

EC centrifugal module - Plug fan

backward curved, single inlet
with support bracket



K3G310-AX52-35 ebmpapst Datasheet
sales@fansco.com
www.fansco.com

Nominal data

Type	K3G310-AX52-35	
Motor	M3G112-EA	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
Speed	min ⁻¹	2580
Power input	W	1000
Current draw	A	1.63
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	50

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations

Data according to ErP directive

Installation category	A
Efficiency category	Static
Variable speed drive	Yes
Specific ratio*	1.01

* Specific ratio = 1 + p_{fs} / 100 000 Pa

		Actual	Request 2013	Request 2015
Overall efficiency η_{es}	%	63.3	47.4	51.4
Efficiency grade N		73.9	58	62
Power input P _{ed}	kW	0.98		
Air flow q _v	m ³ /h	3050		
Pressure increase p _{fs}	Pa	681		
Speed n	min ⁻¹	2590		

Data definition with optimum efficiency.
The ErP data is determined using a motor-impeller combination in a standardised measurement configuration.



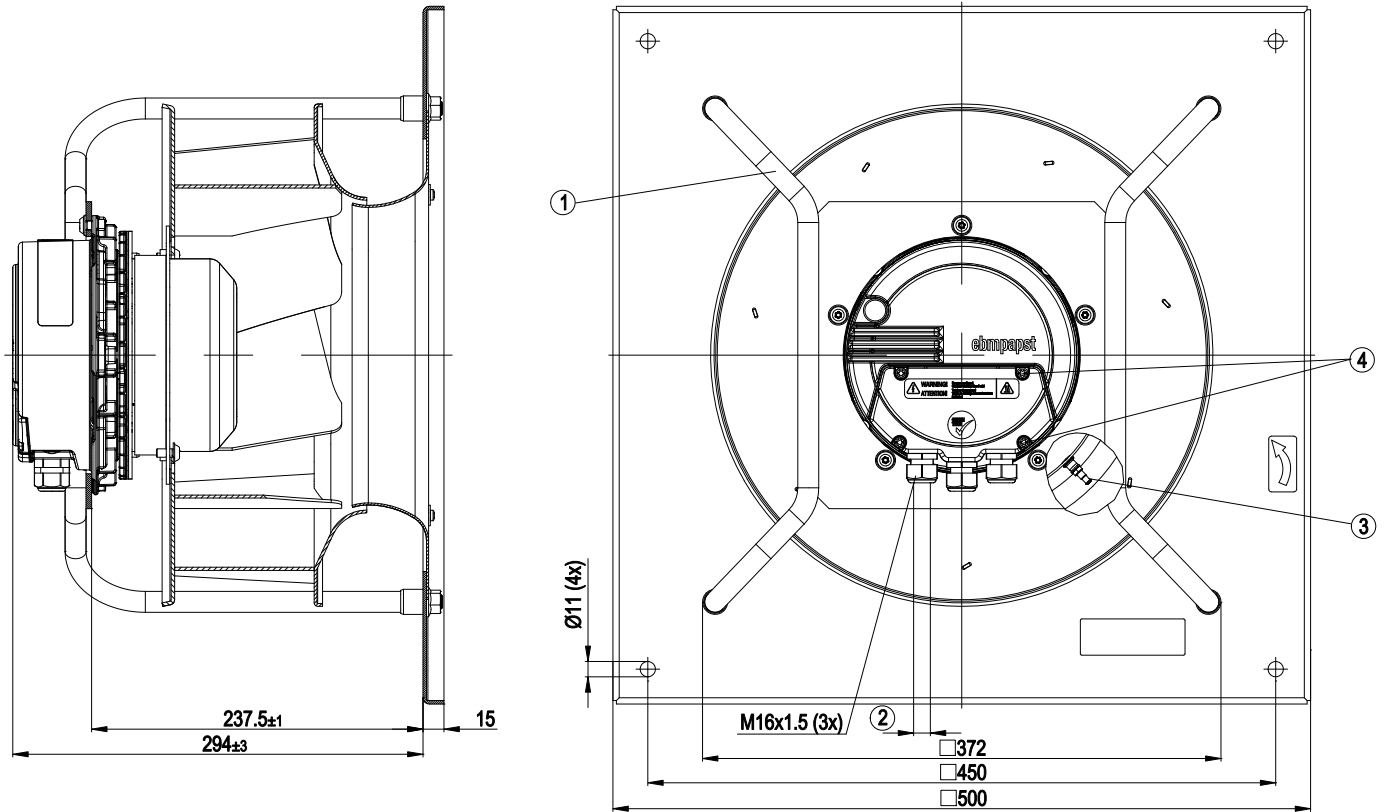
Technical features

Mass	16.9 kg
Size	310 mm
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium, coated in black
Material of impeller	Aluminium sheet, white plastic-coated
Material of mounting plate	Sheet steel, hot-galvanised and coated in white
Material of support bracket	Steel, galvanised and coated in white
