

K3G450-AQ06-03

EC centrifugal module - Plug fan

backward curved, single inlet

with support bracket



K3G450-AQ06-03 ebmpapst Datasheet

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Nominal data

Type	K3G450-AQ06-03	
Motor	M3G150-FF	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
Speed	min ⁻¹	2040
Power input	W	2715
Current draw	A	4.1
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	+40

ml = max. load · me = max. efficiency · fa = running at free air · cs = customer specs · cu = customer unit
Subject to alterations

Data according to ErP directive

Installation category	A
Efficiency category	Static
Variable speed drive	Yes
Specific ratio*	1.01

* Specific ratio = $1 + p_{fs} / 100\,000\text{ Pa}$

	Actual	Request 2013	Request 2015
Overall efficiency η_{es}	65.4	52	56
Efficiency grade N	71.4	58	62
Power input P_{ed}	kW	2.71	
Air flow q_v	m ³ /h	6915	
Pressure increase p_{fs}	Pa	875	
Speed n	min ⁻¹	2050	

Data established at point of optimum efficiency



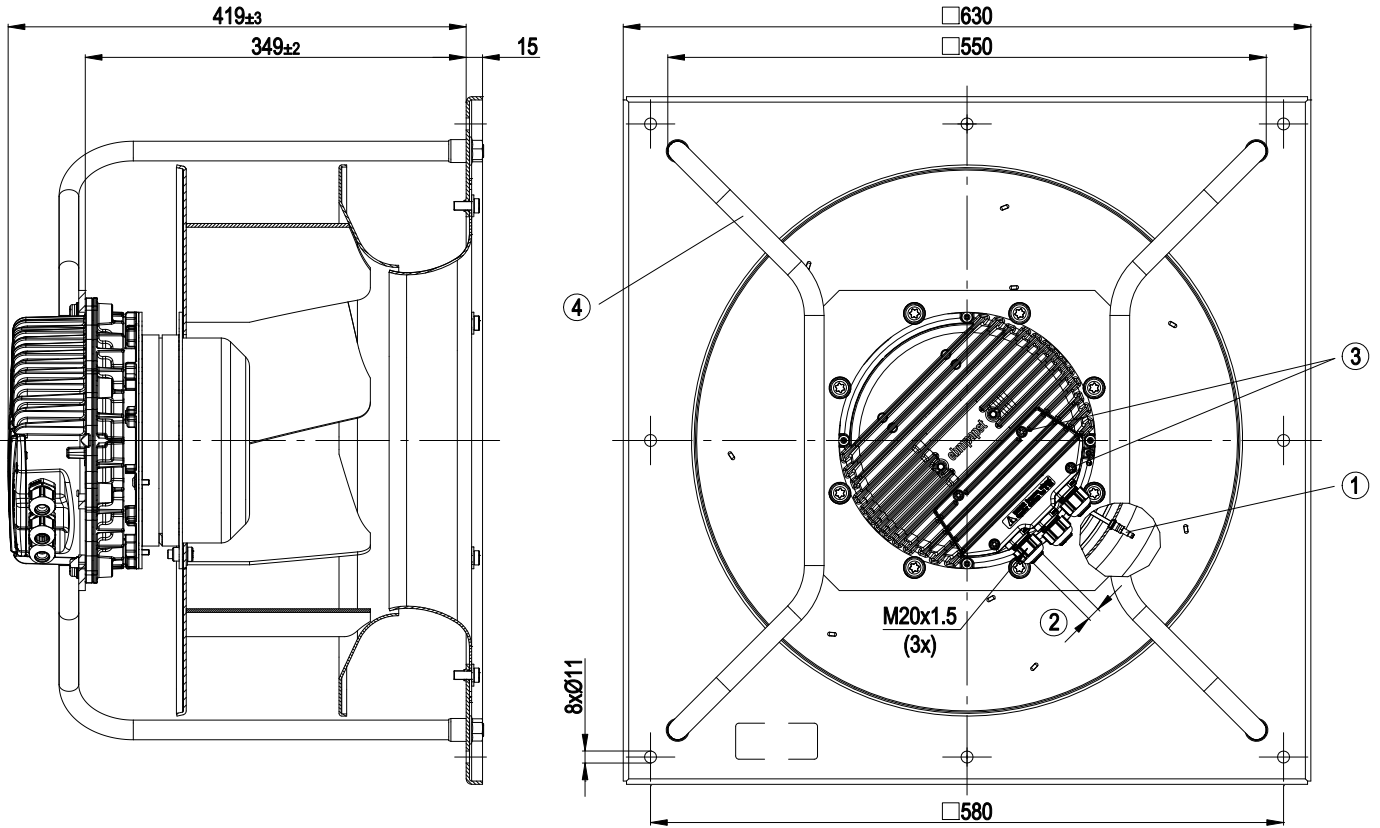
Technical features

Mass	38 kg
Size	450 mm
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium
Material of impeller	Aluminium sheet
Material of mounting plate	Sheet steel, hot-dip galvanised
Material of support bracket	Steel, coated in black
Material of inlet nozzle	Sheet steel, hot-dip galvanised
Number of blades	7
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP 54
Insulation class	"F"
Humidity class	F4-1
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Refer to product drawing
Condensate discharge holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	<ul style="list-style-type: none"> - PFC, passive - Control input 0-10 VDC / PWM - Over-temperature protected electronics / motor - Alarm relay - Integrated PID controller - Input for sensor 0-10 V or 4-20 mA - Output for slave 0-10 V - Output 20 VDC - Output 10 VDC - RS485 ebmBUS - Motor current limit - Soft start - Line undervoltage / phase failure detection
EMC interference immunity	Acc. to EN 61000-6-2 (industrial environment)
EMC interference emission	Acc. to EN 61000-6-3 (household environment)
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical leads	Via terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE
Approval	VDE; UL; GOST; CSA C22.2 Nr.100

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Product drawing



1	Inlet nozzle with bleeder connection for pressure relief (k-factor 240)
2	Cable diameter: min. 4 mm, max. 10 mm, tightening torque: 4±0.6 Nm
3	Tightening torque 3.5±0.5 Nm
4	Mounting position: shaft horizontal (install the support struts only vertically as shown in the view!) or rotor on bottom; rotor on top on request

