K3G630-AO06-03

EC centrifugal module

backward curved, single inlet

with support bracket

K3G630-AO06-03 ebmpapst Datasheet
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ErP2015 EXCEEDS THE NORM

Nominal data

Type	**K3G630-AO06-03**	
Motor	**M3G150-IF**	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
State		prelim.
Speed	min^{-1}	1050
Power input	W	2500
Current draw	A	3.9
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	40

ml = max. load · me = max. efficiency · fa = running at free air · cs = customer specs · cu = customer unit
Subject to alterations

Data according to ErP directive

Installation category	A
Efficiency category	Static
Variable speed drive	Yes
Specific ratio*	1.01

* Specific ratio = 1 + p_{fs} / 100 000 Pa

		Actual	Request 2013	Request 2015
Overall efficiency η_{es}		64.6	51.6	55.6
Efficiency grade N		71	58	62
Power input P_{ed}	kW	2.48		
Air flow q_v	m^3/h	11130		
Pressure increase p_{fs}	Pa	490		
Speed n	min^{-1}	1055		

Data established at point of optimum efficiency

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Technical features

Mass	54.5 kg
Size	630 mm
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium
Material of impeller	Aluminium sheet
Material of mounting plate	Sheet steel, hot-dip galvanised
Material of support bracket	Steel, coated in black
Material of inlet nozzle	Sheet steel, hot-dip galvanised
Number of blades	7
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP 54
Insulation class	"F"
Humidity class	F4-1
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Rotor on bottom
Condensate discharge holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- PFC, passive - Control input 0-10 VDC / PWM - Over-temperature protected electronics / motor - Alarm relay - Integrated PID controller - Input for sensor 0-10 V or 4-20 mA - Output for slave 0-10 V - RS485 ebmBUS - Motor current limit - Soft start - Line undervoltage / phase failure detection - Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA
EMC interference immunity	Acc. to EN 61000-6-2
EMC interference emission	Acc. to EN 61000-6-3
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical leads	Via terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE
Approval	VDE; UL 1004-1; CSA C22.2 Nr.77

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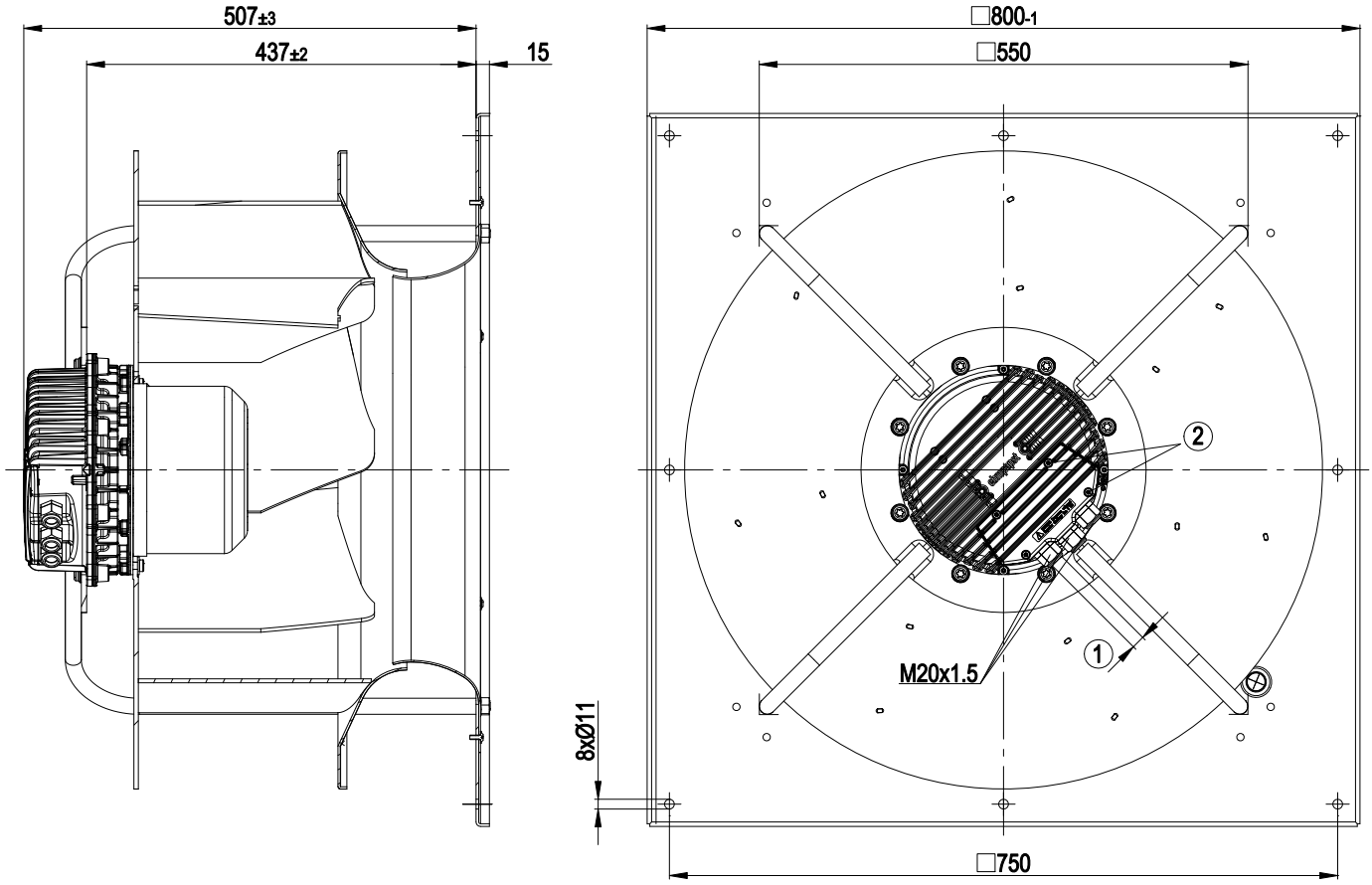
Product drawing



