

EC centrifugal module - RadiPac

backward-curved, single-intake

with cube design

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Nominal data

Type	K3G630-AT09-11	
Motor	M3G200-QA	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min ⁻¹	2200
Power consumption	W	13750
Current draw	A	21.0
Min. ambient temperature	°C	-40
Max. ambient temperature	°C	40

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change



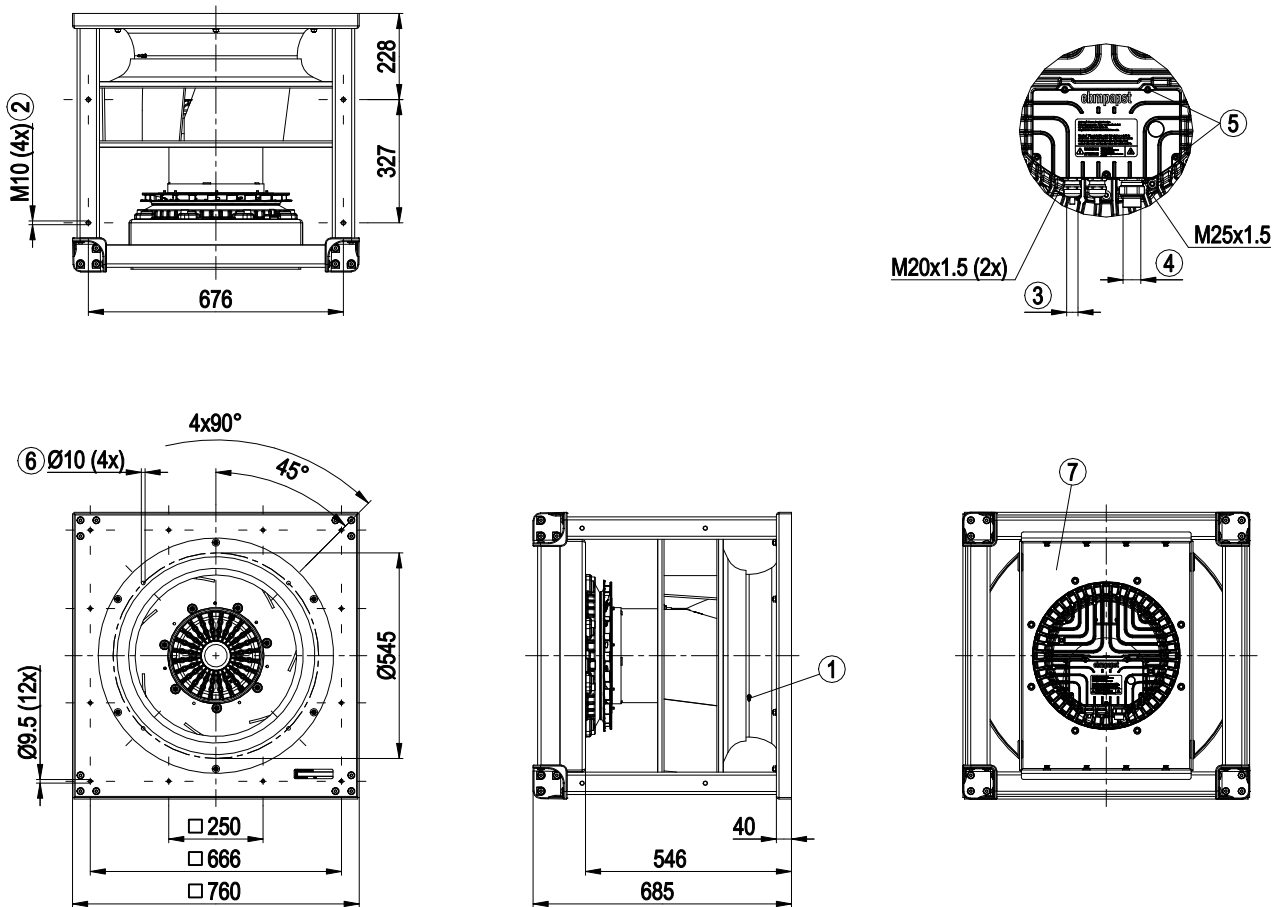
Technical description

Weight	132 kg
Size	630 mm
Motor size	200
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum, painted black
Impeller material	Sheet aluminum
Inlet nozzle material	Sheet steel, galvanized
Support structure material	Sheet steel, galvanized
Number of blades	7
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	"F"
Moisture (F) / Environmental (H) protection class	H1
Ambient temperature note	Occasional start-up at temperatures between -40°C and -25°C is permitted. For continuous operation at ambient temperatures below -25°C (such as refrigeration applications), use must be made of a fan design with special low-temperature bearings.
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	See legend on product drawing
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	- Power limiter - Motor current limitation - PFC, passive - Soft start - Temperature derating - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class assignment	I; If a protective earth is connected by the customer This component for installation may have several local protection classes. This information relates to this component's basic design. The final protection class is based on the component's intended installation and connection.
Conformity with standards	EN 61800-5-1
Approval	UL 1004-7 + 60730-1; EAC; CSA C22.2 No. 77 + CAN/CSA-E60730-1

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Product drawing



1	Inlet ring with pressure tap (k-factor: 438)
2	Mounting position for vibration-absorbing elements, tightening torque max. 40 Nm
3	Cable diameter min. 5 mm, max. 13 mm; tightening torque 6 ± 0.9 Nm
4	Cable diameter min. 16 mm, max. 20.5 mm, tightening torque 6 ± 0.9 Nm
5	Tightening torque 3.5 ± 0.5 Nm
6	Attachment holes for FlowGrid 00630-2-2957 (not included in scope of delivery)
7	Motor support plate
Installation position: Only base mounting, shaft horizontal (motor support plate must be vertical!). Rotor on top or rotor on bottom on request	
The drawing shows the dimensions only and does not represent the installation position	

