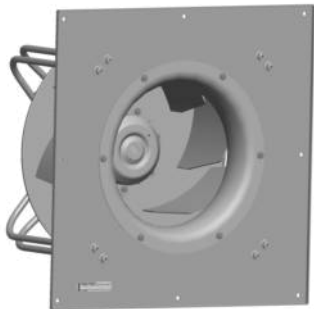


EC centrifugal module - Plug fan

backward curved, single inlet
with support bracket



K3G560-AQ04-03 ebmpapst Datasheet
sales@fansco.com
www.fansco.com

Nominal data

Type	K3G560-AQ04-03	
Motor	M3G150-NA	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
Speed	min ⁻¹	1750
Power input	W	4700
Current draw	A	7.3
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	40

ml = max. load · me = max. efficiency · fa = running at free air · cs = customer specs · cu = customer unit
Subject to alterations

Data according to ErP directive

Installation category	A
Efficiency category	Static
Variable speed drive	Yes
Specific ratio*	1.01

* Specific ratio = 1 + p_{fs} / 100 000 Pa

	Actual	Request 2013	Request 2015
Overall efficiency η_{es}	67.2	54.5	58.5
Efficiency grade N	70.7	58	62
Power input P _{ed}	kW	4.67	
Air flow q _v	m ³ /h	11640	
Pressure increase p _{fs}	Pa	934	
Speed n	min ⁻¹	1765	

Data established at point of optimum efficiency



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Technical features

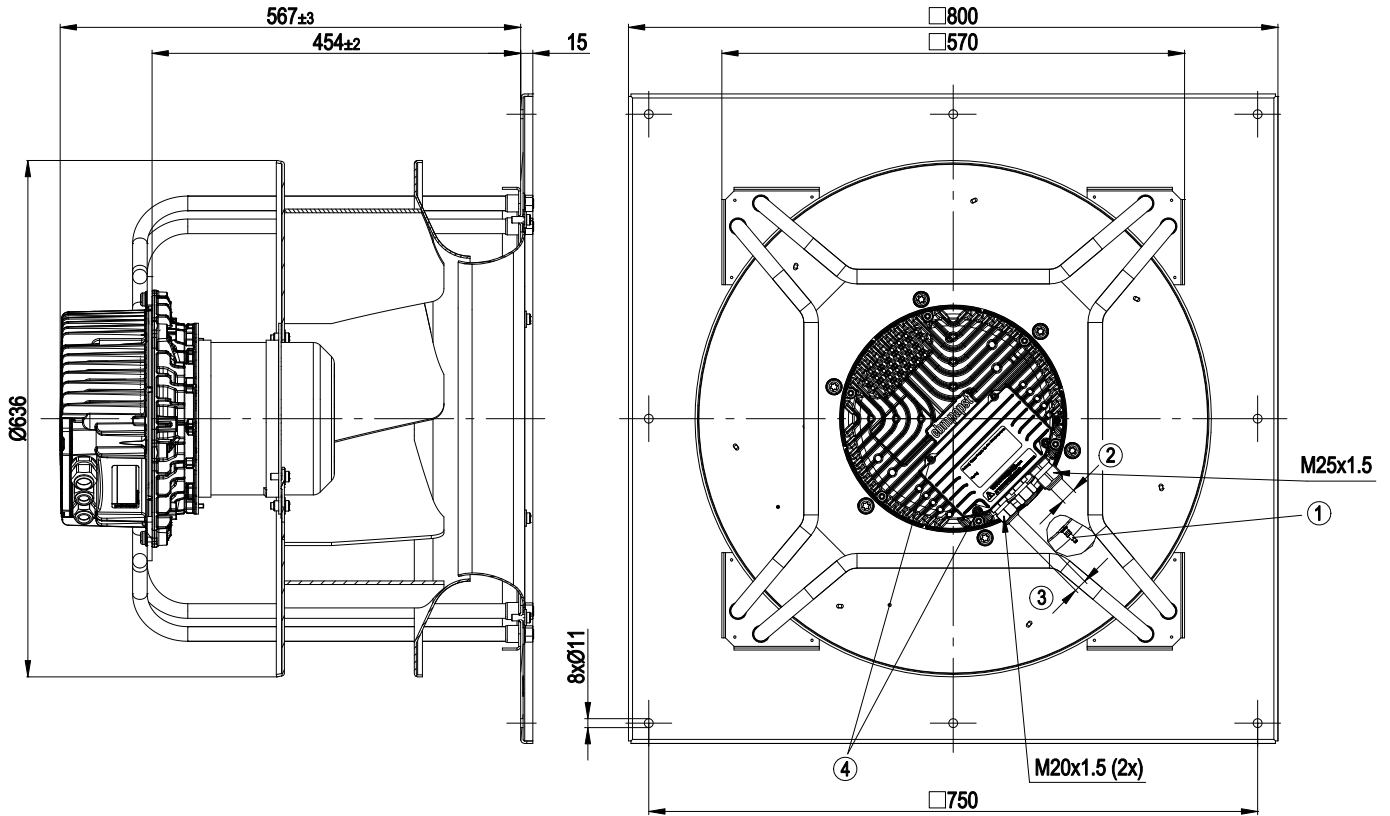
Mass	68.4 kg
Size	560 mm
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium
Material of impeller	Aluminium sheet
Material of mounting plate	Sheet steel, hot-dip galvanised
Material of support bracket	Steel, coated in black
Material of inlet nozzle	Sheet steel, hot-dip galvanised
Number of blades	7
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP 54
Insulation class	"F"
Humidity class	F4-1
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Shaft horizontal or rotor on bottom
Condensate discharge holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- PFC, passive - Control input 0-10 VDC / PWM - Output 10 VDC, max. 10 mA - Over-temperature protected electronics / motor - Alarm relay - Integrated PID controller - Input for sensor 0-10 V or 4-20 mA - Output for slave 0-10 V - RS485 ebmBUS - Motor current limit - Soft start - Line undervoltage / phase failure detection - Output 20 VDC, max. 50 mA
EMC interference immunity	Acc. to EN 61000-6-2 (industrial environment)
EMC interference emission	Acc. to EN 61000-6-3 (household environment)
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical leads	Via terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE



