

Nominal data

Type	K3G400-HA42-15	
Motor	M3G150-FF	
Phase		3~
Nominal voltage	VAC	200
Nominal voltage range	VAC	200 .. 240
Frequency	Hz	50/60
Method of obtaining data		ml
Status		prelim.
Speed (rpm)	min ⁻¹	3700
Power consumption	W	6400
Current draw	A	19.5
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	50

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment

Subject to change



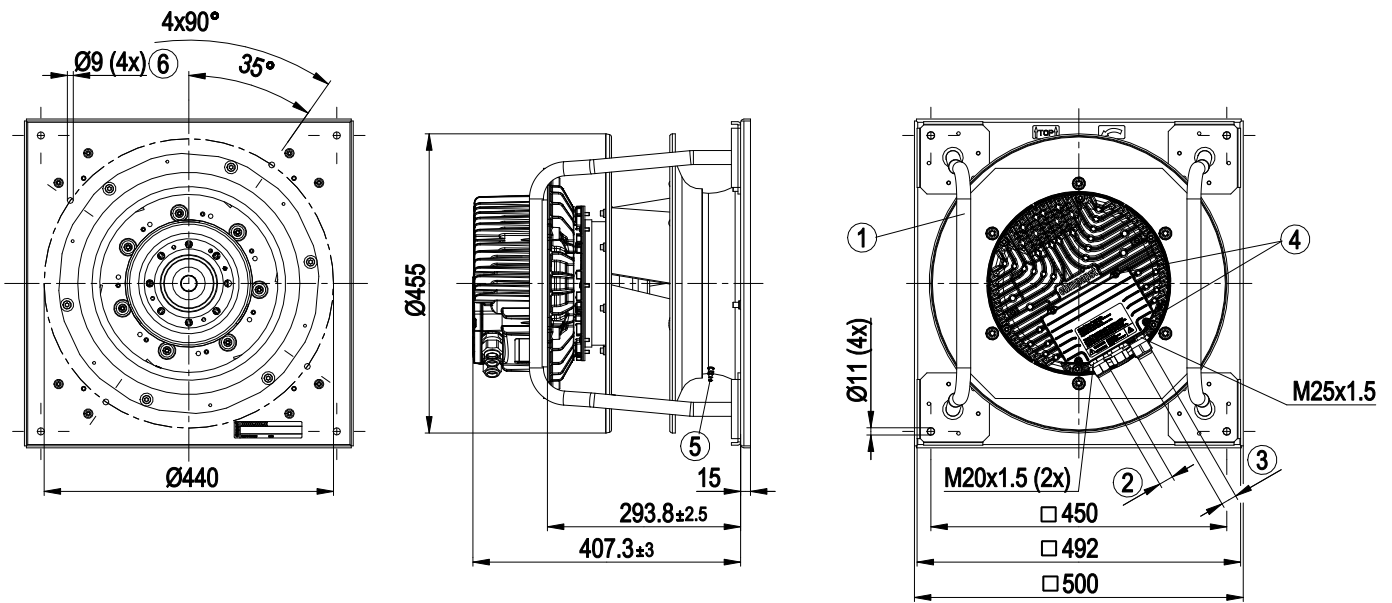
Technical description

Size	400 mm
Motor size	150
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum
Impeller material	Sheet aluminum
Support plate material	Sheet steel, galvanized
Support bracket material	Steel, painted black
Inlet nozzle material	Sheet steel, galvanized
Number of blades	6
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP20
Insulation class	"F"
Moisture (F) / Environmental (H) protection class	H1
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	See legend on product drawing
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - External 24 V input (parameter setting) - External release input - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Terminal box
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1
Approval	CSA C22.2 No. 77 + CAN/CSA-E60730-1; UL 1004-7 + 60730-1; EAC

