

K3G310-RP04-B2 ebmpapst Datasheet

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Nominal data

Type	K3G310-RP04-B2	
Motor	M3G084-FA	
Phase		1~
Nominal voltage	VAC	230
Nominal voltage range	VAC	200 .. 277
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min ⁻¹	2560
Power consumption	W	715
Current draw	A	3.2
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	40

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to Commission Regulation (EU) 327/2011 (EN 17166)

		Actual	Req. 2015			
01 Overall efficiency η_{es}	%	64.9	49.9	09 Power consumption P_{ed}	kW	0.7
02 Measurement category		A		09 Air flow q_v	m ³ /h	2250
03 Efficiency category		Static		09 Pressure increase p_{fs}	Pa	670
04 Efficiency grade N		77	62	10 Speed (rpm) n	min ⁻¹	2565
05 Variable speed drive		Yes		11 Specific ratio*		1.01

Data obtained at optimum efficiency level.

The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

* Specific ratio = $1 + p_{fs} / 100\,000\text{ Pa}$

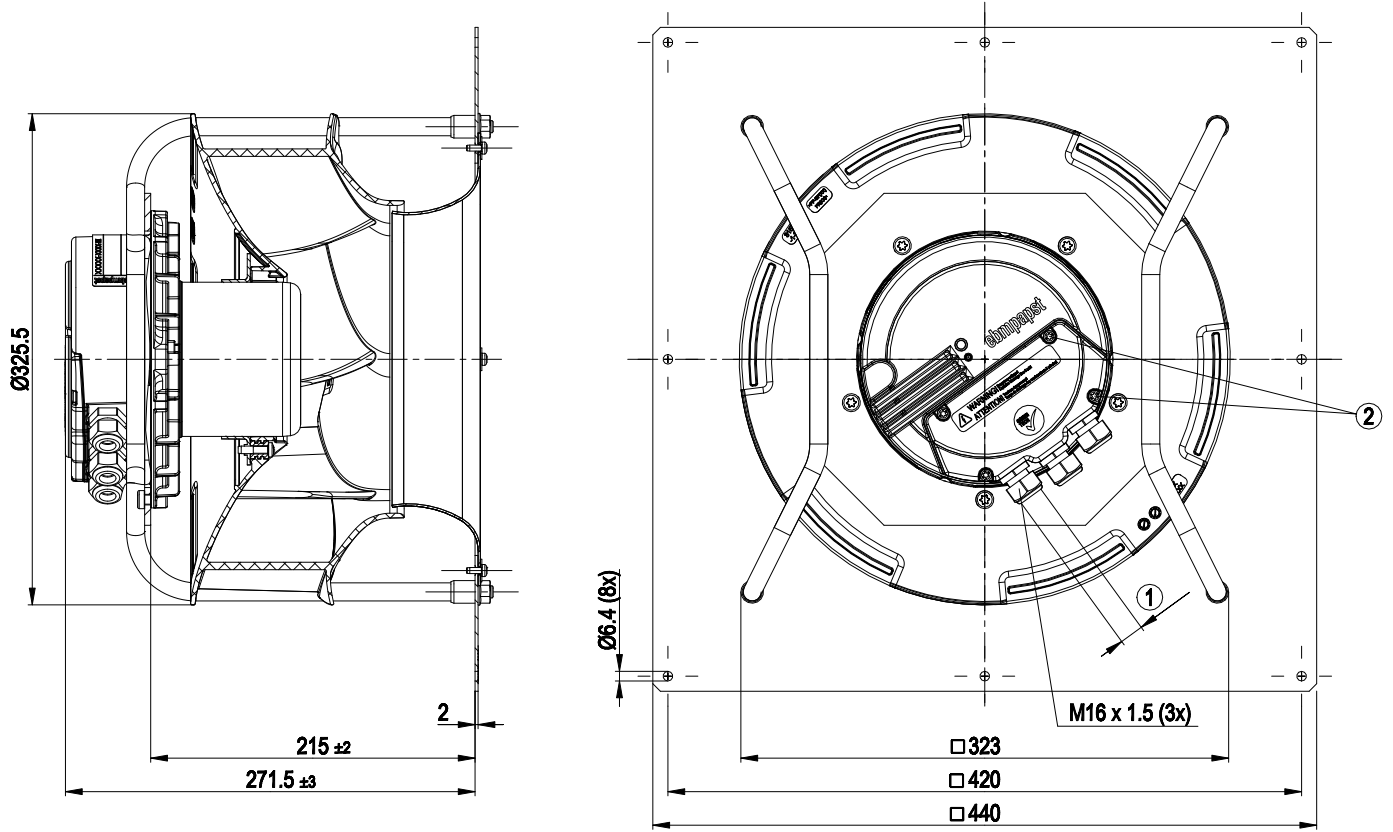
LU-138000



Technical description

Weight	9.3 kg
Size	310 mm
Motor size	84
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum
Impeller material	PP plastic
Support plate material	Sheet steel, galvanized
Support bracket material	Steel, painted black
