

## K3G630-AP01-90

II 2G Ex db eb ib IIB T3 Gb  
IBExU14ATEX1122 X /05

# EC centrifugal module - RadiPac

backward-curved, single-intake  
with cube design



### ebm-papst Mulfingen GmbH & Co. KG

Bachmühle 2 · D-74673 Mulfingen

Phone +49 7938 81-0

Fax +49 7938 81-110

info1@de.fansco.com

www.fansco.com

Limited partnership · Headquarters Mulfingen

Amtsgericht (court of registration) Stuttgart · HRA 590344

General partner Elektrobau Mulfingen GmbH · Headquarters Mulfingen

Amtsgericht (court of registration) Stuttgart · HRB 590142

## Nominal data

Type	K3G630-AP01-90	
Motor	M3G150-NA	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 440
Frequency	Hz	50/60
Method of obtaining data		ml
Status		prelim.
Speed (rpm)	min <sup>-1</sup>	1130
Power consumption	W	2970
Current draw	A	4.6
Min. ambient temperature	°C	-40
Max. ambient temperature	°C	50

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment  
Subject to change

Occasional start-up at temperatures between -40 °C and -25 °C is permitted. For continuous operation at ambient temperatures below -25 °C (such as refrigeration applications), a fan design with special low-temperature bearings must be used.

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## Technical description

Weight	83 kg
Size	630 mm
Motor size	150
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum, painted black
Impeller material	Sheet aluminum
Inlet nozzle material	Sheet aluminum
Support structure material	Sheet steel, galvanized
Number of blades	7
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP44
Insulation class	"F"
Moisture (F) / Environmental (H) protection class	H1
Ambient temperature note	Occasional start-up at temperatures between -40°C and -25°C is permitted. For continuous operation at ambient temperatures below -25°C (such as refrigeration applications), use must be made of a fan design with special low-temperature bearings.
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal (base mounting only) or rotor on bottom; rotor on top not permitted
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	<ul style="list-style-type: none"><li>- Output 10 VDC, max. 10 mA</li><li>- Output 20 VDC, max. 50 mA</li><li>- Output for slave 0-10 V</li><li>- Operation and alarm display</li><li>- Input for sensor 0-10 V or 4-20 mA</li><li>- External 24 V input (parameter setting)</li><li>- External release input</li><li>- Alarm relay</li><li>- Integrated PID controller</li><li>- Motor current limitation</li><li>- PFC, passive</li><li>- RS-485 MODBUS-RTU</li><li>- Soft start</li><li>- Control input 0-10 VDC / PWM</li><li>- Temperature derating</li><li>- Thermal overload protection for electronics/motor</li><li>- Line undervoltage / phase failure detection</li></ul>
Power Factor Correction (PFC)	Passive
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC interference emission	According to EN 61000-6-4 (industrial environment)
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Terminal box

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<b>Motor protection</b>	Reverse polarity and locked-rotor protection
<b>Protection class assignment</b>	I; If a protective earth is connected. The built-in component has several local protection class assignments. The final protection class is determined by the intended installation.
<b>Conformity with standards</b>	EN 14986; EN 60079-0; EN 60079-1; EN 60079-7; EN 60079-11; EN 61800-5-1; CE
<b>Comment on CE</b>	Ecodesign Directive 2009/125/EC + Fan Directive (EC) No. 327/2011 does not apply, as the product is specially designed for operation in potentially explosive atmospheres within the meaning of Directive 94/9/EC.
<b>Approval</b>	EAC; II 2G