EC centrifugal module

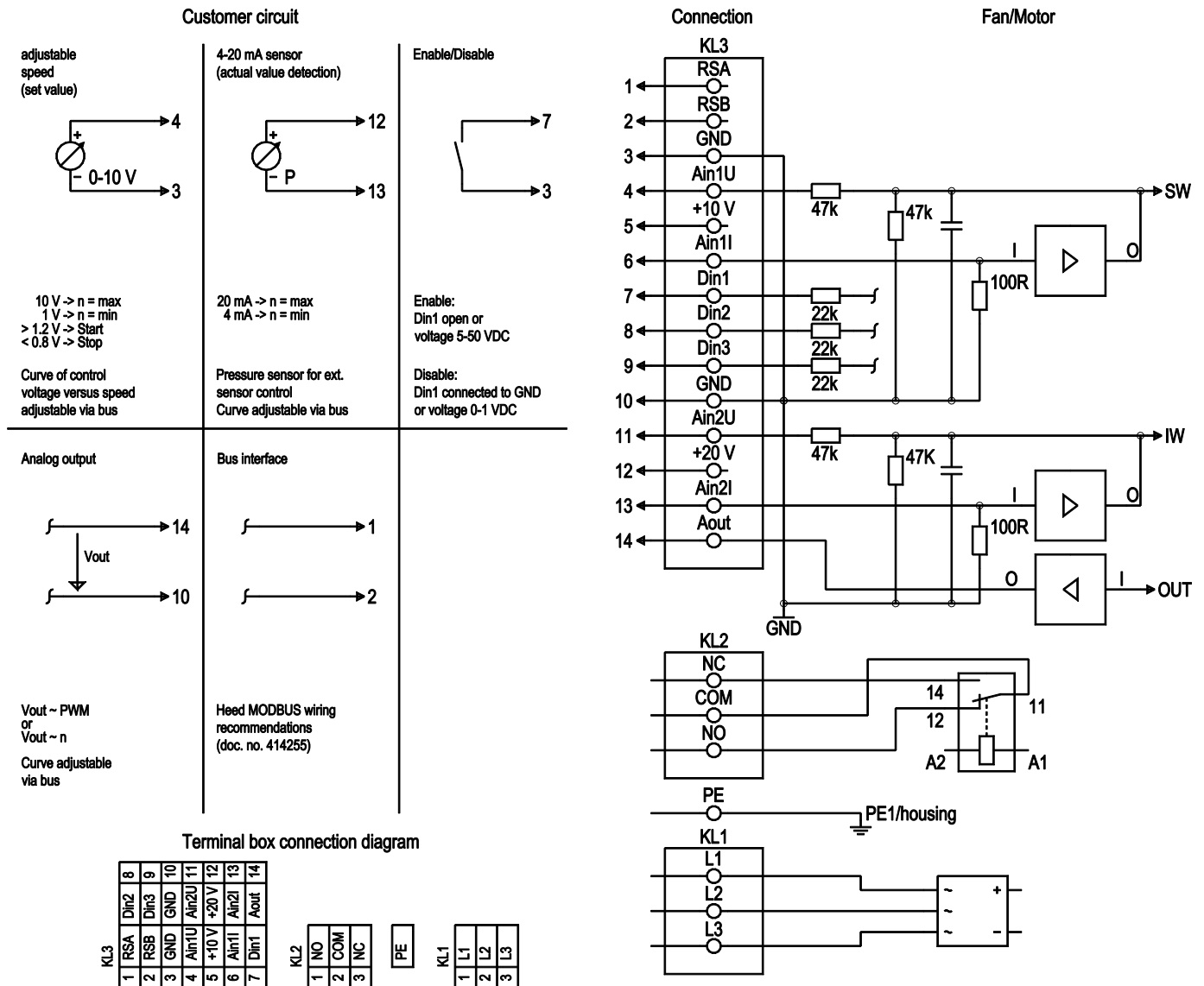
backward-curved, single-intake
with support bracket

Product drawing



1	Installed position: shaft horizontal (install support struts only vertically as illustrated) or rotor on bottom; rotor on top on request
2	Cable diameter min. 4 mm, max. 10 mm, tightening torque 4 ± 0.6 Nm
3	Cable diameter min. 9 mm, max. 16 mm, tightening torque 6 ± 0.9 Nm
4	Tightening torque 3.5 ± 0.5 Nm
5	Inlet ring with pressure tap (k-factor: 188)
6	Attachment holes for FlowGrid (35505-2-2957 not included in scope of delivery)

Connection diagram



No.	Conn.	Designation	Function/assignment
KL 1	1	L1	Supply connection, power supply, phase, see nameplate for voltage range
KL 1	2	L2	Supply connection, power supply, phase, see nameplate for voltage range
KL 1	3	L3	Supply connection, power supply, phase, see nameplate for voltage range
PE		PE	Ground connection, PE connection
KL 2	1	NO	Status relay, floating status contact, make for failure
KL 2	2	COM	Status relay, floating status contact, changeover contact, common connection, contact rating, max. 250 VAC/2 A (AC1)/min. 10 mA
KL 2	3	NC	Status relay, floating status contact, break for failure
KL 3	1	RSA	Bus connection RS485, RSA, MODBUS RTU; SELV
KL 3	2	RSB	Bus connection RS485, RSB, MODBUS RTU; SELV
KL 3	3 / 10	GND	Reference ground for control interface, SELV
KL 3	4	Ain1 U	Analog input 1, set value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain1 I; SELV