Material of inlet nozzle	Sheet steel, hot-galvanised and coated in white
Number of blades	7
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP 54
Insulation class	"B"
Humidity class	F5
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Refer to product drawing
Condensate discharge holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - External 24 V input (programming) - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive - RS485 MODBUS RTU - Soft start - Control input 0-10 VDC / PWM - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection
EMC interference immunity	Acc. to EN 61000-6-2 (industrial environment)
EMC harmonics	Acc. to EN 61000-3-2/3
EMC interference emission	Acc. to EN 61000-6-3 (household environment)
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical leads	Via terminal box
Motor protection	Thermal overload protector (TOP) wired internally
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE
Approval	GOST

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Product drawing



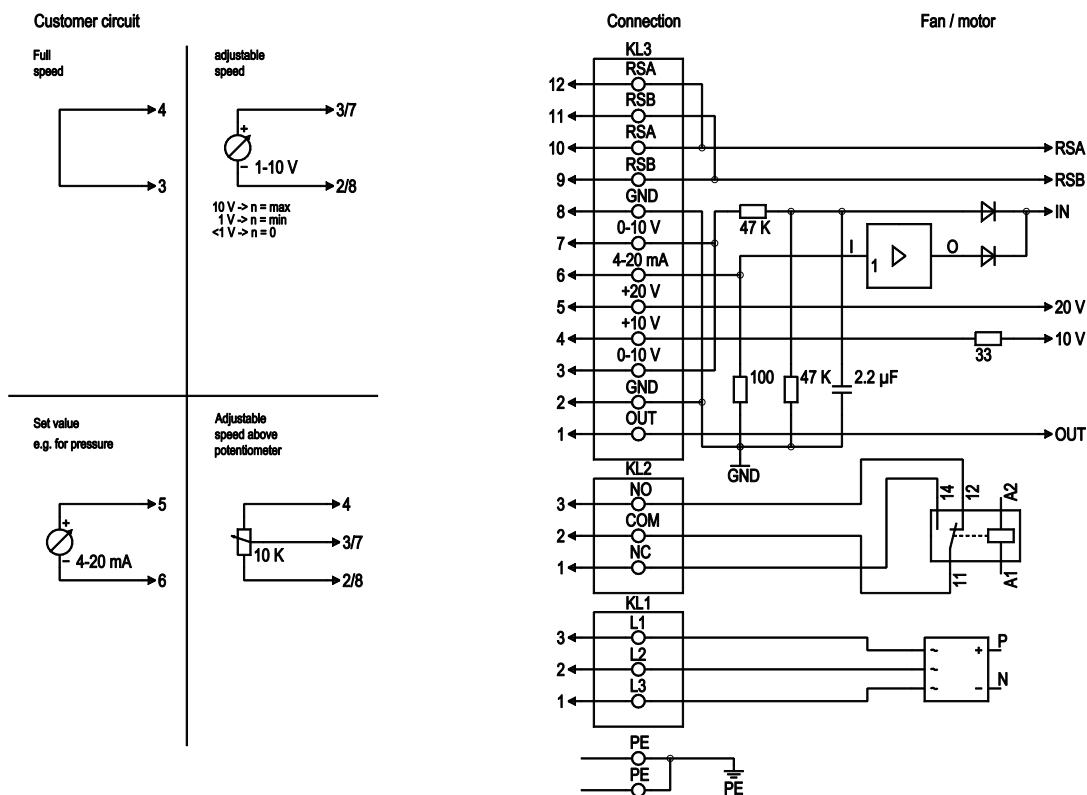
1	Mounting position: shaft horizontal (install the support struts only vertically as shown in the view!) or rotor on bottom; rotor on top on request
2	Cable diameter: min. 4 mm, max. 10 mm; tightening torque: 2.5 ± 0.4 Nm
3	Inlet nozzle with bleeder connection for pressure relief (k-factor: 116)
4	Tightening torque 3.5 ± 0.5 Nm

