

R3G310-BC38-01 ebmpapst Datasheet

sales@fansco.com

www.fansco.com

Limited partnership · Headquarters Muldingen

Amtsgericht (court of registration) Stuttgart · HRA 590344

General partner Elektrobau Muldingen GmbH · Headquarters Muldingen

Amtsgericht (court of registration) Stuttgart · HRB 590142



## Nominal data

Type	R3G310-BC38-01	
Motor	M3G112-GA	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Method of obtaining data		ml
Speed	min <sup>-1</sup>	3170
Power consumption	W	1650
Current draw	A	2.5
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	50

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment  
Subject to change

## Data according to ErP Directive

		Actual	Req. 2015			
01 Overall efficiency $\eta_{es}$	%	53.8	53.8	09 Power consumption $P_{ed}$	kW	1.65
02 Measurement category		A		09 Air flow $q_v$	m <sup>3</sup> /h	3025
03 Efficiency category		Static		09 Pressure increase $p_{fs}$	Pa	944
04 Efficiency grade N		62	62	10 Speed n	min <sup>-1</sup>	3175
05 Variable speed drive		Yes		11 Specific ratio*		1.01

Data obtained at optimum efficiency level.

The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

\* Specific ratio =  $1 + p_{fs} / 100\,000\text{ Pa}$ 

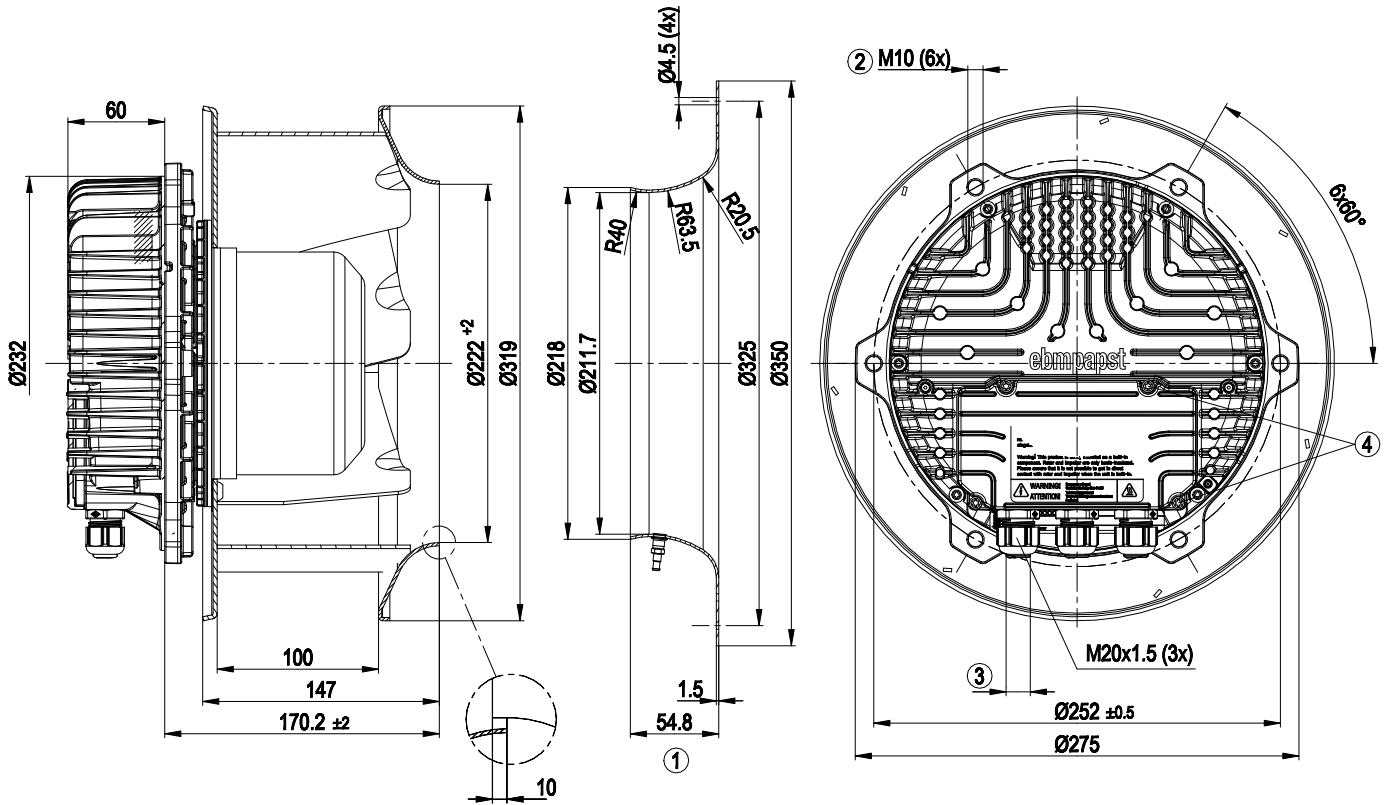
LU-141522



## Technical description

Weight	11.8 kg
Fan size	310 mm
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum
Impeller material	Sheet aluminum
Number of blades	7