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Product drawing



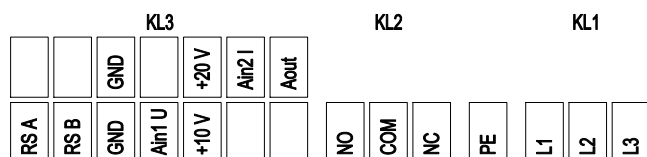
1	Inlet nozzle with bleeder connection for pressure relief (k-factor: 348)
2	Cable diameter: min. 9 mm, max. 16 mm; tightening torque: 6 ± 0.9 Nm
3	Cable diameter: min. 4 mm, max. 10 mm; tightening torque: 4 ± 0.6 Nm
4	Tightening torque 3.5 ± 0.5 Nm

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Connection screen

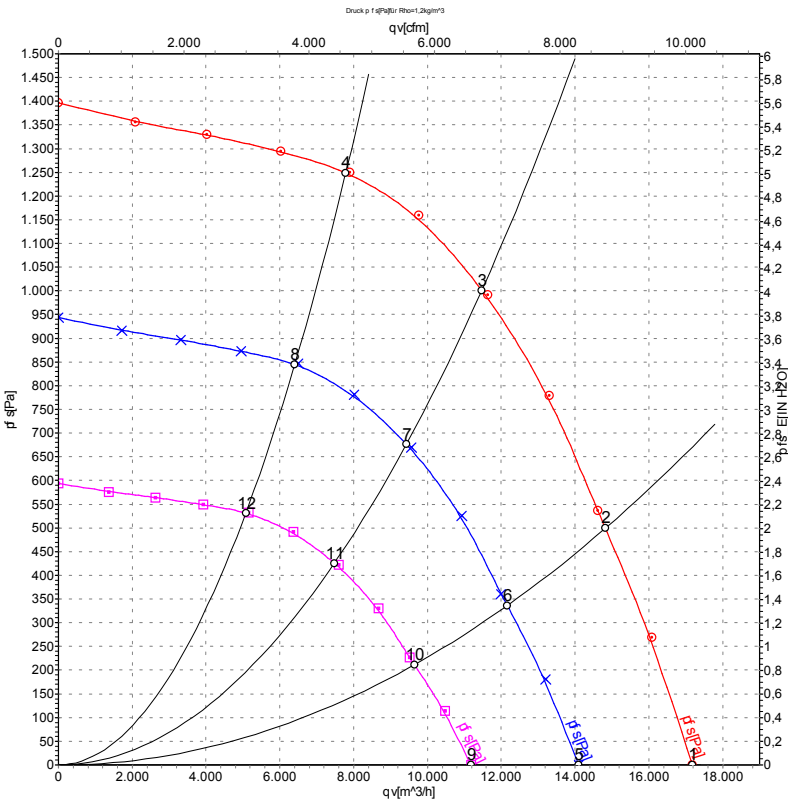


No.	Pin	Signal	Function / assignment
PE		PE	Ground wire
KL1		L3	Power line, L3
KL1		L2	Power line, L2
KL1		L1	Power line, L1
KL2		NC	Alarm relay, normally closed connection
KL2		COM	Alarm relay, COMMON (2 A, 250 VAC, AC1)
KL2		NO	Alarm relay, normally open connection
KL3		+10 V	Supply for external potentiometer, 10 VDC(+/-3 %) max. 10 mA
KL3		Ain1U	Analogue set value input, 0-10 V (impedance 100 kΩ), can be used as an alternative to connection Ain2 I only
KL3		GND	GND
KL3		RSB	RS485 interface for ebmBus, RS B
KL3		RSA	RS485 interface for ebmBus, RS A
KL3		Aout	Analog output 0-10 V max. 5 mA, output of the current level control coefficient
KL3		Ain2 I	Analogue actual value input, 4-20 mA (impedance 100 Ω), can be used only as an alternative to connection Ain1 U only
KL3		+20 V	Supply for external sensor, 20 VDC (+25 %/-10 %) max. 40 mA
KL3		GND	GND

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Charts: Air flow 50 Hz



Measurement: LU-128639

Air performance measured as per ISO 5801
Installation category A. For detailed
information on the measuring set-up, please
contact ebm-papst. Suction-side noise
levels: LwA measured as per ISO 13347 /
LpA measured with 1m distance to fan axis.
The values given are valid under the
measuring conditions mentioned above and
may vary according to the actual installation
situation. With any deviation from the
standard set-up, the specific values have to
be checked and reviewed with the unit
installed.

Measured values

	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	LwA _{out}	qv	p _{fs}
	V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m ³ /h	Pa
1	400	50	1750	3032	4.77	88	97	103	17170	0
2	400	50	1750	3929	6.10	84	91	96	14820	500
3	400	50	1750	4700	7.30	78	84	91	11470	1000
4	400	50	1750	4366	6.71	79	86	92	7785	1250
5	400	50	1450	1675	2.64	84	93	98	14090	0
6	400	50	1450	2171	3.37	80	87	92	12160	336
7	400	50	1450	2602	4.01	74	80	86	9430	681
8	400	50	1450	2432	3.74	75	82	88	6405	848
9	400	50	1150	836	1.32	79	88	93	11180	0
10	400	50	1150	1083	1.68	75	82	87	9650	211
11	400	50	1150	1298	2.00	68	75	81	7480	428
12	400	50	1150	1213	1.87	70	76	83	5080	534

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Power input · I = Current draw · LpA_{in} = Sound pressure level inlet side · LwA_{in} = Sound power level inlet side · LwA_{out} = Sound power level outlet side
qv = Air flow · p_{fs} = Pressure increase