1	Cable diameter: min. 4 mm, max. 10 mm, tightening torque: 4±0.6 Nm
2	Tightening torque 3.5±0.5 Nm

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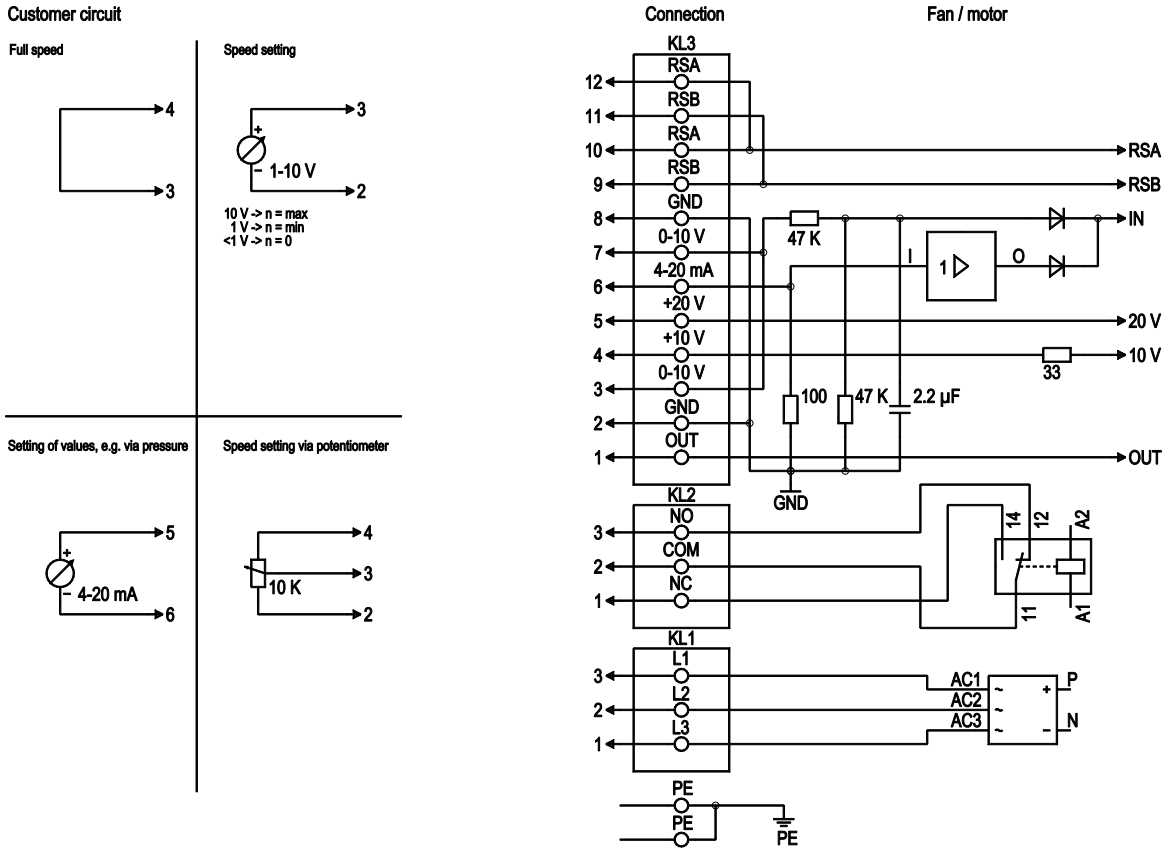
Connection screen



