



R3G250-AV29-B5 ebmpapst Datasheet
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Nominal data

Type	R3G250-AV29-B5	
Motor	M3G084-FA	
Phase		1~
Nominal voltage	VAC	230
Nominal voltage range	VAC	200 .. 277
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min ⁻¹	3450
Power consumption	W	750
Current draw	A	3.3
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	40

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
 Subject to change

Data according to ErP Directive

		Actual	Req. 2015			
01 Overall efficiency η_{es}	%	59.1	50.2	09 Power consumption P_{ed}	kW	0.75
02 Measurement category		A		09 Air flow q_v	m ³ /h	1750
03 Efficiency category		Static		09 Pressure increase p_{fs}	Pa	833
04 Efficiency grade N		70.9	62	10 Speed (rpm) n	min ⁻¹	3445
05 Variable speed drive		Yes		11 Specific ratio*		1.01

Data obtained at optimum efficiency level.
 The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

* Specific ratio = $1 + p_{fs} / 100\,000\text{ Pa}$

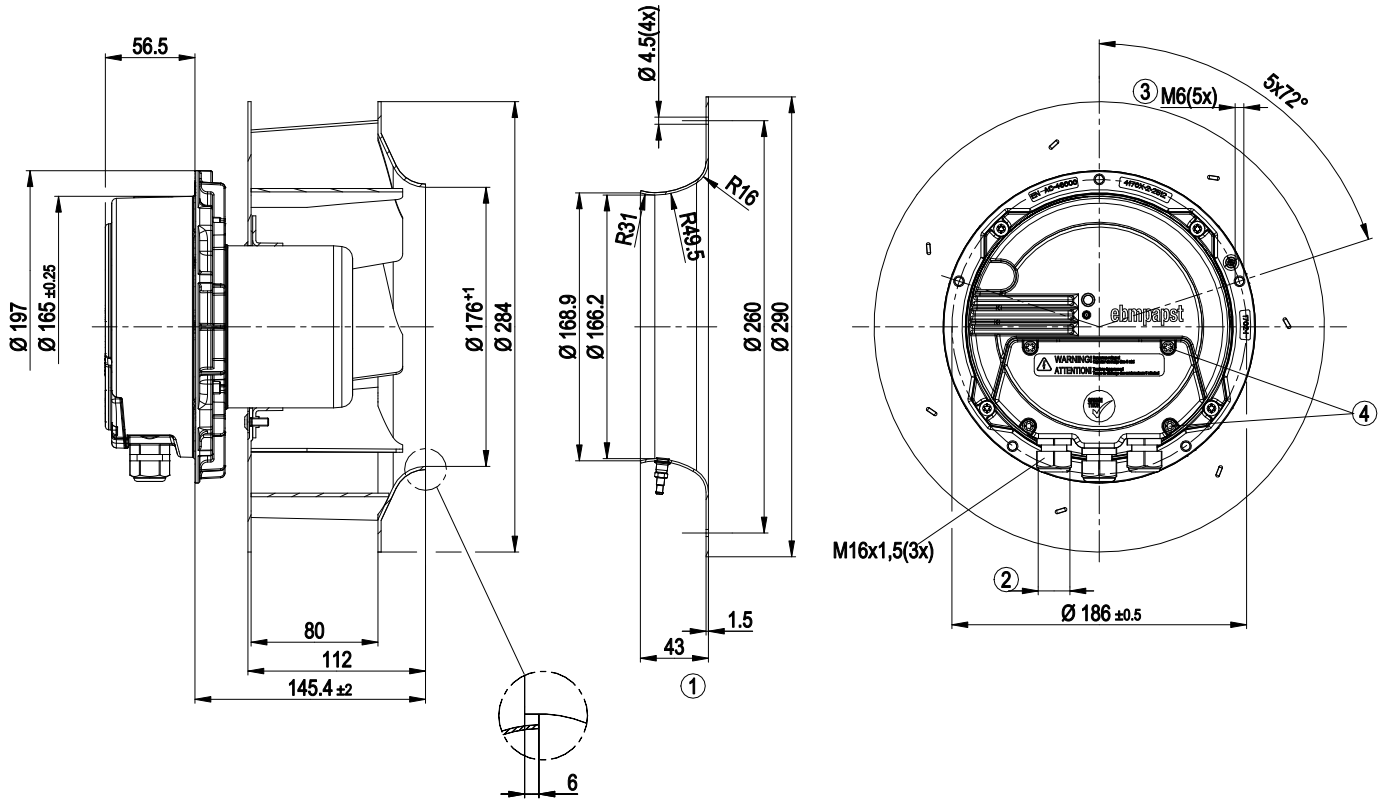
LU-141280



Technical description

Weight	5.6 kg
Fan size	250 mm
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum
