

EC centrifugal module - RadiPac

backward curved, single inlet

with support bracket

K3G500-PA23-75 ebmpapst Datasheet

sales@fansco.com

www.fansco.com

Limited partnership · Headquarters Mulfingen
County court Stuttgart · HRA 590344

General partner Elektrobau Mulfingen GmbH · Headquarters Mulfingen
County court Stuttgart · HRB 590142

Nominal data

Type	K3G500-PA23-75	
Motor	M3G150-FF	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
Speed (rpm)	min ⁻¹	1910
Power input	W	3450
Current draw	A	5.3
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	40

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations

Data according to ErP directive

		Actual	Request 2015			
01 Overall efficiency η_{es}	%	68.7	57.2	09 Power input P_{ed}	kW	3.46
02 Measurement category		A		09 Air flow q_v	m ³ /h	8740
03 Efficiency category		Static		09 Pressure increase p_{fs}	Pa	929
04 Efficiency grade N		73.5	62	10 Speed (rpm) n	min ⁻¹	1910
05 Variable speed drive		Yes		11 Specific ratio [*]		1.01

Data definition with optimum efficiency.
The ErP data is determined using a motor-impeller combination in a standardised measurement configuration.

^{*} Specific ratio = $1 + p_{fs} / 100\,000\text{ Pa}$

LU-173866



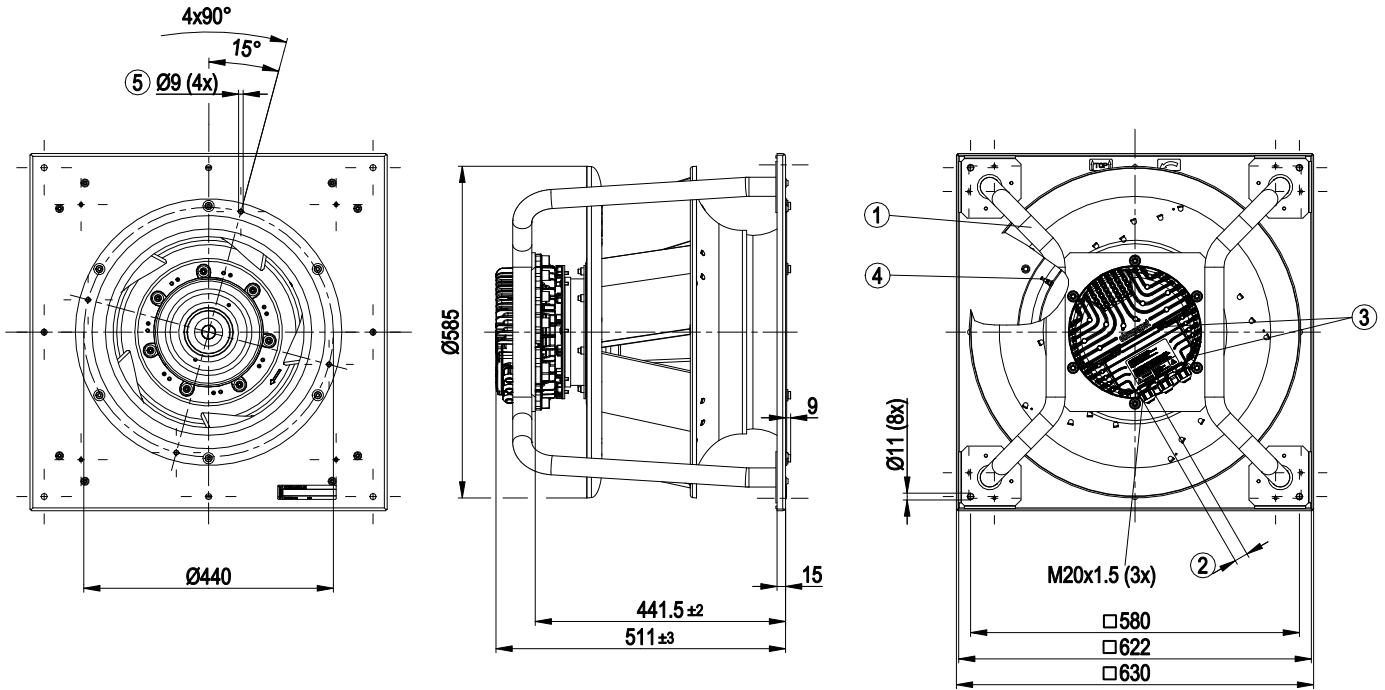
Technical features

Mass	38 kg
Size	500 mm
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium
Material of impeller	Aluminium sheet
Material of mounting plate	Sheet steel, galvanised
Material of support bracket	Steel, coated in black
