

R3G355-RG52-25 ebmpapst Datasheet

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## Nominal data

Type	R3G355-RG52-25	
Motor	M3G112-EA	
Phase		1~
Nominal voltage	VAC	230
Nominal voltage range	VAC	200 .. 277
Frequency	Hz	50/60
Method of obtaining data		ml
Status		prelim.
Speed (rpm)	min <sup>-1</sup>	2100
Power consumption	W	750
Current draw	A	3.3
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	50

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment  
Subject to change

## Data according to Commission Regulation (EU) 327/2011

		Actual	Req. 2015			
01 Overall efficiency $\eta_{es}$	%	64.6	50.4	09 Power consumption $P_{ed}$	kW	0.77
02 Measurement category		A		09 Air flow $q_v$	m <sup>3</sup> /h	3205
03 Efficiency category		Static		09 Pressure increase $p_{fs}$	Pa	517
04 Efficiency grade N		76.3	62	10 Speed (rpm) n	min <sup>-1</sup>	2110
05 Variable speed drive		Yes		11 Specific ratio <sup>*</sup>		1.01

Data obtained at optimum efficiency level.

The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

<sup>\*</sup> Specific ratio =  $1 + p_{fs} / 100\,000\text{ Pa}$ 

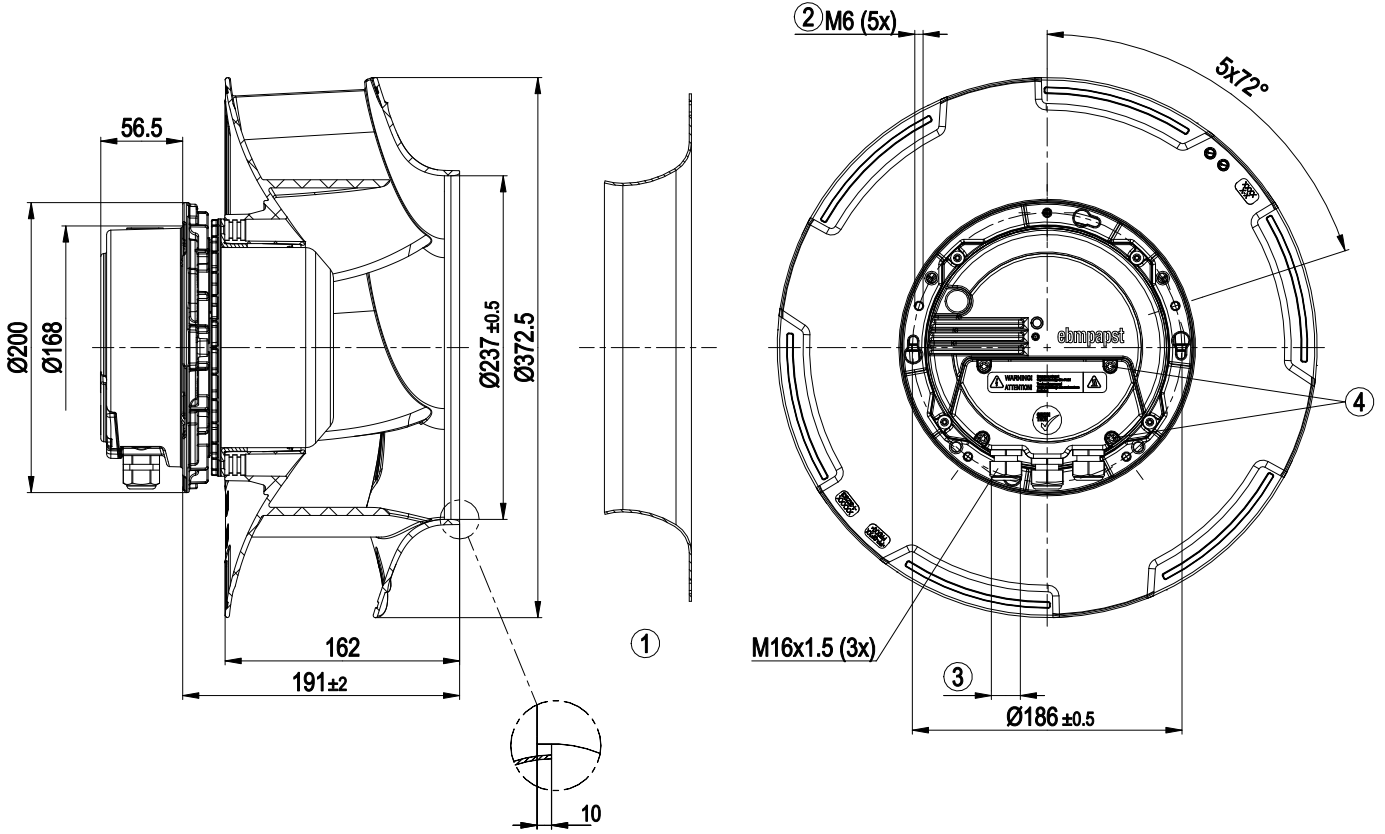
LU-189372



## Technical description

Weight	8.2 kg
Fan size	355 mm
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum
Impeller material	PP plastic
Number of blades	6
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP54
Insulation class	"B"
Moisture (F) / Environmental (H) protection class	H1
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	<ul style="list-style-type: none"> <li>- Output 10 VDC, max. 10 mA</li> <li>- Output 20 VDC, max. 50 mA</li> <li>- Output for slave 0-10 V</li> <li>- Operation and alarm display</li> <li>- Selection of direction of rotation left/right</li> <li>- Input for sensor 0-10 V or 4-20 mA</li> <li>- External 24 V input (parameter setting)</li> <li>- Alarm relay</li> <li>- Integrated PID controller</li> <li>- Power limiter</li> <li>- Motor current limitation</li> <li>- PFC, active</li> <li>- RS-485 MODBUS-RTU</li> <li>- Soft start</li> <li>- Control input 0-10 VDC / PWM</li> <li>- Control interface with SELV potential safely disconnected from the mains</li> <li>- Thermal overload protection for electronics/motor</li> <li>- Line undervoltage / phase failure detection</li> </ul>
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Via terminal box
Motor protection	Thermal overload protector (TOP) internally connected
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approval	EAC; CCC