Connection diagram

1	RSA	Din 2	8
2	RSB	Din 3	9
3	GND	GND	10
4	Ain 1 U	Ain 2 U	11
5	+ 10 V	+ 20 V	12
6	Ain 1 I	Ain 2 I	13
7	Din 1	Aout	14

KL 3

1	NO
2	COM
3	NC

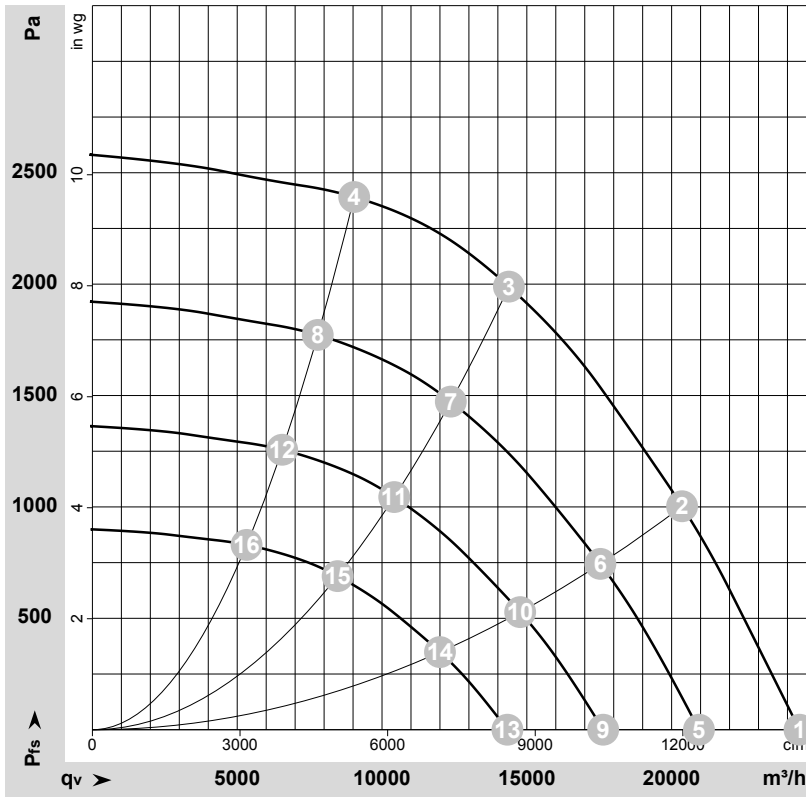
KL 2

1	L 1
2	L 2
3	L 3
	PE

KL 1 PE

No.	Conn.	Designation	Function/assignment
KL 1	1	L1	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
KL 1	2	L2	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
KL 1	3	L3	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
PE		PE	Ground connection, PE connection
KL 2	1	NO	Status relay, floating status contact, make for failure
KL2	2	COM	Status relay, floating status contact; changeover contact; common connection; contact rating 250 VAC / max. 2 A (AC1) / min. 10 mA
KL2	3	NC	Status relay, floating status contact, break for failure
KL 3	1	RSA	Bus connection RS485, RSA, MODBUS RTU
KL 3	2	RSB	Bus connection RS485, RSB, MODBUS RTU
KL 3	3 / 10	GND	Reference ground for control interface
KL 3	4	Ain1 U	Analog input 1 (set value), 0-10 V, Ri = 100 kΩ, adjustable curves, only usable as alternative to input Ain1I
KL 3	5	+ 10 V	Fixed voltage output 10 VDC, +10 V ±3%; max. 10 mA; short-circuit-proof; power supply for external devices (e.g. pot)
KL 3	6	Ain1 I	Analog input 1 (set value), 4-20 mA, Ri = 100 Ω, adjustable curves, only usable as alternative to input Ain1U
KL 3	7	Din1	Digital input 1: enable electronics, enable: pin open or applied voltage 5...50 VDC; disable: bridge to GND or applied voltage < 1 VDC; reset function: triggers software reset after a level change to < 1 V
KL 3	8	Din2	Digital input 2: Switching parameter sets 1/2; according to EEPROM setting, the valid or used parameter set can be selected via bus or via digital input DIN2. Parameter set 1: pin open or applied voltage 5-50 VDC; parameter set 2: bridge to GND or applied voltage < 1 VDC
KL 3	9	Din3	Digital input 3: according to EEPROM setting, the integrated controller's direction of action can be selected as normal/inverse via bus or digital input; normal: pin open or applied voltage 5-50 VDC inverse: bridge to GND or applied voltage < 1 VDC
