

K3G500-AQ34-19

# EC centrifugal module

backward curved, single inlet  
with support bracket



K3G500-AQ34-19 ebmpapst Datasheet  
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## Nominal data

Type	K3G500-AQ34-19	
Motor	M3G150-IF	
Phase		3~
Nominal voltage	VAC	200
Nominal voltage range	VAC	200 .. 240
Frequency	Hz	50/60
Type of data definition		ml
State		prelim.
Speed	min <sup>-1</sup>	2200
Power input	W	5400
Current draw	A	16.5
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	40

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit  
Subject to alterations



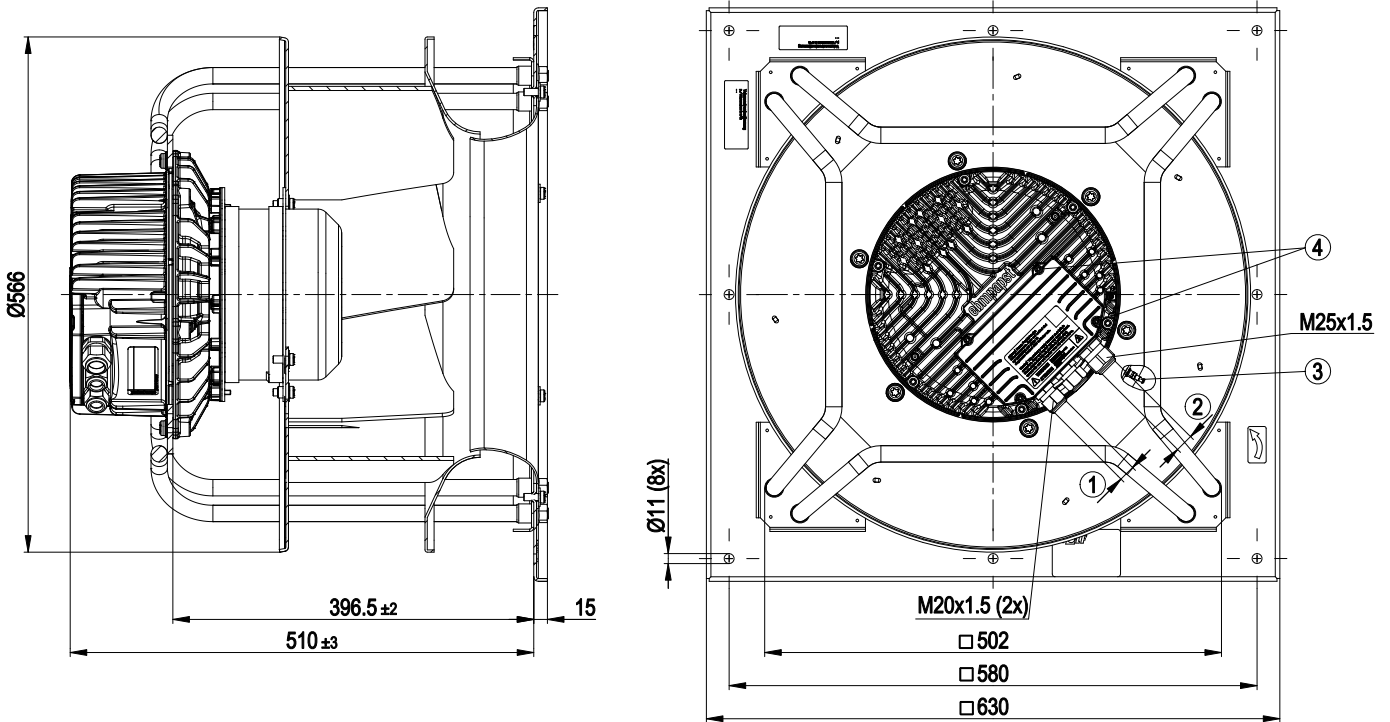
## Technical features

Mass	55.9 kg
Size	500 mm
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium
Material of impeller	Aluminium sheet
Material of mounting plate	Sheet steel, galvanised
Material of support bracket	Steel, coated in black
Material of inlet nozzle	Sheet steel, galvanised
Number of blades	7
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP 54
Insulation class	"F"
Humidity class	F4-1
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensate discharge holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	<ul style="list-style-type: none"> <li>- Output 10 VDC, max. 10 mA</li> <li>- Output 20 VDC, max. 50 mA</li> <li>- Output for slave 0-10 V</li> <li>- Input for sensor 0-10 V or 4-20 mA</li> <li>- External 24 V input (programming)</li> <li>- External release input</li> <li>- Alarm relay</li> <li>- Integrated PID controller</li> <li>- Motor current limit</li> <li>- PFC, passive</li> <li>- RS485 MODBUS RTU</li> <li>- Soft start</li> <li>- Control input 0-10 VDC / PWM</li> <li>- Control interface with SELV potential safely disconnected from the mains</li> <li>- Over-temperature protected electronics / motor</li> <li>- Line undervoltage / phase failure detection</li> </ul>
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical leads	Via terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE
Approval	UL 1004-7 + 60730; C22.2 Nr.77 + CAN/CSA-E60730-1

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## Product drawing



1	Cable diameter: min. 4 mm, max. 10 mm; tightening torque: $4 \pm 0.6$ Nm
2	Cable diameter: min. 9 mm, max. 16 mm; tightening torque: $6 \pm 0.9$ Nm
3	Inlet nozzle with bleeder connection for pressure relief (k-factor: 281)
4	Tightening torque $3.5 \pm 0.5$ Nm



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## Connection screen

	8		
	Din 2		
	9		
	Din 3		
	10		
