

R3G280-AJ14-C1 ebmpapst Datasheet

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Nominal data

Type	R3G280-AJ14-C1	
Motor	M3G084-GF	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
State		prelim.
Speed	min ⁻¹	3260
Power input	W	985
Current draw	A	1.6
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	60

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations

Data according to ErP directive

Installation category	A
Efficiency category	Static
Variable speed drive	Yes
Specific ratio*	1.01

* Specific ratio = $1 + p_{fs} / 100\,000\text{ Pa}$

		Actual	Request 2013	Request 2015
Overall efficiency η_{es}	%	51.3	47.3	51.3
Efficiency grade N		62	58	62
Power input P_{ed}	kW	0.96		
Air flow q_v	m ³ /h	2080		
Pressure increase p_{fs}	Pa	784		
Speed n	min ⁻¹	3260		

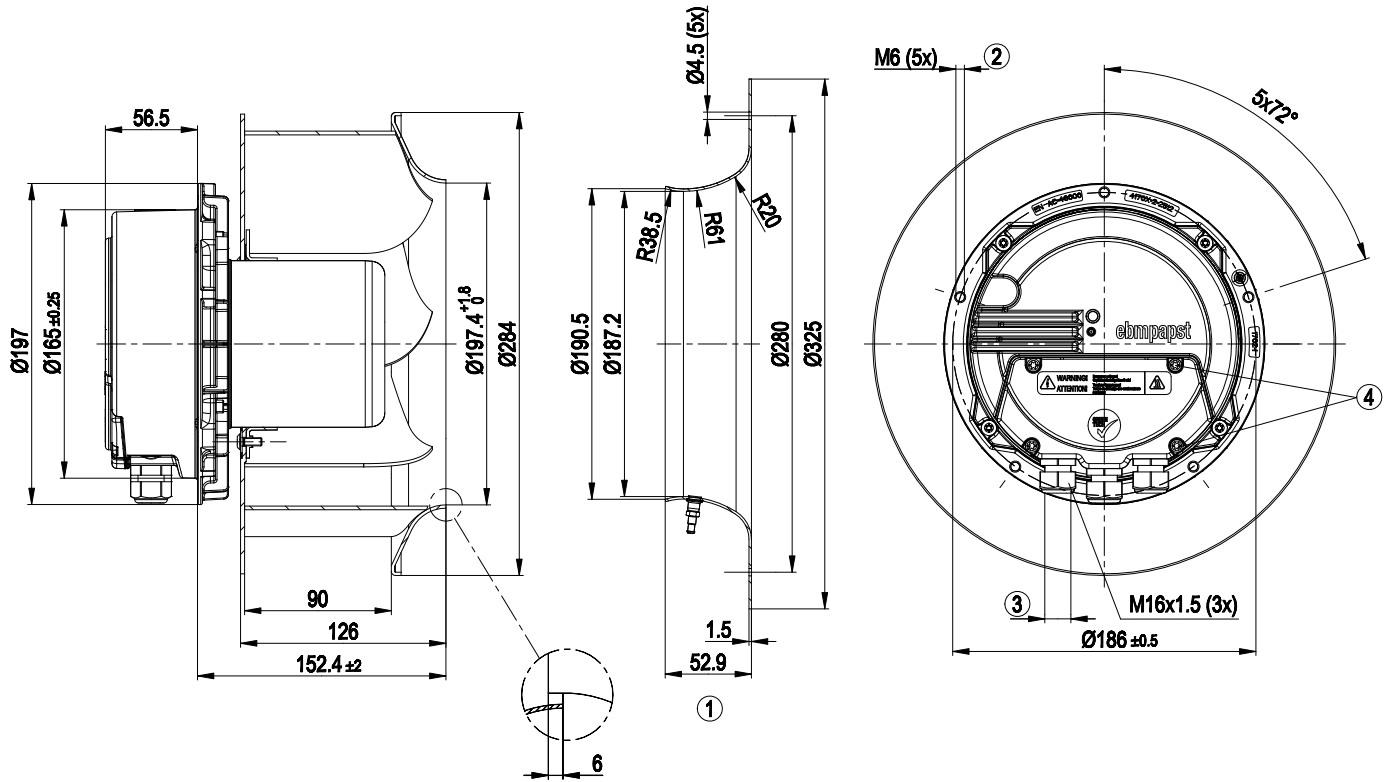
Data definition with optimum efficiency. LU-141548
The ErP data is determined using a motor-impeller combination in a standardised measurement configuration.