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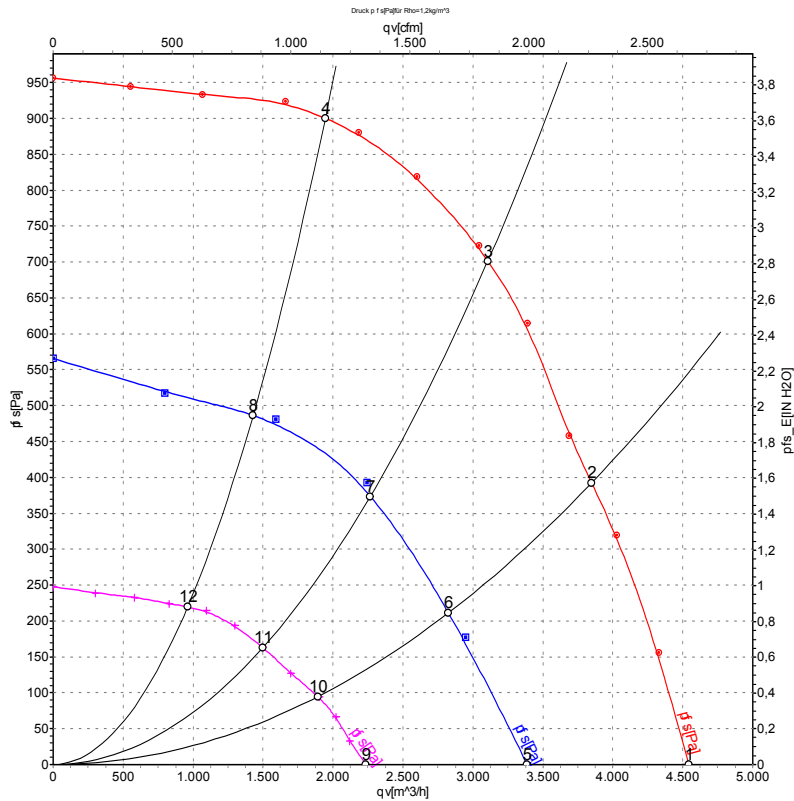
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Connection screen



No.	Pin	Signal	Function / assignment
PE		PE	Protective earth connection
KL1	1, 2, 3	L1, L2, L3	Supply voltage, voltage range (see type plate), 50/60 Hz
KL2	1	NC	Floating status contact, break with error
KL2	2	COM	Floating status contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status contact, close with error
KL3	1	OUT	Analogue output, 0-10 VDC, max. 3 mA, SELV, Output of the actual motor duty cycle (PWM): 1 V corresponds to 10% PWM, 10 V correspond to 100% PWM.
KL3	2, 8	GND	Signal ground for control interface, SELV
KL3	3, 7	0-10 V	Set value / actual sensor value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (+/-3%), max. 10 mA, power supply for external devices (e.g. potentiometer), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25%/-10%), max. 50 mA, supply voltage for external devices (e.g. sensors), SELV
KL3	6	4-20 mA	Set value / actual sensor value input 4-20 mA, impedance 100 Ω, only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for MODBUS, RSB
KL3	10, 12	RSA	RS485 interface for MODBUS, RSA

Charts: Air flow 50 Hz



Measurement: LU-106400
 Measurement: LU-108542
 Measurement: LU-106401

Air performance measured as per ISO 5801
 Installation category A. For detailed
 information on the measuring set-up, please
 contact ebm-papst. Suction-side noise
 levels: L_{wA} measured as per ISO 13347 /
 L_{pA} measured with 1m distance to fan axis.
 The values given are valid under the
 measuring conditions mentioned above and
 may vary according to the actual installation
 situation. With any deviation from the
 standard set-up, the specific values have to
 be checked and reviewed with the unit
 installed.

Measured values

	U	f	n	P_{ed}	I	$L_{pA_{in}}$	$L_{wA_{in}}$	$L_{wA_{out}}$	qv	p_{fs}
	V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m ³ /h	Pa
1	400	50	2580	669	1.17	82	88	92	4540	0
2	400	50	2580	862	1.46	75	81	87	3850	400
3	400	50	2580	1000	1.63	70	77	83	3105	700
4	400	50	2580	907	1.53	72	79	85	1945	900
5	400	50	1930	288	0.57	73	80	84	3385	0
6	400	50	1910	348	0.69	67	74	79	2825	216
7	400	50	1900	396	0.77	63	70	76	2265	386
8	400	50	1905	360	0.72	65	71	77	1430	489
9	400	50	1305	123	0.28	65	72	76	2235	0
10	400	50	1305	144	0.33	60	67	72	1890	96
11	400	50	1305	151	0.34	55	62	68	1495	164
12	400	50	1300	151	0.34	56	62	69	960	220

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Power input · I = Current draw · $L_{pA_{in}}$ = Sound pressure level inlet side · $L_{wA_{in}}$ = Sound power level inlet side · $L_{wA_{out}}$ = Sound power level outlet side
 qv = Air flow · p_{fs} = Pressure increase