	GND		
	11		
	Ain 2 U		
	12		
	+ 20 V		
	13		
	Ain 2 I		
	14		
	Aout		

KL 3

1	NO
2	COM
3	NC

KL 2

PE
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PE

1	L1
2	L2
3	L3

KL 1

No.	Conn.	Designation	Function / assignment
KL 1	1	L1	Mains supply connection, supply voltage 3~200-240 VAC; 50/60 Hz
KL 1	2	L2	Mains supply connection, supply voltage 3~200-240 VAC; 50/60 Hz
KL 1	3	L3	Mains supply connection, supply voltage 3~200-240 VAC; 50/60 Hz
PE		PE	Earth connection, PE connection
KL 2	1	NO	Status relay, floating status contact; normally open; close with error
KL2	2	COM	Status relay; floating status contact; changeover contact; common connection; contact rating 250 VAC / max. 2 A (AC1) / min. 10 mA
KL2	3	NC	Status relay, floating status contact; break with error
KL 3	1	RSA	Bus connection RS-485, RSB, MODBUS RTU; SELV
KL 3	2	RSB	Bus connection RS-485, RSA, MODBUS RTU; SELV
KL 3	3 / 10	GND	Signal ground for control interface; SELV
KL 3	4	Ain1 U	Analogue input 1, set value: 0-10 V, Ri = 100 kΩ, parametrisable curve, only usable as alternative to input Ain1; SELV
KL 3	5	+ 10 V	Fixed voltage output 10 VDC, +10 V ±3%, max. 10 mA, short-circuit-proof, power supply for external devices (e.g. potentiometer), SELV
KL 3	6	Ain1 I	Analogue input 1, set value: 4-20 mA; Ri = 100 Ω, parametrisable curve, only usable as alternative to input Ain1 U; SELV
KL 3	7	Din1	Digital input 1: enabling of electronics, enabling: open pin or applied voltage 5-50 VDC disabling: bridge to GND or applied voltage <1 VDC reset function: triggers software reset after a level change to <1 VDC; SELV
KL 3	8	Din2	Digital input 2: parameter set switch 1/2, according to EEPROM setting, the valid/used parameter set can be selected via bus or via digital input DIN2. Parameter set 1: open pin or applied voltage 5-50 VDC Parameter set 2: bridge to GND or applied voltage <1 VDC; SELV
KL 3	9	Din3	Digital input 3: controller function of integrated controller, according to EEPROM setting, the controller function of the integrated controller is normally/inversely selectable per bus or per digital input normal: open pin or applied voltage 5-50 VDC inverse: bridge to GND or applied voltage <1 VDC; SELV
KL 3	11	Ain2 U	Analogue input 2, actual value: 0-10 V, Ri = 100 kΩ, parametrisable curve, only usable as alternative to input Ain2; SELV
KL 3	12	+ 20 V	Fixed voltage output 20 VDC, +20 V ±25/-10%, max. 50 mA, short-circuit-proof, power supply for external devices (e.g. sensors); SELV



