

EC centrifugal module - RadiPac

backward-curved, single-intake

with support bracket

ebm-papst Mulfingen GmbH & Co. KG

Bachmühle 2 · D-74673 Mulfingen

Phone +49 7938 81-0

Fax +49 7938 81-110

info1@de.fansco.com

www.fansco.com

Limited partnership · Headquarters Mulfingen

Amtsgericht (court of registration) Stuttgart · HRA 590344

General partner Elektrobau Mulfingen GmbH · Headquarters Mulfingen

Amtsgericht (court of registration) Stuttgart · HRB 590142

Nominal data

Type	K3G310-PG93-27	
Motor	M3G112-EA	
Phase		1~
Nominal voltage	VAC	230
Nominal voltage range	VAC	200 .. 277
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min ⁻¹	3200
Power consumption	W	1500
Current draw	A	6.6
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	50

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment

Subject to change

Data according to Commission Regulation (EU) 327/2011 (EN 17166)

		Actual	Req. 2015			
01 Overall efficiency η_{es}	%	63.2	53.4	09 Power consumption P_{ed}	kW	1.52
02 Measurement category		A		09 Air flow q_v	m ³ /h	3115
03 Efficiency category		Static		09 Pressure increase p_{fs}	Pa	1042
04 Efficiency grade N		71.8	62	10 Speed (rpm) n	min ⁻¹	3170
05 Variable speed drive		Yes		11 Specific ratio*		1.01

Data obtained at optimum efficiency level.

* Specific ratio = $1 + p_b / 100\,000\text{ Pa}$

LU-197917

The efficiency values displayed for achieving conformity with the Ecodesign Regulation EU 327/2011 has been reached with defined air duct components (e.g. inlet rings). The dimensions must be requested from ebm-papst. If other air conduction geometries are used on the installation side, the ebm-papst evaluation loses its validity/the conformity must be confirmed again. The product does not fall within the scope of Regulation (EU) 2019/1781 due to the exception specified in Article 2 (2a) (motors completely integrated into a product).



Technical description

Size	310 mm
Motor size	112
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum
Impeller material	Sheet aluminum
Support plate material	Sheet steel, galvanized
Support bracket material	Steel, painted black
Inlet nozzle material	Sheet steel, galvanized
Number of blades	5
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP54
Insulation class	"B"
Moisture (F) / Environmental (H) protection class	H1
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	See legend on product drawing
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Tach output - Input for sensor 0-10 V or 4-20 mA - External 24 V input (parameter setting) - External release input - Alarm relay - Integrated PID controller - Power limiter - Motor current limitation - PFC, active - RS-485 MODBUS-RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Terminal box
Motor protection	Thermal overload protector (TOP) internally connected

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Protection class assignment	I; If a protective earth is connected by the customer This component for installation may have several local protection classes. This information relates to this component's basic design. The final protection class is based on the component's intended installation and connection.
Conformity with standards	EN 61800-5-1; CE
Approval	CSA C22.2 No. 77 + CAN/CSA-E60730-1; EAC; UL 1004-7 + 60730-1