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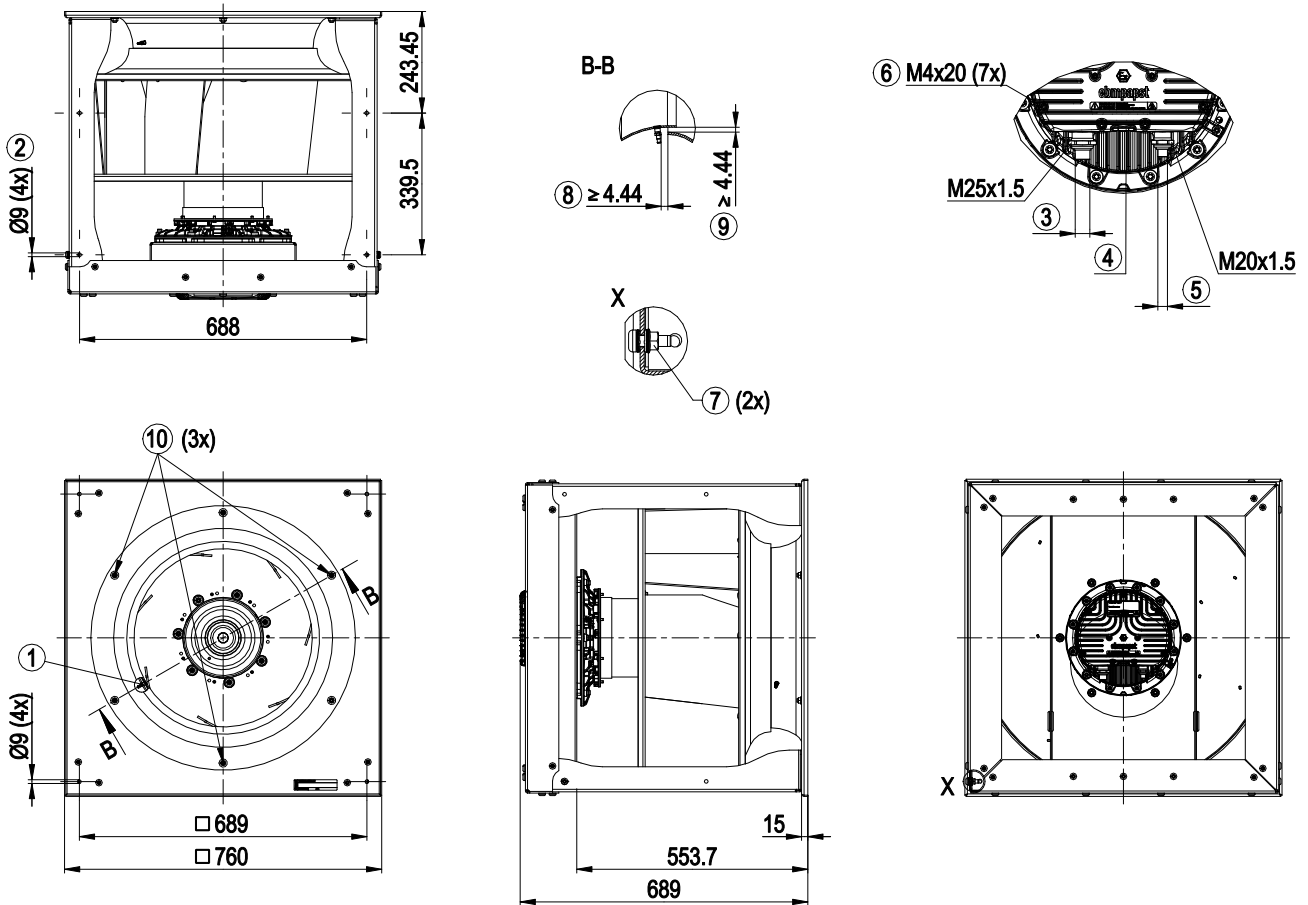
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## Product drawing



1	Inlet ring with pressure tap
2	Mounting position for vibration-absorbing elements
3	Cable diameter min. 10 mm, max. 16 mm, tightening torque $6 \pm 0.6$ Nm; standard value depending on cable
4	Screw plug M20 x 1.5
5	Cable diameter min. 10 mm, max. 14 mm, tightening torque $6 \pm 0.6$ Nm; standard value depending on cable
6	Terminal box fastening screws, tightening torque $3.5 \pm 0.5$ Nm
7	Ground connection point M8 (functional ground for electrostatic discharge, no protective earth), do not unfasten the nut provided, contact is established by way of another nut.
8	Axial gap dimension
9	Radial gap dimension
10	Fastening points for the optionally available guard grill (78138-2-4039 (guard grill); 79630-2-4039 (mesh guard grill))