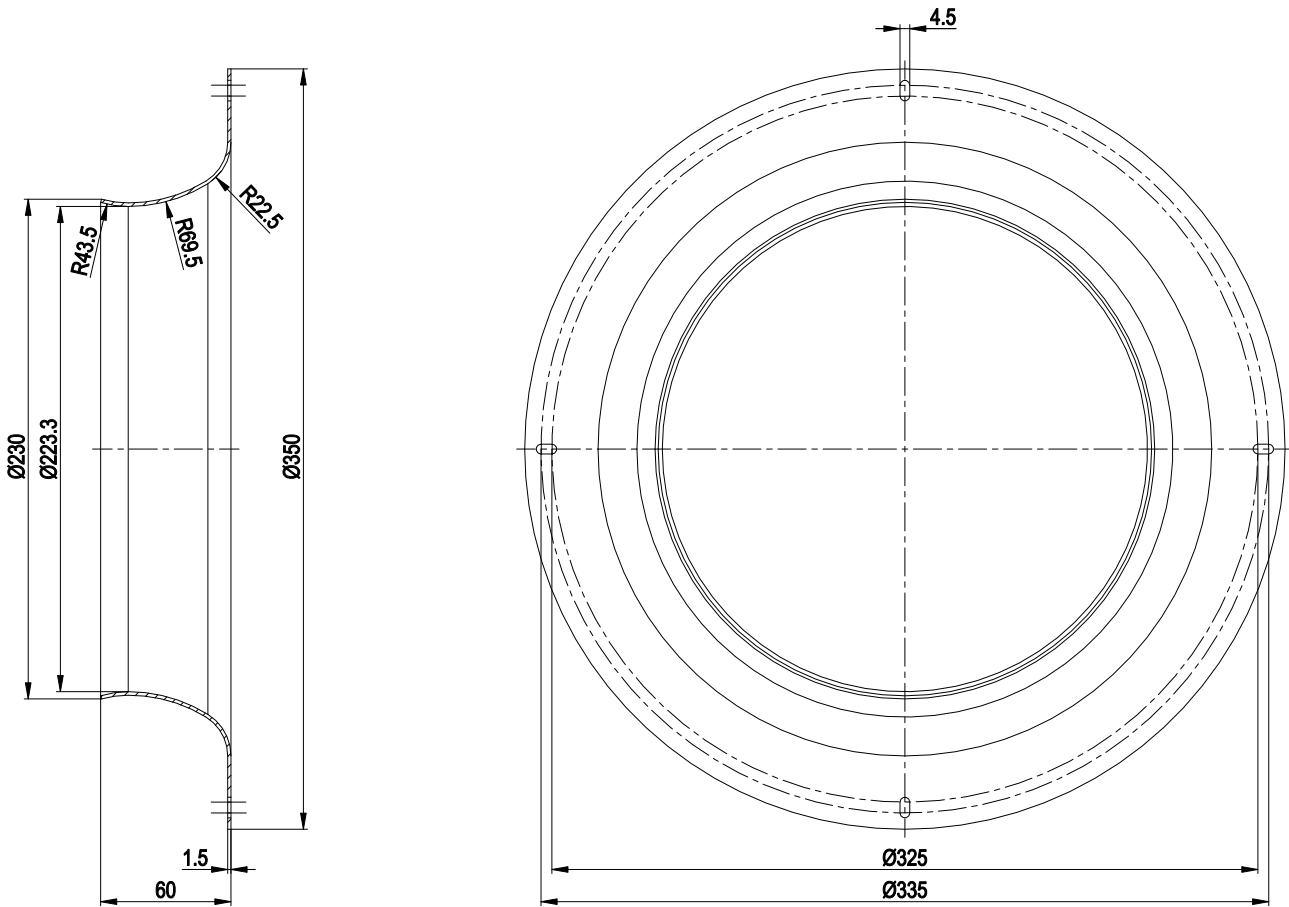
Product drawing



1	Accessory part: inlet ring 35500-2-4013 not included in scope of delivery
2	Max. clearance for screw 16 mm
3	Cable diameter min. 4 mm, max. 10 mm, tightening torque $4 \pm 0.6$ Nm
4	Tightening torque $3.5 \pm 0.5$ Nm