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP54
Insulation class	"B"
Moisture (F) / Environmental (H) protection class	F4-1
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	<ul style="list-style-type: none"> <li>- Output 10 VDC, max. 10 mA</li> <li>- Output 20 VDC, max. 50 mA</li> <li>- Output for slave 0-10 V</li> <li>- Input for sensor 0-10 V or 4-20 mA</li> <li>- External 24 V input (parameter setting)</li> <li>- External release input</li> <li>- Alarm relay</li> <li>- Integrated PID controller</li> <li>- Motor current limitation</li> <li>- PFC, passive</li> <li>- RS-485 MODBUS-RTU</li> <li>- Soft start</li> <li>- Control input 0-10 VDC / PWM</li> <li>- Control interface with SELV potential safely disconnected from supply</li> <li>- Thermal overload protection for electronics/motor</li> <li>- Line undervoltage / phase failure detection</li> </ul>
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Via terminal box
Motor protection	Thermal overload protector (TOP) internally connected
With cable	Variable
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approval	EAC; UL 1004-7 + 60730

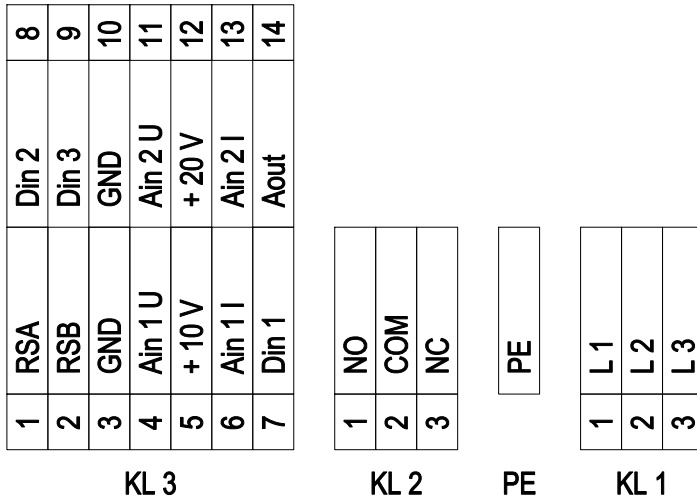
Product drawing



1	Accessory part: inlet ring with pressure tap 31575-2-4013 (k-factor: 116) not included in scope of delivery
2	Max. clearance for screw 20 mm
3	Cable diameter min. 4 mm, max. 10 mm, tightening torque $4 \pm 0.6$ Nm
4	Tightening torque $3.5 \pm 0.5$ Nm