Technical features

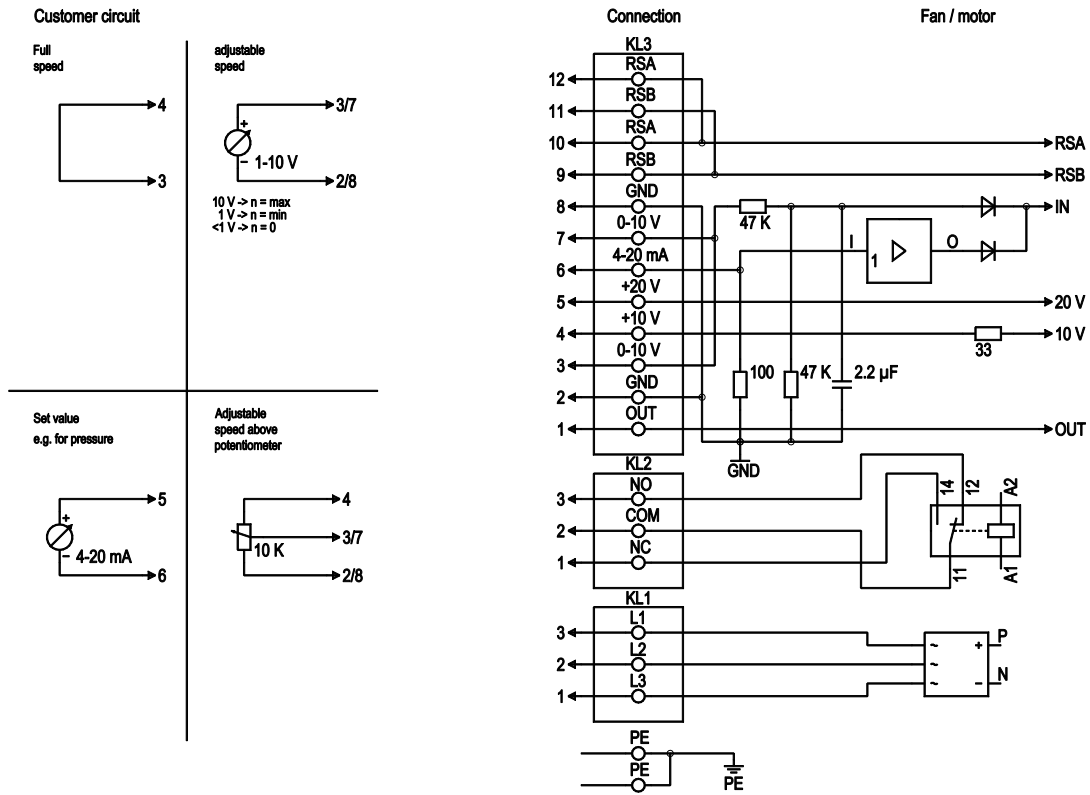
Mass	7.1 kg
Size	280 mm
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium
Material of impeller	Aluminium sheet
Number of blades	7
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP 54
Insulation class	"B"
Humidity class	F3-1
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensate discharge holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	<ul style="list-style-type: none"> - Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - External 24 V input (programming) - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive - RS485 MODBUS RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical leads	Via terminal box
Motor protection	Thermal overload protector (TOP) wired internally
Protection class	I (if protective earth is connected by customer at the connection point of the housing)
Product conforming to standard	EN 61800-5-1; CE
Approval	C22.2 Nr.77 + CAN/CSA-E60730-1; EAC; UL 1004-7 + 60730