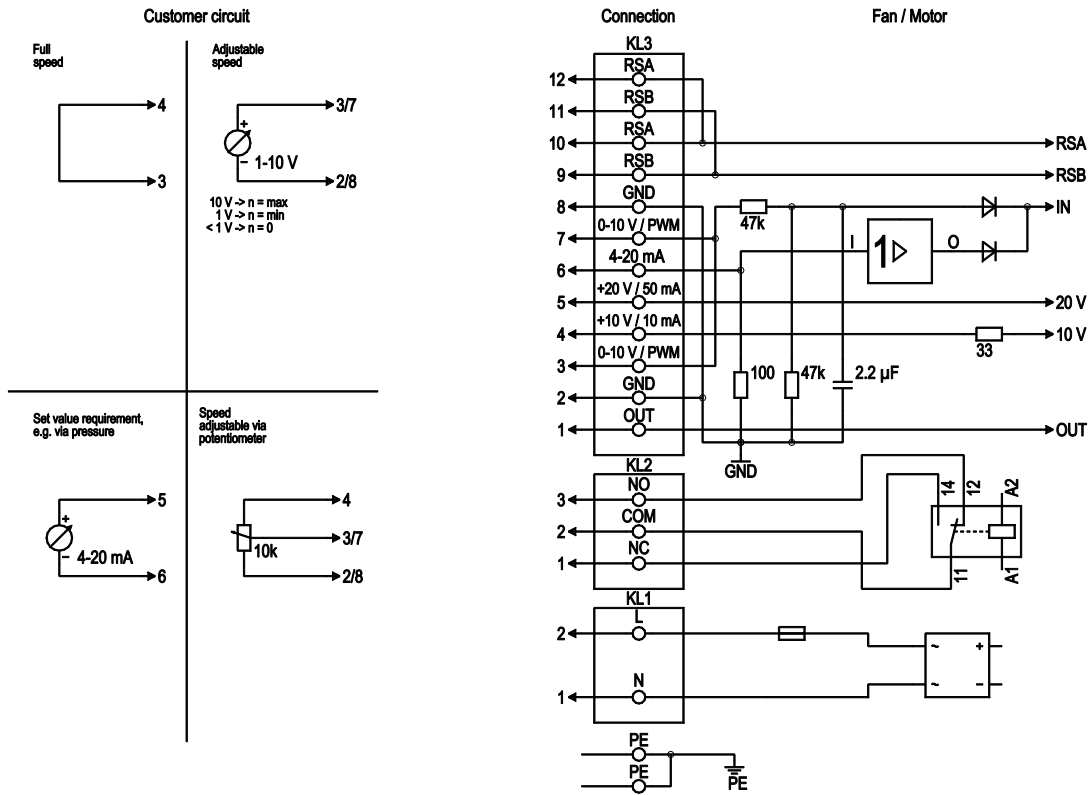
## Accessory part



Inlet ring 35500-2-4013 not included in scope of delivery



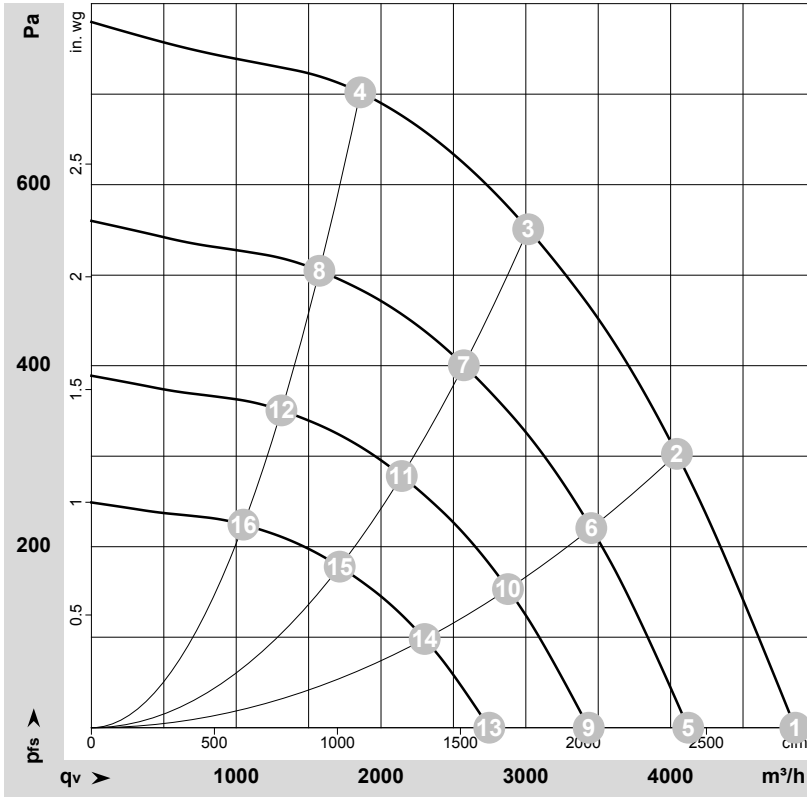
## Connection diagram



No.	Conn.	Designation	Function/assignment
PE	-	PE	Protective earth terminal
KL1	1, 2	N, L	Power supply 50/60 Hz
KL2	1	NC	Floating status contact, break for failure
KL2	2	COM	Floating status contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status contact, make for failure
KL3	1	OUT	Analog output, 0-10 VDC, max. 3 mA, SELV output of current motor modulation level: 1 V corresponds to 10% modulation level. 10 V corresponds to 100% modulation level.
KL3	2, 8	GND	Reference ground for control interface, SELV
KL3	3, 7	0-10 V	Control/current sensor value input 0-10 VDC, impedance 100 kΩ, use only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (+/- 3%), max. 10 mA, power supply for ext. devices (e.g. potentiometer), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25%/-10%), max. 50 mA power supply for ext. devices (e.g. sensors), SELV
KL3	6	4-20 mA	Control/current sensor value input 4-20 mA, impedance 100 Ω, use only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for MODBUS, RSB
KL3	10, 12	RSA	RS485 interface for MODBUS, RSA