Impeller material	Sheet aluminum
Number of blades	7
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP54
Insulation class	"B"
Moisture (F) / Environmental (H) protection class	F3-1
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	<ul style="list-style-type: none"> - Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Selection of direction of rotation left/right - Input for sensor 0-10 V or 4-20 mA - Alarm relay - Motor current limitation - PFC, active - RS-485 MODBUS-RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC circuit feedback	According to EN 61000-3-2/3
EMC interference emission	According to EN 55022 (Class B, household environment)
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Motor protection	Thermal overload protector (TOP) internally connected
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE

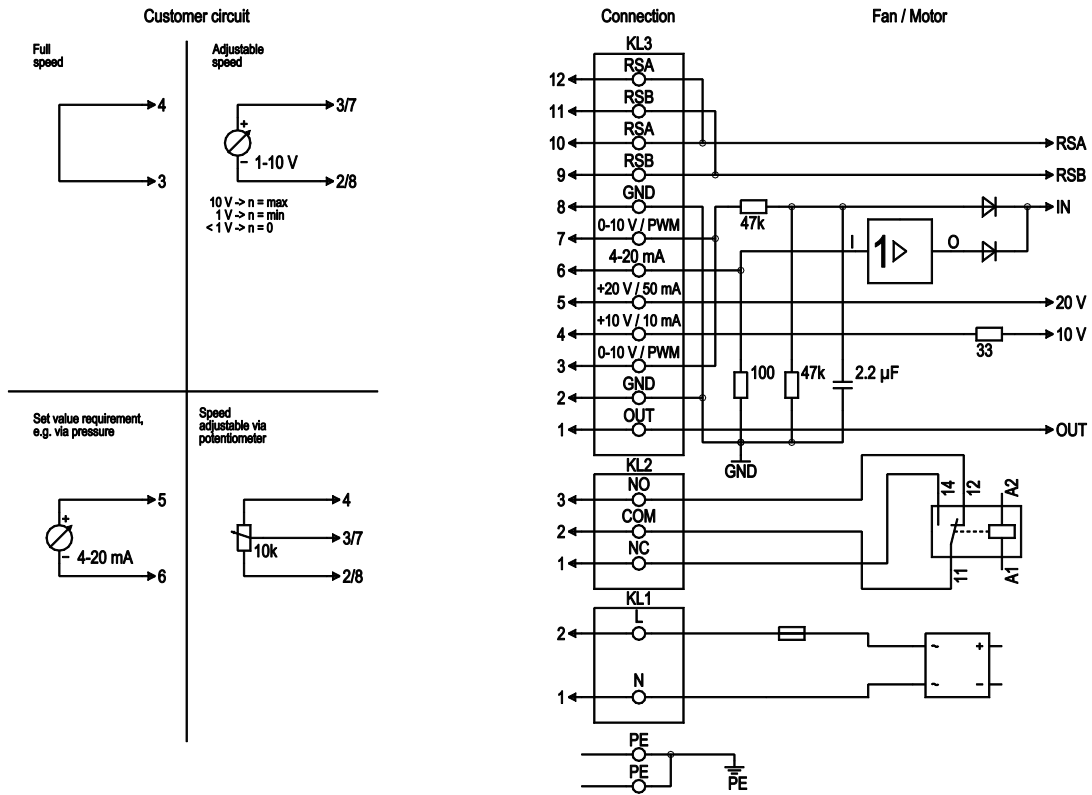
Product drawing



1	Accessory part: Inlet ring 25075-2-4013 with pressure tap (k-factor: 70) not included in scope of delivery.
2	Cable diameter min. 4 mm, max. 10 mm; tightening torque 2.5±0.4 Nm
3	Max. clearance for screw 16 mm
4	Tightening torque 3.5 ± 0.5 Nm