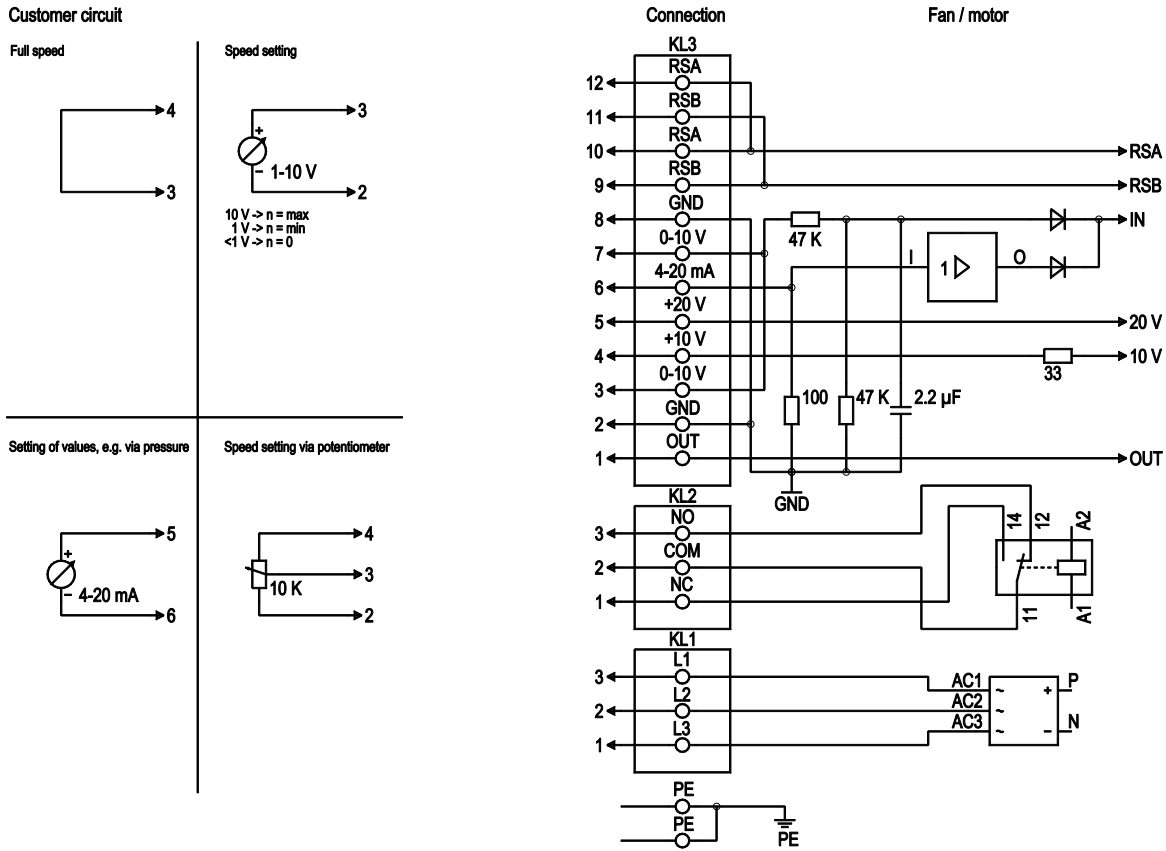


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Connection screen



No.	Pin	Signal	Function / assignment
PE		PE	Protective earth connection
KL1	1, 2, 3	L1, L2, L3	Supply voltage, 50/60 Hz
KL2	1	NC	Floating status message contact, normally closed connection
KL2	2	COM	Floating status message contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status message contact, normally open connection
KL3	1	OUT	Analog output, 0-10 VDC, max. 3 mA, SELV, output of the current level control coefficient: 1 V equates to 10 % level control coefficient. 10 V equate to 100 % level control coefficient.
KL3	2, 8	GND	Reference mass for control interface, SELV
KL3	3, 7	0-10 V	Use control / actual value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (+/-3 %), max. 10 mA, supply voltage for ext. devices (e.g. potentiometers), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25 %/-10 %), max. 50 mA, supply voltage for ext. devices (e.g. sensors), SELV
KL3	6	4-20 mA	Use control / actual value input 4-20 mA, impedance 100 Ω, only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for ebmBus, RSB, SELV
KL3	10, 12	RSA	RS485 interface for ebmBus, RSA, SELV

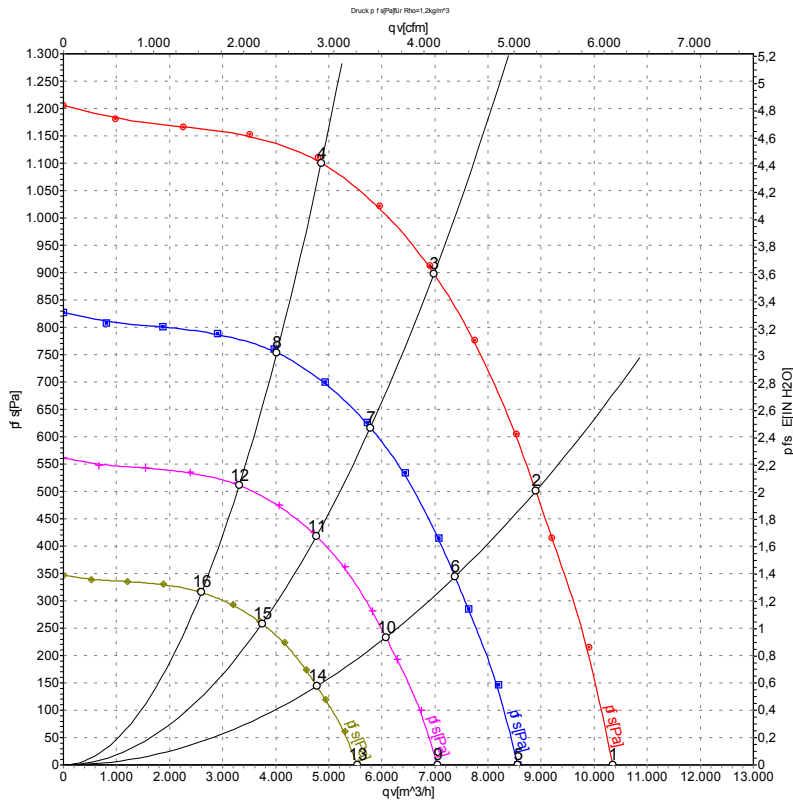