## Curves: Air performance 50 Hz



$\rho = 1.15 \text{ kg/m}^3 \pm 2 \%$

Measurement: LU-189372-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebmpapst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

## Measured values

	Wired	U	f	n	P <sub>ed</sub>	I	q <sub>v</sub>	P <sub>fs</sub>	q <sub>v</sub>	P <sub>fs</sub>
		V	Hz	min <sup>-1</sup>	W	A	m <sup>3</sup> /h	Pa	cfm	in. wg
1	1~	230	50	2100	547	2.39	4860	0	2860	0.00
2	1~	230	50	2100	719	3.14	4045	300	2380	1.20
3	1~	230	50	2100	750	3.30	3015	550	1775	2.21
4	1~	230	50	2100	714	3.11	1855	700	1095	2.81
5	1~	230	50	1800	333	1.45	4120	0	2425	0.00
6	1~	230	50	1800	448	1.95	3450	222	2030	0.89
7	1~	230	50	1800	484	2.11	2570	400	1515	1.61
8	1~	230	50	1800	435	1.90	1575	505	925	2.03
9	1~	230	50	1500	193	0.84	3435	0	2020	0.00
10	1~	230	50	1500	259	1.13	2875	154	1695	0.62
11	1~	230	50	1500	280	1.22	2145	278	1260	1.12
12	1~	230	50	1500	252	1.10	1310	351	770	1.41
13	1~	230	50	1200	99	0.43	2750	0	1615	0.00
14	1~	230	50	1200	133	0.58	2300	99	1355	0.40
15	1~	230	50	1200	143	0.62	1715	178	1010	0.71
16	1~	230	50	1200	129	0.56	1050	224	620	0.90

Wired = Wiring · U = Power supply · f = Frequency · n = Speed (rpm) · P<sub>ed</sub> = Power consumption · I = Current draw · q<sub>v</sub> = Air flow · P<sub>fs</sub> = Pressure increase

