm; tightening torque 4 ± 0.6 Nm
4	Tightening torque 3.5 ± 0.5 Nm

Accessory part



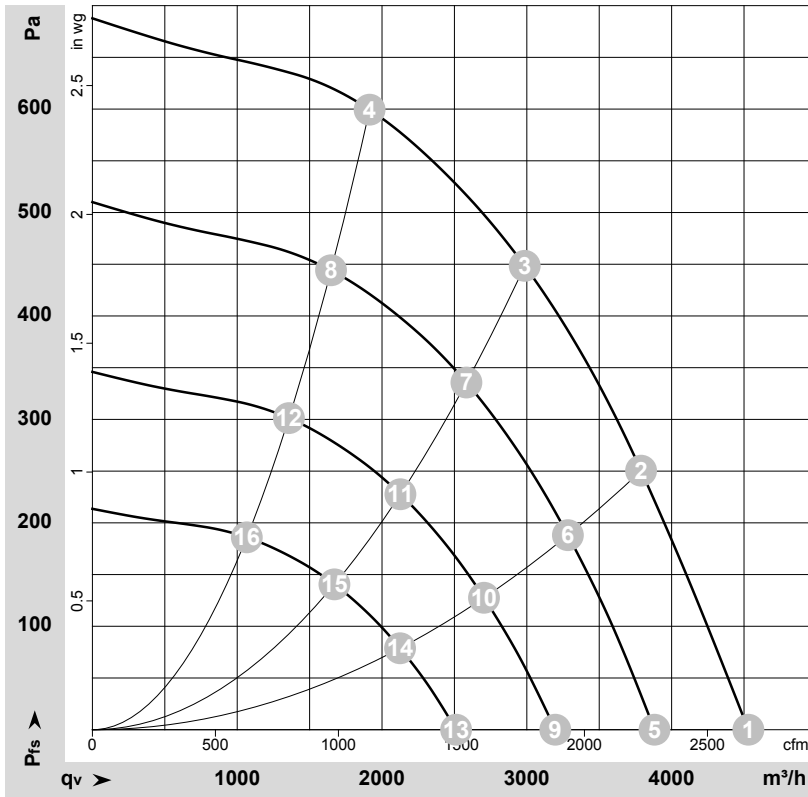
Inlet ring 35500-2-4013 not included in scope of delivery

Connection diagram



No.	Conn.	Designation	Function/assignment
PE	-	PE	Protective earth terminal
KL1	1, 2	N, L	Power supply 50/60 Hz
KL2	1	NC	Floating status contact, break for failure
KL2	2	COM	Floating status contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status contact, make for failure
KL3	1	OUT	Analog output, 0-10 VDC, max. 3 mA, SELV output of current motor modulation level: 1 V corresponds to 10% modulation level. 10 V corresponds to 100% modulation level.
KL3	2, 8	GND	Reference ground for control interface, SELV
KL3	3, 7	0-10 V	Control/current sensor value input 0-10 VDC, impedance 100 kΩ, use only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (+/- 3%), max. 10 mA, power supply for ext. devices (e.g. potentiometer), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25%/-10%), max. 50 mA power supply for ext. devices (e.g. sensors), SELV
KL3	6	4-20 mA	Control/current sensor value input 4-20 mA, impedance 100 Ω, use only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for MODBUS, RSB
KL3	10, 12	RSA	RS485 interface for MODBUS, RSA

Curves: Air performance 50 Hz



$$\rho = 1.15 \text{ kg/m}^3 \pm 2 \%$$

Measurement: LU-183867-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	q _v	p _{fs}	q _v	p _{fs}
	V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	m³/h	Pa	cfm	inH ₂ O
1	230	50	1955	455	1.99	74	81	4530	0	2665	0.00
2	230	50	1955	575	2.51	69	76	3790	250	2230	1.00
3	230	50	1955	640	2.80	65	72	2985	450	1755	1.81
4	230	50	1955	612	2.67	66	73	1915	600	1125	2.41
5	230	50	1700	286	1.25	70	77	3880	0	2285	0.00
6	230	50	1700	374	1.63	65	72	3285	188	1935	0.75
7	230	50	1700	414	1.81	62	68	2585	336	1520	1.35
8	230	50	1700	391	1.71	62	69	1650	445	970	1.79
9	230	50	1400	160	0.70	65	73	3195	0	1880	0.00
10	230	50	1400	209	0.91	60	67	2705	128	1590	0.51
11	230	50	1400	231	1.01	57	63	2125	228	1250	0.92
12	230	50	1400	218	0.95	57	64	1355	302	800	1.21
13	230	50	1100	77	0.34	59	66	2510	0	1480	0.00
14	230	50	1100	101	0.44	54	61	2125	79	1250	0.32
15	230	50	1100	112	0.49	51	57	1670	141	985	0.57
16	230	50	1100	106	0.46	51	58	1065	186	625	0.75

U = Power supply · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
q_v = Air flow · p_{fs} = Pressure increase