EC centrifugal module

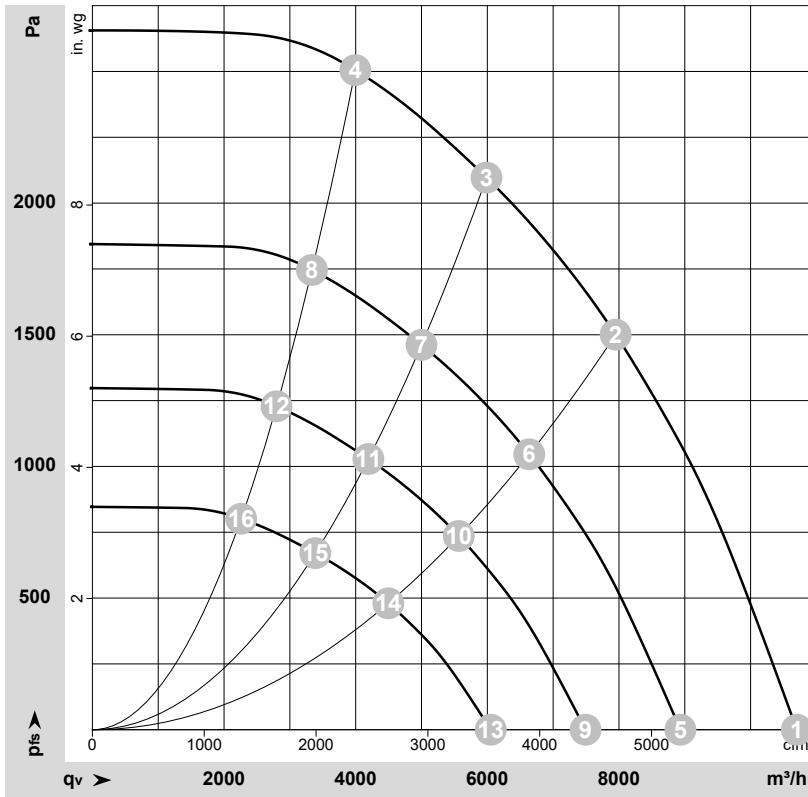
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No.	Conn.	Designation	Function/assignment
KL 3	5	+ 10 V	Fixed voltage output 10 VDC, +10 V $\pm$ 3%, max. 10 mA, short-circuit-proof, power supply for external devices (e.g. pot); SELV
KL 3	6	Ain1 I	Analog input 1, set value: 4-20 mA, R_i = 100 Ω , adjustable curve, only usable as alternative to input Ain1 U; SELV
KL 3	7	Din1	Digital input 1: enable electronics, enable: pin open or applied voltage 5-50 VDC disable: bridge to GND or applied voltage < 1 VDC reset function: triggers software reset after a level change to < 1 VDC; SELV
KL 3	8	Din2	Digital input 2: Switching parameter sets 1/2, according to EEPROM setting, the valid or used parameter set can be selected via bus or via digital input DIN2. Parameter set 1: pin open or applied voltage 5-50 VDC Parameter set 2: bridge to GND or applied voltage < 1 VDC; SELV
KL 3	9	Din3	Digital input 3: Direction of action of integrated controller, according to EEPROM setting, the direction of action of the integrated controller can be selected as normal/inverse via bus or digital input Normal: Pin open or applied voltage 5-50 VDC Inverse: Bridge to GND or applied voltage < 1 VDC; SELV
KL 3	11	Ain2 U	Analog input 2, measured value: 0-10 V, R_i = 100 k Ω , adjustable curve, only usable as alternative to input Ain2 I; SELV
KL 3	12	+ 20 V	Fixed voltage output 20 VDC, +20 V $\pm$ 25/-10%, max. 50 mA, short-circuit-proof, power supply for external devices (e.g. sensors); SELV Alternatively: +24 VDC input for parameterization without line voltage
KL 3	13	Ain2 I	Analog input 2, measured value: 4-20 mA, R_i = 100 Ω , adjustable curve, only usable as alternative to input Ain2 U; SELV
KL 3	14	Aout	Analog output 0-10 V, max. 5 mA, output of current motor modulation level; adjustable curve; SELV



Curves: Air performance 50 Hz



$$\rho = 1.15 \text{ kg/m}^3 \pm 2 \%$$

Measurement: LU-207138-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	Wired	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	LwA _{out}	q _v	p _{fs}	q _v	p _{fs}
		V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m ³ /h	Pa	cfm	in. wg
1	3~	200	50	3700	3494	10.74	94	101	106	10705	0	6300	0.00
2	3~	200	50	3700	5870	17.89	89	94	101	7950	1500	4680	6.02
3	3~	200	50	3700	6400	19.50	89	95	101	5990	2100	3525	8.43
4	3~	200	50	3700	6055	18.44	94	101	104	3995	2500	2350	10.04
5	3~	200	50	3100	2032	6.25	90	96	102	8935	0	5260	0.00
6	3~	200	50	3100	3416	10.41	84	90	97	6635	1049	3905	4.21
7	3~	200	50	3100	3710	11.30	85	90	97	5000	1463	2940	5.87
8	3~	200	50	3100	3524	10.73	89	96	99	3335	1747	1965	7.01
9	3~	200	50	2600	1199	3.69	85	92	97	7490	0	4410	0.00
10	3~	200	50	2600	2015	6.14	80	85	92	5565	738	3275	2.96
11	3~	200	50	2600	2189	6.67	80	86	92	4195	1029	2470	4.13
12	3~	200	50	2600	2079	6.33	85	92	95	2800	1229	1645	4.93
13	3~	200	50	2100	632	1.94	80	87	92	6050	0	3560	0.00
14	3~	200	50	2100	1062	3.24	74	80	87	4495	481	2645	1.93
15	3~	200	50	2100	1153	3.51	75	80	87	3385	672	1995	2.70
16	3~	200	50	2100	1095	3.34	79	86	89	2260	802	1330	3.22

Wired = Wiring · U = Voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
 LwA_{out} = Sound power level outlet side · q_v = Air flow · p_{fs} = Pressure increase