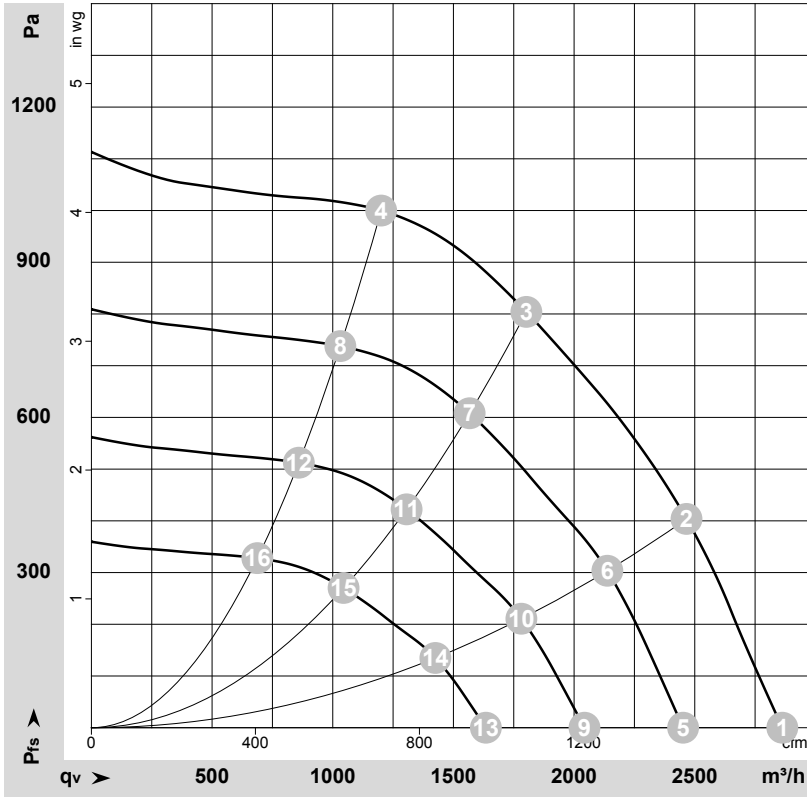
Connection diagram



No.	Conn.	Designation	Function/assignment
PE	-	PE	Protective earth terminal
KL1	1, 2	N, L	Power supply 50/60 Hz
KL2	1	NC	Floating status contact, break for failure
KL2	2	COM	Floating status contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status contact, make for failure
KL3	1	OUT	Analog output, 0-10 VDC, max. 3 mA, SELV output of current motor modulation level: 1 V corresponds to 10% modulation level. 10 V corresponds to 100% modulation level.
KL3	2, 8	GND	Reference ground for control interface, SELV
KL3	3, 7	0-10 V	Control/current sensor value input 0-10 VDC, impedance 100 kΩ, use only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (+/- 3%), max. 10 mA, power supply for ext. devices (e.g. potentiometer), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25%/-10%), max. 50 mA power supply for ext. devices (e.g. sensors), SELV
KL3	6	4-20 mA	Control/current sensor value input 4-20 mA, impedance 100 Ω, use only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for MODBUS, RSB
KL3	10, 12	RSA	RS485 interface for MODBUS, RSA



Curves: Air performance 50 Hz



$\rho = 1.15 \text{ kg/m}^3 \pm 2 \%$

Measurement: LU-141280-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebmpapst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	qv	p _{fs}	qv	p _{fs}
	V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	m ³ /h	Pa	CFM	inH ₂ O
1	230	50	3450	618	2.74	79	87	2865	0	1685	0.00
2	230	50	3450	734	3.24	76	84	2465	400	1450	1.61
3	230	50	3450	750	3.30	73	81	1800	800	1060	3.21
4	230	50	3450	705	3.12	74	82	1200	1000	705	4.01
5	230	50	3000	388	1.72	75	83	2450	0	1445	0.00
6	230	50	3000	479	2.11	73	81	2140	305	1260	1.22
7	230	50	3000	493	2.18	69	77	1565	609	920	2.44
8	230	50	3000	447	1.98	70	78	1030	739	605	2.97
9	230	50	2500	225	0.99	70	78	2045	0	1200	0.00
10	230	50	2500	277	1.22	68	76	1780	212	1050	0.85
11	230	50	2500	285	1.26	65	73	1305	423	770	1.70
12	230	50	2500	258	1.14	65	74	860	513	505	2.06
13	230	50	2000	115	0.51	65	72	1635	0	960	0.00
14	230	50	2000	142	0.63	63	70	1425	135	840	0.54
15	230	50	2000	146	0.65	59	67	1045	271	615	1.09
16	230	50	2000	132	0.59	60	68	690	328	405	1.32

U = Power supply · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
 qv = Air flow · p_{fs} = Pressure increase