No.	Pin	Signal	Function / assignment
PE		PE	Protective earth connection
KL1	1, 2, 3	L1, L2, L3	Supply voltage, 50/60 Hz
KL2	1	NC	Floating status message contact, normally closed connection
KL2	2	COM	Floating status message contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status message contact, normally open connection
KL3	1	OUT	Analog output, 0-10 VDC, max. 3 mA, SELV, output of the current level control coefficient: 1 V equates to 10 % level control coefficient. 10 V equate to 100 % level control coefficient.
KL3	2, 8	GND	Reference mass for control interface, SELV
KL3	3, 7	0-10 V	Use control / actual value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (+/-3 %), max. 10 mA, supply voltage for ext. devices (e.g. potentiometers), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25 %/-10 %), max. 50 mA, supply voltage for ext. devices (e.g. sensors), SELV
KL3	6	4-20 mA	Use control / actual value input 4-20 mA, impedance 100 Ω, only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for ebmBus, RSB, SELV
KL3	10, 12	RSA	RS485 interface for ebmBus, RSA, SELV

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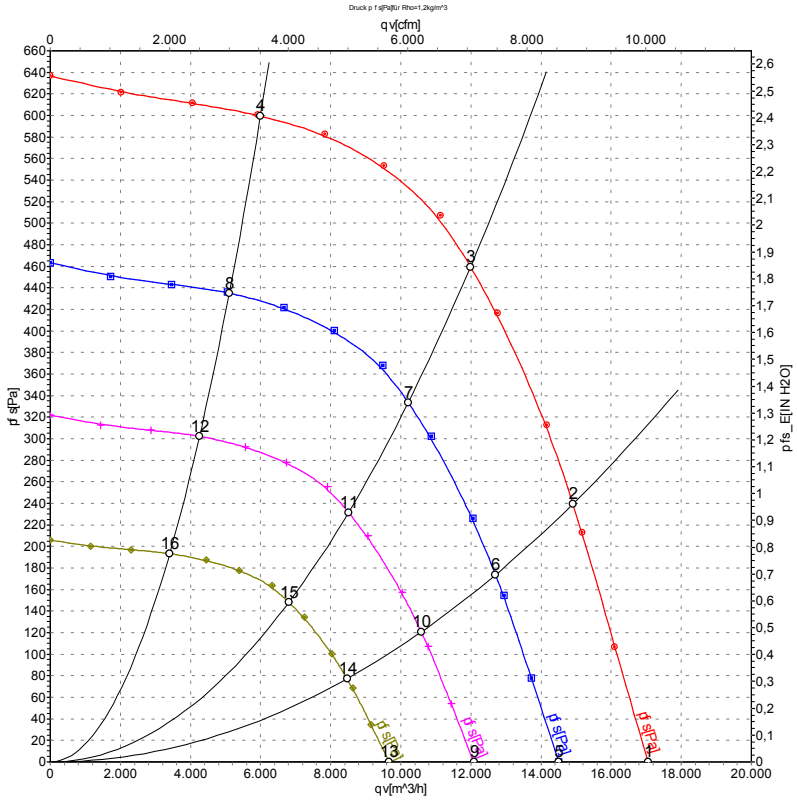
Charts: Air flow 50 Hz



Measurement: LU-113165

Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebm-papst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

Measured values

	Conn.	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	qv	p_{fs}
		V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa
1	Y	400	50	1050	1664	2.57	77	86	92	17050	0
2	Y	400	50	1050	2159	3.29	72	80	86	14910	240
3	Y	400	50	1050	2500	3.90	68	76	82	11990	460
4	Y	400	50	1050	1946	2.96	69	77	84	5995	600
5	Y	400	50	900	1024	1.59	74	82	88	14500	0
6	Y	400	50	900	1335	2.03	68	76	82	12700	174
7	Y	400	50	900	1540	2.33	65	73	78	10210	333
8	Y	400	50	900	1204	1.83	66	73	81	5110	436
9	Y	400	50	750	593	0.92	70	78	84	12090	0
10	Y	400	50	750	772	1.18	64	72	79	10580	121
11	Y	400	50	750	891	1.35	61	69	74	8510	232
12	Y	400	50	750	697	1.06	62	70	77	4255	303
13	Y	400	50	600	304	0.47	65	74	79	9670	0
14	Y	400	50	600	396	0.60	59	68	74	8465	77
15	Y	400	50	600	456	0.69	56	64	70	6805	148
16	Y	400	50	600	357	0.54	57	65	72	3405	194

Conn. = Connection · U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Power input · I = Current draw · LpA_{in} = Sound pressure level inlet side · LwA_{in} = Sound power level inlet side LwA_{out} = Sound power level outlet side · qv = Air flow · p_{fs} = Pressure increase