Product drawing



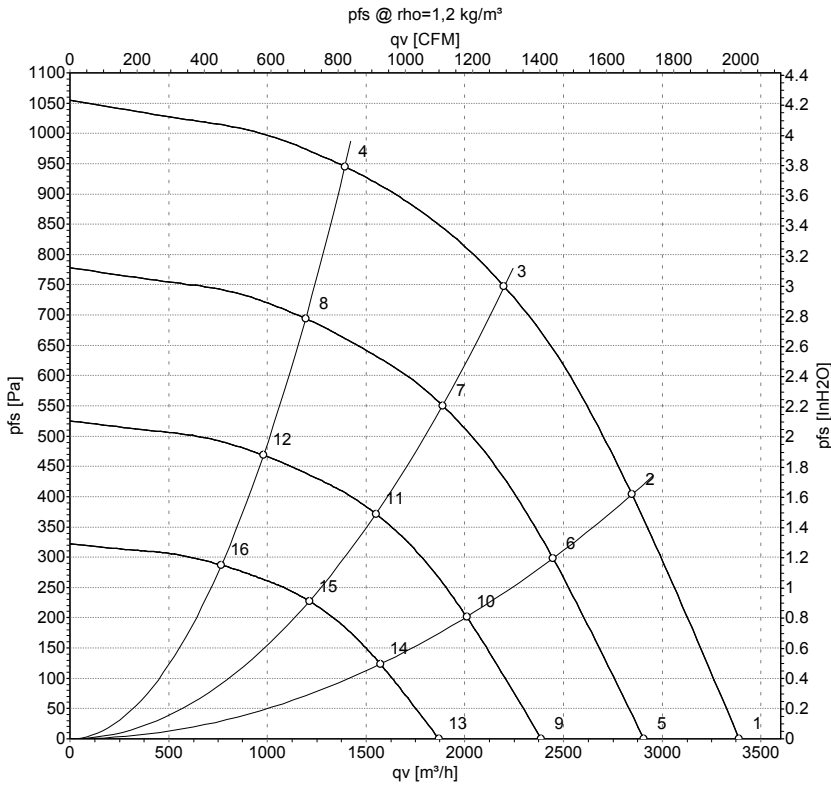
1	Accessory part: Inlet nozzle 28075-2-4013 with a bleeder connection for pressure relief (k-factor: 93), not included in the standard scope of delivery.
2	Depth of screw max. 16 mm
3	Cable diameter: min. 4 mm, max. 10 mm; tightening torque: 2.5 ± 0.4 Nm
4	Tightening torque 3.5 ± 0.5 Nm

Connection screen



No.	Conn.	Designation	Function / assignment
PE		PE	Protective earth connection
KL1	1, 2, 3	L1, L2, L3	Supply voltage, voltage range (see type plate), 50/60 Hz
KL2	1	NC	Floating status contact, break with error
KL2	2	COM	Floating status contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status contact, close with error
KL3	1	OUT	Analogue output, 0-10 VDC, max. 3 mA, SELV, Output of the actual motor duty cycle (PWM): 1 V corresponds to 10% PWM, 10 V correspond to 100% PWM.
KL3	2, 8	GND	Signal ground for control interface, SELV
KL3	3, 7	0-10 V	Set value / actual sensor value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (+/-3%), max. 10 mA, power supply for external devices (e.g. potentiometer), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25%/-10%), max. 50 mA, supply voltage for external devices (e.g. sensors), SELV
KL3	6	4-20 mA	Set value / actual sensor value input 4-20 mA, impedance 100 Ω, only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for MODBUS, RSB
KL3	10, 12	RSA	RS485 interface for MODBUS, RSA

Charts: Air flow 50 Hz



Measurement: LU-141548

Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebmpapst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

Measured values

	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	LwA _{out}	qv	p _{fs}
	V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m ³ /h	Pa
1	400	50	3260	703	1.31	79	89	94	3390	0
2	400	50	3260	877	1.57	78	86	92	2845	400
3	400	50	3260	985	1.60	76	84	89	2200	750
4	400	50	3260	873	1.57	76	85	89	1390	950
5	400	50	2800	443	0.82	75	85	90	2905	0
6	400	50	2800	557	1.00	74	82	88	2445	300
7	400	50	2800	613	1.07	72	80	85	1885	551
8	400	50	2800	550	0.99	72	81	85	1195	696
9	400	50	2300	246	0.46	70	80	85	2390	0
10	400	50	2300	309	0.55	69	77	83	2010	203
11	400	50	2300	340	0.60	67	75	80	1550	372
12	400	50	2300	305	0.55	67	76	80	980	470
13	400	50	1800	118	0.22	64	74	79	1870	0
14	400	50	1800	148	0.26	63	71	77	1575	124
15	400	50	1800	163	0.29	61	69	74	1215	228
16	400	50	1800	146	0.26	61	70	74	765	288

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Power input · I = Current draw · LpA_{in} = Sound pressure level inlet side · LwA_{in} = Sound power level inlet side · LwA_{out} = Sound power level outlet side
 qv = Air flow · p_{fs} = Pressure increase