KL 3	11	Ain2 U	Analog input 2, measured value 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain2I
KL 3	12	+ 20 V	Fixed voltage output 20 VDC, 20 V +25/-10%, max. 50 mA, short-circuit-proof power supply for external devices (e.g. sensors)
KL 3	13	Ain2 I	Analog input 2, measured value: 4-20 mA, Ri = 100 Ω, adjustable curve, only usable as alternative to input Ain2U
KL 3	14	Aout	Analog output 0-10 V, max. 5 mA, output of current motor modulation level / of the current motor speed. Adjustable curve.

Curves: Air performance 50 Hz



$$\rho = 1.15 \text{ kg/m}^3 \pm 2 \%$$

Measurement: LU-174526-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	Wired	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	LwA _{out}	q _v	p _{fs}	q _v	p _{fs}
		V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m³/h	Pa	cfm	in. wg
1	3~	400	50	2200	8678	13.55	98	107	111	24415	0	14370	0.00
2	3~	400	50	2200	12002	18.49	94	100	104	20360	1000	11985	4.01
3	3~	400	50	2200	13750	21.00	86	94	100	14380	2000	8465	8.03
4	3~	400	50	2200	12352	18.92	92	99	102	9040	2400	5320	9.64
5	3~	400	50	1900	5477	8.55	94	103	107	20945	0	12325	0.00
6	3~	400	50	1900	7670	11.82	90	96	101	17540	747	10325	3.00
7	3~	400	50	1900	8744	13.38	82	90	96	12375	1475	7285	5.92
8	3~	400	50	1900	7881	12.07	88	95	99	7780	1776	4580	7.13
9	3~	400	50	1600	3271	5.11	90	99	103	17635	0	10380	0.00
10	3~	400	50	1600	4581	7.06	85	92	96	14770	530	8695	2.13
11	3~	400	50	1600	5222	7.99	78	86	92	10420	1046	6135	4.20
12	3~	400	50	1600	4706	7.21	84	91	94	6550	1260	3855	5.06
13	3~	400	50	1300	1754	2.74	84	94	98	14330	0	8435	0.00
14	3~	400	50	1300	2457	3.78	80	86	91	12000	350	7065	1.41
15	3~	400	50	1300	2801	4.29	73	81	87	8465	691	4985	2.77
16	3~	400	50	1300	2524	3.87	78	85	89	5325	832	3135	3.34

Wired = Wiring · U = Voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
 LwA_{out} = Sound power level outlet side · q_v = Air flow · p_{fs} = Pressure increase