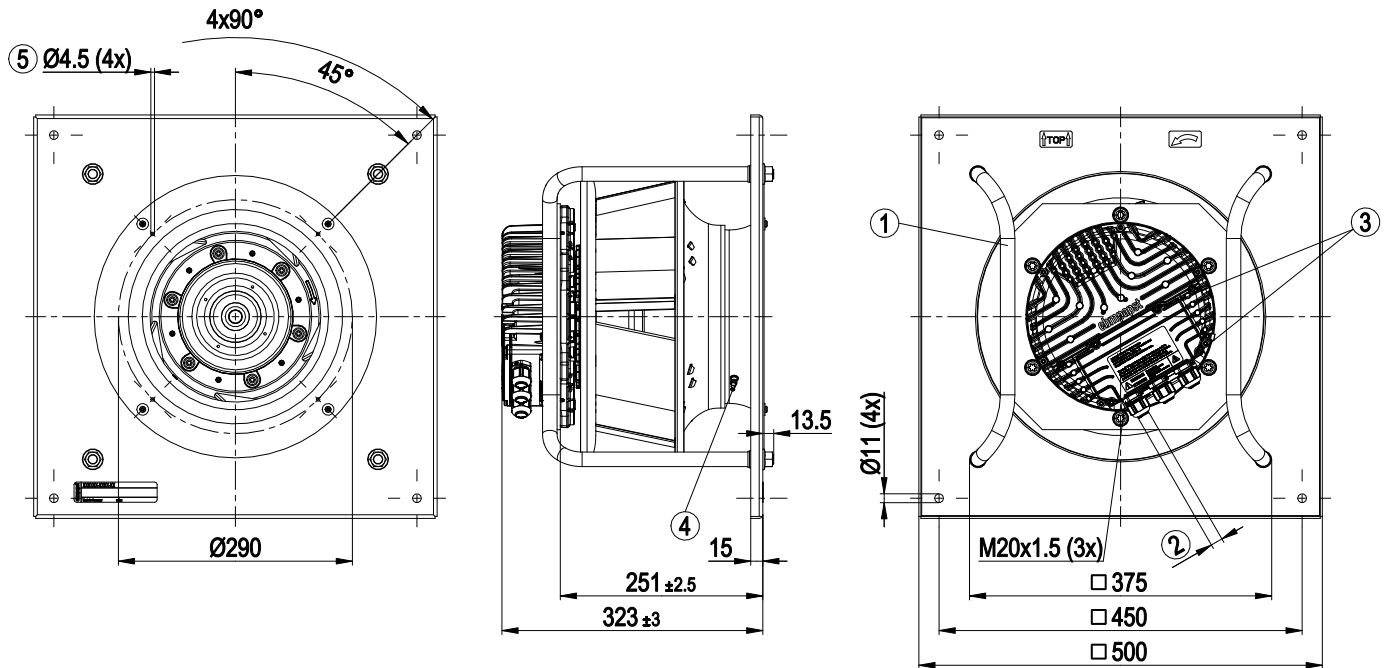


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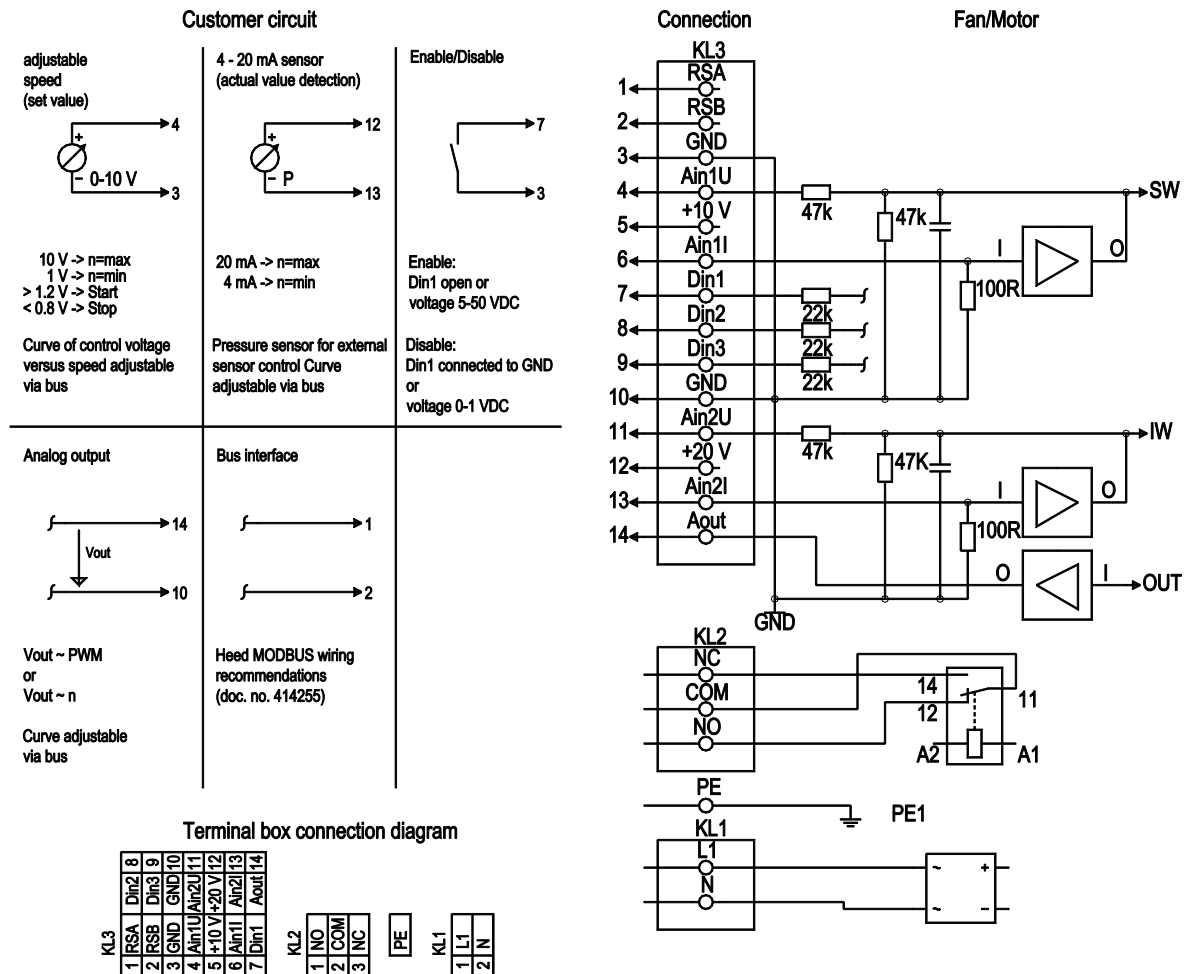
Product drawing