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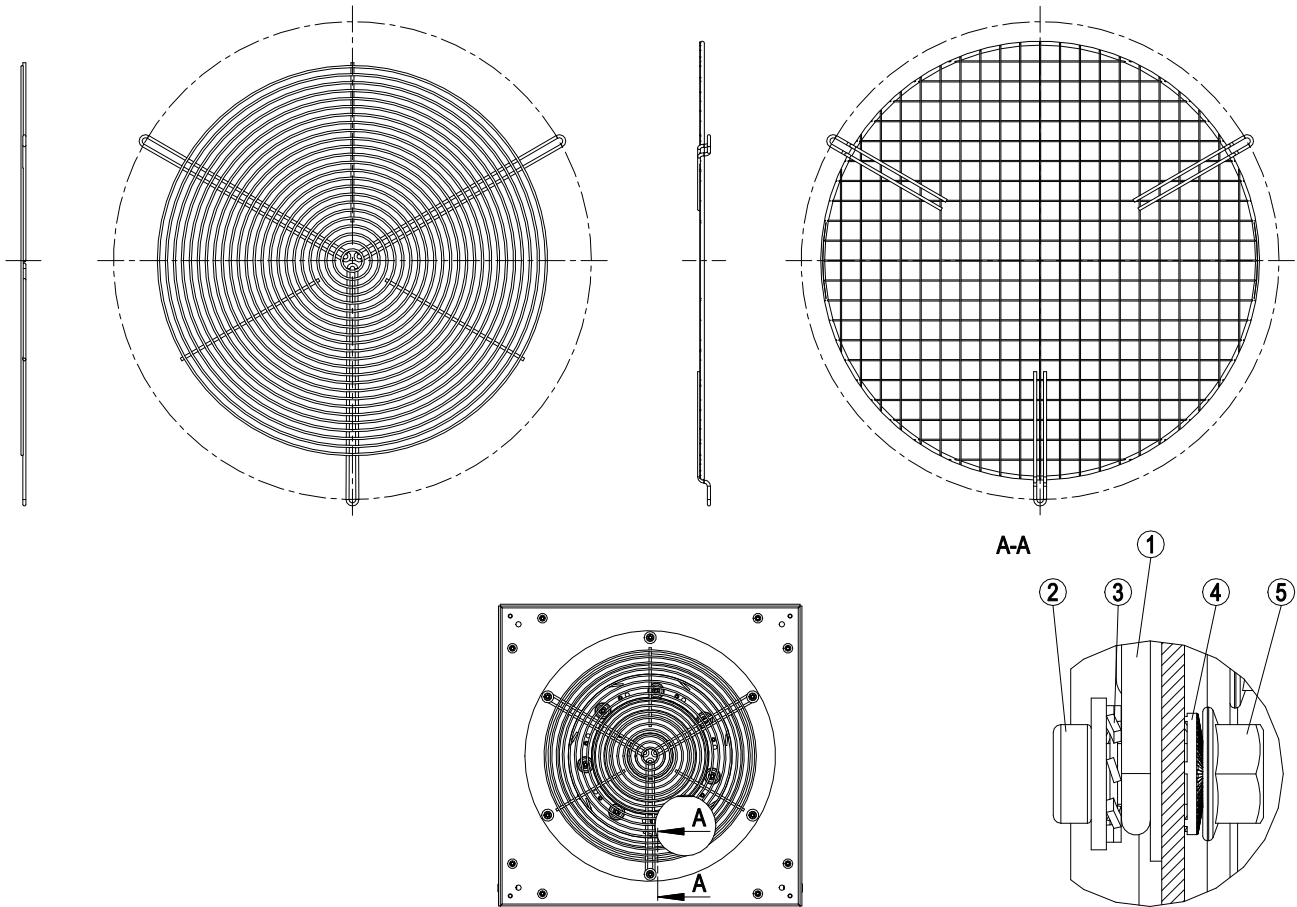
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## Accessory part



This drawing shows how to install the guard grille with the article numbers specified in the product drawing. The necessary bolts, nuts and washers are available from ebm-papst.