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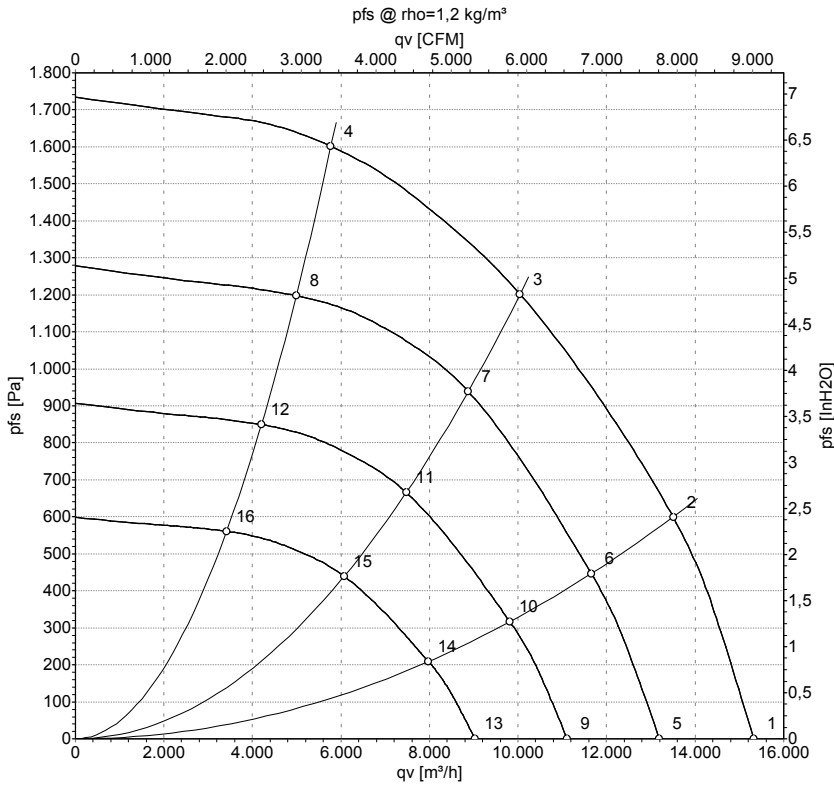
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No.	Conn.	Designation	Function / assignment
KL 3	13	Ain2 I	Analogue input 2, actual value: 4-20 mA, $R_i = 100 \Omega$ , parametrisable curve, only usable as alternative to input Ain2 U; SELV
KL 3	14	Aout	Analogue output 0-10 VDC, max. 5 mA, output of the current motor level control coefficient / motor speed parametrisable curve; SELV



## Charts: Air flow 50 Hz



Measurement: LU-139069

Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebmpapst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

## Measured values

	U	f	n	P <sub>ed</sub>	I	LpA <sub>in</sub>	LwA <sub>in</sub>	LwA <sub>out</sub>	qv	p <sub>fs</sub>
	V	Hz	min <sup>-1</sup>	W	A	dB(A)	dB(A)	dB(A)	m <sup>3</sup> /h	Pa
1	200	50	2200	3789	11.52	92	99	105	15325	0
2	200	50	2200	4865	14.74	87	94	100	13505	600
3	200	50	2200	5400	16.50	81	88	93	10045	1200
4	200	50	2200	4999	15.13	84	91	97	5770	1600
5	200	50	1900	2418	7.35	88	95	101	13190	0
6	200	50	1900	3125	9.47	83	91	96	11655	446
7	200	50	1900	3703	11.21	78	85	90	8875	946
8	200	50	1900	3237	9.80	81	88	93	4990	1198
9	200	50	1600	1444	4.39	83	91	96	11110	0
10	200	50	1600	1866	5.65	79	86	91	9815	317
11	200	50	1600	2211	6.70	73	80	86	7475	671
12	200	50	1600	1933	5.85	76	83	89	4205	849
13	200	50	1300	774	2.35	78	86	91	9025	0
14	200	50	1300	1001	3.03	73	81	86	7975	209
15	200	50	1300	1186	3.59	68	75	81	6075	443
16	200	50	1300	1037	3.14	71	78	83	3415	561

U = Supply voltage · f = Frequency · n = Speed · P<sub>ed</sub> = Power input · I = Current draw · LpA<sub>in</sub> = Sound pressure level inlet side · LwA<sub>in</sub> = Sound power level inlet side · LwA<sub>out</sub> = Sound power level outlet side  
 qv = Air flow · p<sub>fs</sub> = Pressure increase