- | | |
|---|--|
| 1 | Installed position: shaft horizontal (install support struts only vertically as illustrated) or rotor on bottom; rotor on top on request |
| 2 | Cable diameter min. 4 mm, max. 10 mm, tightening torque 4 ± 0.6 Nm |
| 3 | Tightening torque 3.5 ± 0.5 Nm |
| 4 | Inlet ring with pressure tap (k-factor: 116) |
| 5 | Attachment holes for FlowGrid (25310-2-2957 not included in scope of delivery) |



Connection diagram



No.	Conn.	Designation	Function/assignment
KL1	1, 2	L1/N	Supply connection, power supply; for nominal voltage range see technical data
PE	PE	PE	Ground connection, PE connection
KL2	1	NO	Status relay, floating status contact, make for failure
KL2	2	COM	Status relay, floating status contact, changeover contact, common connection, contact rating, max. 250 VAC/2 A (AC1)/min. 10 mA
KL2	3	NC	Status relay, floating status contact, break for failure
KL3	1	RSA	Bus connection RS485, RSA, MODBUS-RTU; SELV
KL3	2	RSB	Bus connection RS485, RSB, MODBUS-RTU; SELV
KL3	3	GND	Reference ground for control interface, SELV
KL3	4	Ain1 U	Analog input 1, set value: 0-10 V, $R_i = 100\text{ k}\Omega$, adjustable curve, only usable as alternative to input Ain1 I; SELV
KL3	5	+10 V	Fixed voltage output 10 VDC, $+10\text{ V} \pm 3\%$, max. 10 mA, short-circuit-proof, power supply for external devices (e.g. pot); SELV
KL3	6	Ain1 I	Analog input 1, set value: 4-20 mA, $R_i = 100\text{ }\Omega$, adjustable curve, only usable as alternative to input Ain1 U; SELV
KL3	7	Din1	Digital input 1: enable electronics, enable: pin open or applied voltage 5-50 VDC disable: bridge to GND or applied voltage $< 1\text{ VDC}$ reset function: triggers software reset after a level change to $< 1\text{ VDC}$; SELV