- |   |   |
|---|---|
| 1 | Guard grill for protection against accidental contact (ring- or mesh guard grill version, depending on scope of delivery) |
| 2 | Bolt M8x18 micro-encapsulated   |
| 3 | Toothed lock washer   |
| 4 | Contact washer (only necessary on one screw, only with painted housing)   |
| 5 | Nut M8  |

Attention! To mount the guard grill, only loosen and unscrew the three screws marked in the product drawing.

The other bolts must not be loosened!

Used screws and nuts must be disposed of.

Use the fastening components available from ebm-papst for assembly.

If the housing is painted, the contact washer (4) must also be inserted between the housing and the nut for one screw.

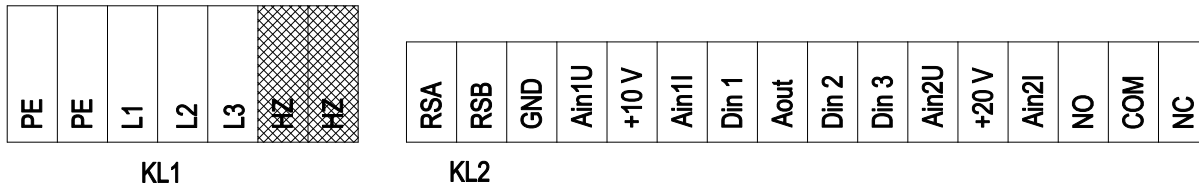
Tighten the bolts to a torque of  $20 \text{ Nm} \pm 3 \text{ Nm}$ .

If a guard grille other than that specified in the product drawing is installed, the operator must ensure proper installation according to the ATEX directive.

In particular, it must be ensured that the necessary distance from rotating parts is observed and that static charge that arises is safely dissipated. If you have any questions, please contact ebm-papst.



## Connection diagram



Shaded => terminals not used

No.	Conn.	Designation	Function/assignment
1		PE	Ground connection, PE connection
1		L1	Supply connection, power supply 3-phase 380-440 VAC, 50/60 Hz
1		L2	Supply connection, power supply 3-phase 380-440 VAC, 50/60 Hz
1		L3	Supply connection, power supply 3-phase 380-440 VAC, 50/60 Hz
1		HZ	not used (optional: internal heating element)
2		RSA	Bus connection RS485, RSA, MODBUS RTU; double terminal point (SELV)
2		RSB	Bus connection RS485, RSB, MODBUS RTU; double terminal point (SELV)
2		GND	Reference ground for control interface (SELV)
2		Ain1 U	Analog input 1, set value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain1 I; SELV
2		+10 V	Fixed voltage output 10 VDC, +10 V ±3%, max. 10 mA, short-circuit-proof power supply for external devices (e.g. pot); SELV
2		Ain1 I	Analog input 1, set value: 4-20 mA, Ri = 100 Ω, adjustable curve, only usable as alternative to input Ain1 U; SELV
2		Din 1	Digital input 1: enable electronics, enable: pin open or applied voltage 5-50 VDC disable: bridge to GND or applied voltage < 1 VDC reset function: triggers software reset after a level change to < 1 VDC; SELV
2		Aout	Analog output 0-10 VDC, max. 5 mA, output of current motor modulation level / motor speed adjustable curve; SELV
2		Din 2	Digital input 2: Switching parameter sets 1/2, according to EEPROM setting, the valid or used parameter set can be selected via bus or via digital input DIN2. Parameter set 1: pin open or applied voltage 5-50 VDC Parameter set 2: bridge to GND or applied voltage < 1 VDC; SELV
2		Din 3	Digital input 3: Direction of action of integrated controller, according to EEPROM setting, the direction of action of the integrated controller can be selected as normal/inverse via bus or digital input Normal: Pin open or applied voltage 5-50 VDC Inverse: Bridge to GND or applied voltage < 1 VDC; SELV
2		Ain2 U	Analog input 2, measured value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain2 I; SELV
2		+20 V	Fixed voltage output 20 VDC, +20 V +25/-10%, max. 50 mA, short-circuit-proof power supply for external devices (e.g. sensors); SELV or: +24 VDC input for parameter setting via MODBUS without line voltage
2		Ain2 I	Analog input 2, measured value: 4-20 mA, Ri = 100 Ω, adjustable curve, only usable as alternative to input Ain2 U; SELV
2		NO	Status relay, floating status contact; make for failure
2		COM	Status relay, floating status contact, common connection, contact rating 250 VAC / max. 2 A (AC1) / min. 10 mA