Inlet nozzle material	Sheet steel, galvanized
Number of blades	6
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP54
Insulation class	"B"
Moisture (F) / Environmental (H) protection class	H1
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal or rotor on top; rotor on bottom on request
Condensation drainage holes	None
Mode	S1
Motor bearing	Ball bearing
Technical features	<ul style="list-style-type: none"> - Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - Alarm relay - Motor current limitation - PFC, active - RS-485 MODBUS-RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from supply - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC circuit feedback	According to EN 61000-3-2/3
EMC interference emission	According to EN 61000-6-3 (household environment)
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Terminal box
Motor protection	Thermal overload protector (TOP) internally connected
Protection class	I (if protective earth is connected by customer to the housing's connection point)
Conformity with standards	EN 61800-5-1; CE
Approval	CCC; EAC

Product drawing

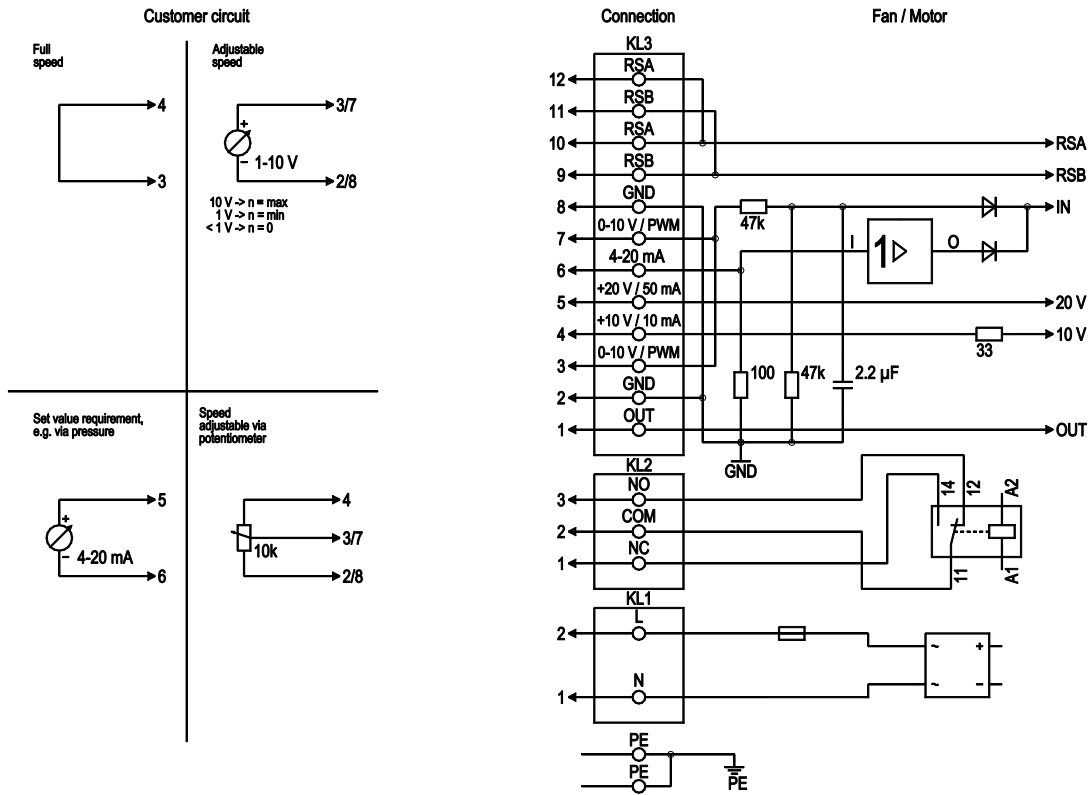


- 1 Cable diameter min. 4 mm, max. 10 mm; tightening torque 2.5 ± 0.4 Nm
- 2 Tightening torque 3.5 ± 0.5 Nm