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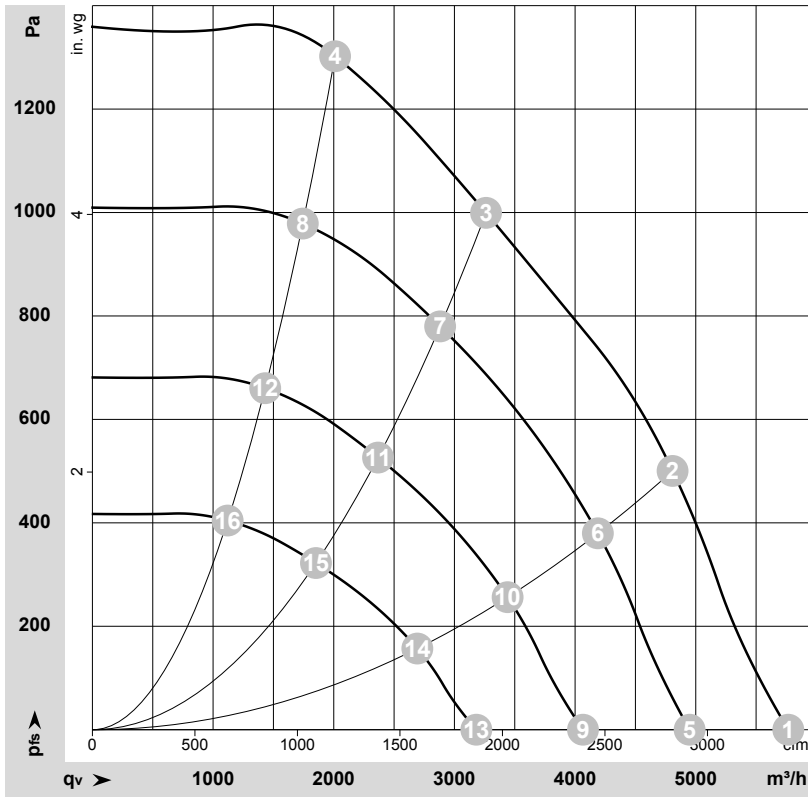
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No.	Conn.	Designation	Function/assignment
KL3	8	Din2	Digital input 2: Switching parameter sets 1/2, according to EEPROM setting, the valid or used parameter set can be selected via bus or via digital input DIN2. Parameter set 1: pin open or applied voltage 5-50 VDC Parameter set 2: bridge to GND or applied voltage < 1 VDC; SELV
KL3	9	Din3	Digital input 3: according to EEPROM setting, the integrated controller's direction of action can be selected via bus or digital input Din3; normal: pin open or applied voltage 5-50 VDC inverse: bridge to GND or applied voltage < 1 VDC; SELV
KL3	10	GND	Reference ground for control interface, SELV
KL3	11	Ain2 U	Analog input 2, measured value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain2 I; SELV
KL3	12	+20 V	Fixed voltage output 20 VDC, +20 V +25/-10%, max. 50 mA, short-circuit-proof, power supply for external devices (e.g. sensors); SELV Alternatively: +24 VDC input for parameterization without line voltage
KL3	13	Ain2 I	Analog input 2, measured value: 4-20 mA, Ri = 100 Ω, adjustable curve, only usable as alternative to input Ain2 U; SELV
KL3	14	Aout	Analog output 0-10 VDC, max. 5 mA, output of current motor modulation level / motor speed adjustable curve; SELV



Curves: Air performance 50 Hz



$$\rho = 1.15 \text{ kg/m}^3 \pm 2 \%$$

Measurement: LU-197917-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	Wired	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	LwA _{out}	q _v	p _{fs}	q _v	p _{fs}
		V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m ³ /h	Pa	cfm	in. wg
1	1~	230	50	3200	1034	4.51	88	95	97	5765	0	3395	0.00
2	1~	230	50	3200	1377	6.00	81	88	91	4810	500	2830	2.01
3	1~	230	50	3200	1500	6.60	73	81	87	3260	1000	1920	4.01
4	1~	230	50	3200	1490	6.50	77	86	90	2010	1300	1185	5.22
5	1~	230	50	2800	654	2.85	84	91	93	4950	0	2915	0.00
6	1~	230	50	2800	910	3.97	77	84	88	4190	380	2465	1.53
7	1~	230	50	2800	1052	4.58	70	78	84	2880	781	1695	3.14
8	1~	230	50	2800	980	4.27	74	82	87	1745	979	1025	3.93
9	1~	230	50	2300	362	1.58	79	87	88	4065	0	2395	0.00
10	1~	230	50	2300	505	2.20	72	79	83	3440	257	2025	1.03
11	1~	230	50	2300	583	2.54	65	73	79	2365	527	1395	2.12
12	1~	230	50	2300	543	2.37	69	77	82	1430	660	845	2.65
13	1~	230	50	1800	174	0.76	73	80	82	3180	0	1875	0.00
14	1~	230	50	1800	242	1.05	66	73	77	2695	157	1585	0.63
15	1~	230	50	1800	280	1.22	59	67	73	1850	323	1090	1.30
16	1~	230	50	1800	260	1.13	63	71	76	1120	404	660	1.62

Wired = Wiring · U = Voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
LwA_{out} = Sound power level outlet side · q_v = Air flow · p_{fs} = Pressure increase