## Connection diagram

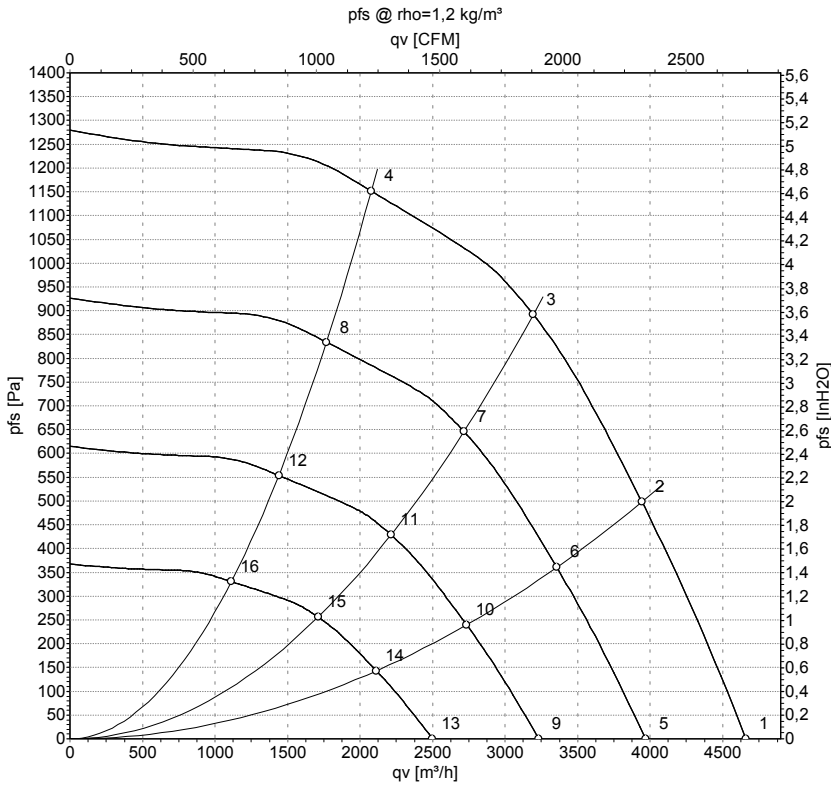


No.	Conn.	Designation	Function/assignment
KL 1	1	L1	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
KL 1	2	L2	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
KL 1	3	L3	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
PE		PE	Ground connection, PE connection
KL 2	1	NO	Status relay, floating status contact; make for failure
KL2	2	COM	Status relay, floating status contact; changeover contact; common connection; contact rating 250 VAC / max. 2 A (AC1) / min. 10 mA
KL2	3	NC	Status relay, floating status contact; break for failure
KL 3	1	RSA	Bus connection RS485, RSA, MODBUS-RTU; SELV
KL 3	2	RSB	Bus connection RS485, RSB, MODBUS-RTU; SELV
KL 3	3 / 10	GND	Reference ground for control interface; SELV
KL 3	4	Ain1 U	Analog input 1, set value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain1 I; SELV
KL 3	5	+ 10 V	Fixed voltage output 10 VDC, +10 V ±3%, max. 10 mA, short-circuit-proof power supply for external devices (e.g. pot); SELV
KL 3	6	Ain1 I	Analog input 1, set value: 4-20 mA, Ri = 100 Ω, adjustable curve, only usable as alternative to input Ain1U; SELV
KL 3	7	Din1	Digital input 1: enable electronics, enable: pin open or applied voltage 5-50 VDC disable: bridge to GND or applied voltage < 1 VDC reset function: triggers software reset after a level change to < 1 VDC; SELV
KL 3	8	Din2	Digital input 2: Switching parameter sets 1/2, according to EEPROM setting, the valid or used parameter set can be selected via bus or via digital input DIN2. Parameter set 1: pin open or applied voltage 5-50 VDC Parameter set 2: bridge to GND or applied voltage < 1 VDC; SELV
KL 3	9	Din3	Digital input 3: according to EEPROM setting, the integrated controller's direction of action can be selected as normal/inverse via bus or digital input normal: pin open or applied voltage 5-50 VDC inverse: bridge to GND or applied voltage < 1 VDC; SELV
KL 3	11	Ain2 U	Analog input 2, measured value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain2I; SELV
KL 3	12	+ 20 V	Fixed voltage output 20 VDC, +20 V ±5/-10%, max. 50 mA, short-circuit-proof power supply for external devices (e.g. sensors); SELV

No.	Conn.	Designation	Function/assignment
KL 3	13	Ain2 I	Analog input 2, measured value: 4-20 mA, Ri = 100 $\Omega$ , adjustable curve, only usable as alternative to input Ain2U; SELV
KL 3	14	Aout	Analog output 0-10 VDC, max. 5 mA, output of current motor modulation level / motor speed adjustable curve; SELV



## Curves: Air performance 50 Hz



Measurement: LU-141522-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebmpapst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

## Measured values

	U	f	n	P <sub>ed</sub>	I	LpA <sub>in</sub>	LwA <sub>in</sub>	LwA <sub>out</sub>	qv	P <sub>fs</sub>
	V	Hz	min <sup>-1</sup>	W	A	dB(A)	dB(A)	dB(A)	m <sup>3</sup> /h	Pa
1	400	50	3170	1230	1.83	82	90	96	4660	0
2	400	50	3170	1523	2.27	80	88	94	3945	500
3	400	50	3170	1650	2.50	77	85	92	3195	900
4	400	50	3170	1540	2.30	79	88	92	2075	1150
5	400	50	2700	758	1.13	78	86	92	3965	0
6	400	50	2700	939	1.40	76	84	90	3355	362
7	400	50	2700	1013	1.50	73	81	88	2715	646
8	400	50	2700	949	1.42	75	84	88	1770	834
9	400	50	2200	410	0.61	73	81	87	3235	0
10	400	50	2200	508	0.76	70	79	85	2735	240
11	400	50	2200	548	0.81	68	76	82	2215	429
12	400	50	2200	513	0.77	70	79	83	1440	554
13	400	50	1700	189	0.28	66	74	81	2500	0
14	400	50	1700	234	0.35	64	72	79	2115	143
15	400	50	1700	253	0.37	61	70	76	1710	256
16	400	50	1700	237	0.35	63	72	77	1115	331

U = Power supply · f = Frequency · n = Speed · P<sub>ed</sub> = Power consumption · I = Current draw · LpA<sub>in</sub> = Sound pressure level intake side · LwA<sub>in</sub> = Sound power level intake side  
 LwA<sub>out</sub> = Sound power level outlet side · qv = Air flow · p<sub>fs</sub> = Pressure increase