backward-curved
with support bracket

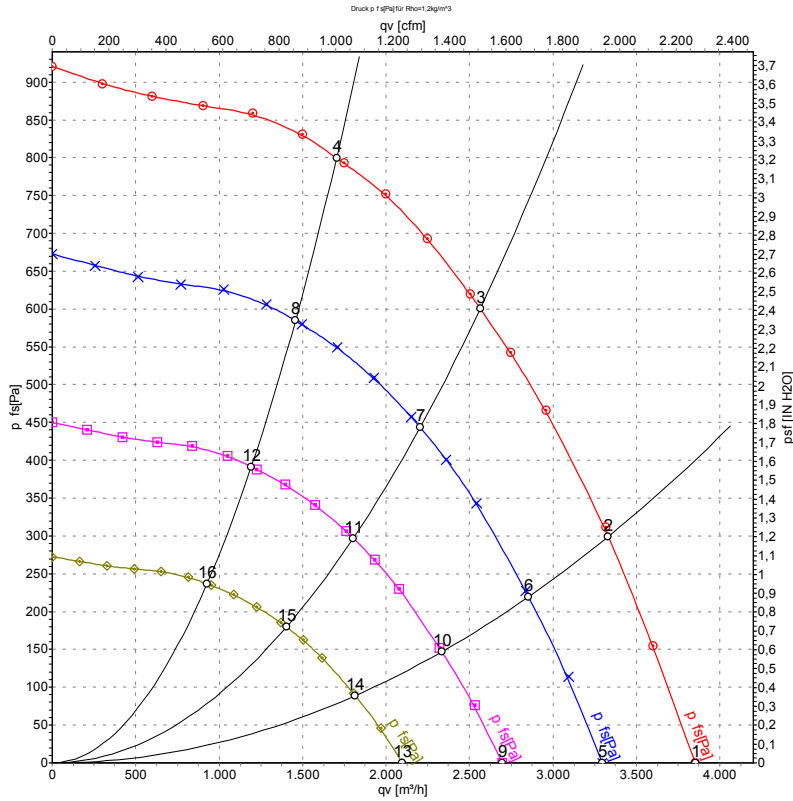
Connection diagram



No.	Conn.	Designation	Function/assignment
PE	-	PE	Protective earth terminal
KL1	1, 2	N, L	Power supply 50/60 Hz
KL2	1	NC	Floating status contact, break for failure
KL2	2	COM	Floating status contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status contact, make for failure
KL3	1	OUT	Analog output, 0-10 VDC, max. 3 mA, SELV output of current motor modulation level: 1 V corresponds to 10% modulation level. 10 V corresponds to 100% modulation level.
KL3	2, 8	GND	Reference ground for control interface, SELV
KL3	3, 7	0-10 V	Control/current sensor value input 0-10 VDC, impedance 100 kΩ, use only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (+/- 3%), max. 10 mA, power supply for ext. devices (e.g. potentiometer), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25%/-10%), max. 50 mA power supply for ext. devices (e.g. sensors), SELV
KL3	6	4-20 mA	Control/current sensor value input 4-20 mA, impedance 100 Ω, use only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for MODBUS, RSB
KL3	10, 12	RSA	RS485 interface for MODBUS, RSA



Curves: Air performance 50 Hz



Measurement: LU-138000-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebmpapst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	q _v	P _{fs}	q _v	P _{fs}
	V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	m ³ /h	Pa	cfm	in. wg
1	230	50	2560	488	2.21	74	82	3850	0	2265	0.00
2	230	50	2560	623	2.77	71	78	3330	300	1960	1.20
3	230	50	2560	715	3.20	65	72	2565	600	1510	2.41
4	230	50	2560	665	2.95	68	76	1705	800	1005	3.21
5	230	50	2200	305	1.38	70	78	3295	0	1940	0.00
6	230	50	2200	390	1.73	67	74	2850	221	1680	0.89
7	230	50	2200	453	2.01	61	68	2205	444	1295	1.78
8	230	50	2200	416	1.84	64	72	1455	585	860	2.35
9	230	50	1800	167	0.76	65	73	2695	0	1585	0.00
10	230	50	1800	214	0.95	62	69	2335	148	1375	0.59
11	230	50	1800	248	1.10	56	63	1805	297	1060	1.19
12	230	50	1800	228	1.01	59	67	1190	392	700	1.57
13	230	50	1400	79	0.36	59	66	2095	0	1235	0.00
14	230	50	1400	100	0.45	55	63	1815	89	1070	0.36
15	230	50	1400	117	0.52	50	57	1405	180	825	0.72
16	230	50	1400	107	0.48	53	60	925	237	545	0.95

U = Voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
q_v = Air flow · P_{fs} = Pressure increase