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Charts: Air flow 50 Hz



Measurement: LU-118210

Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebm-papst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

Measured values

	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	LwA _{out}	qv	p _{fs}
	V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m ³ /h	Pa
1	400	50	2040	1783	2.72	85	93	98	10350	0
2	400	50	2040	2339	3.57	78	85	91	8900	500
3	400	50	2040	2715	4.10	75	81	88	6980	900
4	400	50	2040	2569	3.90	77	84	89	4860	1100
5	400	50	1700	1008	1.54	81	89	94	8560	0
6	400	50	1700	1332	2.03	74	81	87	7380	344
7	400	50	1700	1540	2.35	71	77	84	5785	619
8	400	50	1700	1456	2.21	73	80	85	4020	758
9	400	50	1400	563	0.86	77	84	90	7050	0
10	400	50	1400	744	1.13	70	77	83	6075	233
11	400	50	1400	860	1.32	66	73	80	4765	420
12	400	50	1400	813	1.23	69	75	81	3310	514
13	400	50	1100	273	0.42	72	79	84	5540	0
14	400	50	1100	361	0.55	65	72	78	4775	144
15	400	50	1100	417	0.64	61	68	75	3745	259
16	400	50	1100	394	0.60	63	70	76	2600	317

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Power input · I = Current draw · LpA_{in} = Sound pressure level inlet side · LwA_{in} = Sound power level inlet side · LwA_{out} = Sound power level outlet side
 qv = Air flow · p_{fs} = Pressure increase