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No.	Conn.	Designation	Function/assignment
2		NC	Status relay; floating status contact, break for failure

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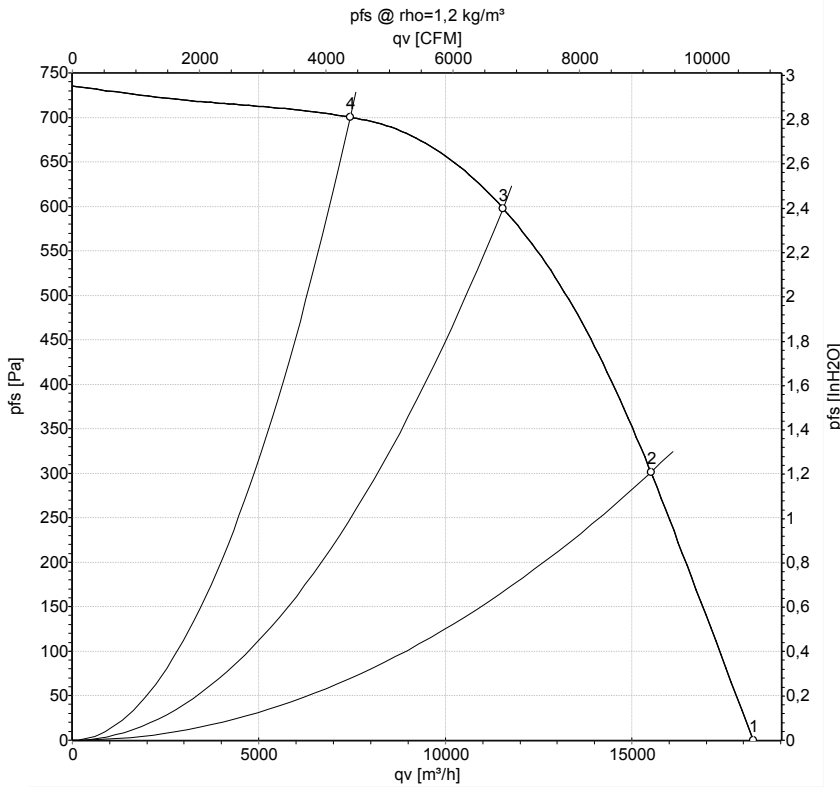
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## Curves: Air performance 50 Hz



Measurement: LU-161868-1  
Date: 2014-03-27  
Nozzle: 96375-2-4013

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

## Measured values

	Wired	U	f	n	P <sub>ed</sub>	I	LpA <sub>in</sub>	LwA <sub>in</sub>	LwA <sub>out</sub>	q <sub>v</sub>	p <sub>fs</sub>	q <sub>v</sub>	p <sub>fs</sub>
		V	Hz	min <sup>-1</sup>	W	A	dB(A)	dB(A)	dB(A)	m <sup>3</sup> /h	Pa	cfm	in. wg
1	Y	400	50	1130	1896	2.93	81	90	94	18240	0	10735	0.00
2	Y	400	50	1130	2513	3.87	76	84	89	15505	300	9125	1.20
3	Y	400	50	1130	2970	4.60	74	83	89	11540	600	6795	2.41
4	Y	400	50	1130	2544	3.93	73	82	88	7445	700	4380	2.81

Wired = Wiring · U = Voltage · f = Frequency · n = Speed (rpm) · P<sub>ed</sub> = Power consumption · I = Current draw · LpA<sub>in</sub> = Sound pressure level intake side · LwA<sub>in</sub> = Sound power level intake side  
LwA<sub>out</sub> = Sound power level outlet side · q<sub>v</sub> = Air flow · p<sub>fs</sub> = Pressure increase