Material of inlet nozzle	Sheet steel, galvanised
Number of blades	5
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP 55
Insulation class	"F"
Humidity (F)/environmental protection class (H)	H1
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Refer to product drawing
Condensate discharge holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	<ul style="list-style-type: none"> - Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (programming) - External release input - Integrated PID controller - Motor current limit - PFC, passive - RS485 MODBUS RTU - Soft start -Maximum EEPROM write cycles 100,000 - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection
EMC interference immunity	Acc. to EN 61000-6-2 (industrial environment)
EMC interference emission	Acc. to EN 61000-6-4 (industrial environment)
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical leads	Via terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE
Approval	EAC

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Product drawing



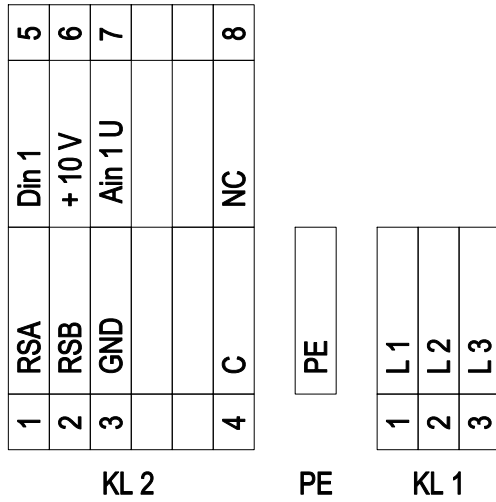
1	Installation position: Shaft horizontal (install the support struts only vertically as shown in the illustration!) or rotor on bottom; rotor on top on request
2	Cable diameter min. 4 mm, max. 10 mm, tightening torque 4 ± 0.6 Nm
3	Tightening torque 3.5 ± 0.5 Nm
4	Inlet nozzle with pressure tap (k-factor: 281)
5	Mounting holes for FlowGrid



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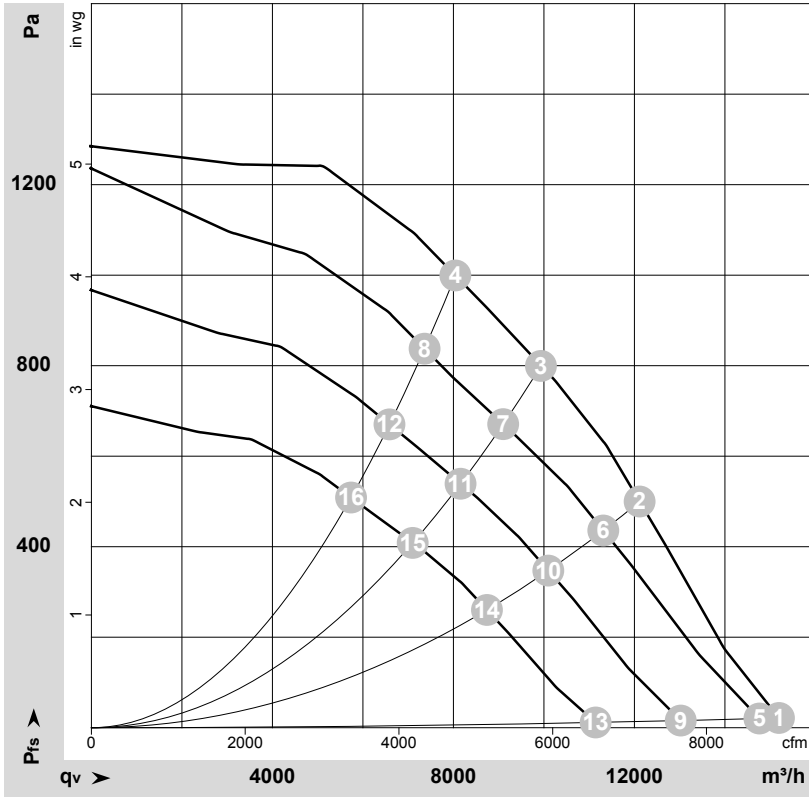
Connection screen



No.	Conn.	Designation	Function / assignment
KL 1	1	L1	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
KL 1	2	L2	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
KL 1	3	L3	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
PE		PE	Earth connection, PE connection
KL 2	1	RSA	Bus connection RS-485, RSA, MODBUS RTU; SELV
KL 2	2	RSB	Bus connection RS-485, RSB, MODBUS RTU; SELV
KL 2	3	GND	Signal ground for control interface; SELV
KL2	4	C	Status relay; floating status contact; changeover contact; common connection; contact rating 250 VAC / 2 A (AC1)
KL 2	5	Din1	Digital input 1 enabling of electronics, enabling: open pin or applied voltage 5-50 VDC disabling: bridge to GND or applied voltage <1 VDC reset function: triggers software reset after a level change to <1 V; SELV
KL 2	6	+ 10 V	Fixed voltage output 10 VDC; +10 V -3 %, max. 10 mA, short-circuit-proof, power supply for external devices (e.g. potentiometer); SELV Alternative: +24 VDC input for parametrisation via MODBUS without mains power
KL 2	7	Ain1 U	Analogue input 1 (set value) 0-10 V, Ri=100 kΩ, parametrisable curve; SELV
KL2	8	NC	Status relay, floating status contact; break for failure



Charts: Air flow 50 Hz



$\rho = 1.15 \text{ kg/m}^3 \pm 2 \%$

Measurement: LU-173866-1

Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebmpapst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

Measured values

	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	LwA _{out}	q _v	P _{fs}	q _v	P _{fs}
	V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m ³ /h	Pa	cfm	inH ₂ O
1	400	50	1910	1980	3.09	94	102	102	15200	0	8945	0.00
2	400	50	1910	2920	4.49	84	92	93	12115	500	7130	2.01
3	400	50	1910	3380	5.19	78	86	88	9930	800	5845	3.21
4	400	50	1910	3450	5.30	76	83	87	8050	1000	4740	4.01
5	400	50	1870	1818	2.86	93	101	101	14760	0	8690	0.00
6	400	50	1785	2367	3.67	84	91	92	11310	436	6660	1.75
7	400	50	1750	2598	4.01	77	83	86	9100	671	5355	2.69
8	400	50	1750	2616	4.04	74	81	85	7365	838	4335	3.36
9	400	50	1655	1287	2.09	92	98	98	13025	0	7665	0.00
10	400	50	1595	1705	2.70	81	87	89	10095	347	5945	1.39
11	400	50	1570	1872	2.94	73	81	84	8160	539	4800	2.16
12	400	50	1565	1893	2.97	71	78	83	6585	670	3875	2.69
13	400	50	1425	832	1.46	85	94	95	11145	0	6560	0.00
14	400	50	1385	1117	1.85	75	83	86	8740	260	5145	1.04
15	400	50	1365	1241	2.03	69	77	80	7100	409	4180	1.64
16	400	50	1365	1247	2.04	68	74	79	5740	509	3375	2.04

U = Supply voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power input · I = Current draw · LpA_{in} = Sound pressure level inlet side · LwA_{in} = Sound power level inlet side · LwA_{out} = Sound power level outlet side
q_v = Air flow · P_{fs} = Pressure increase

