

K3G280-AU15-K2

EC centrifugal module - RadiPac

backward-curved, single-intake
with support bracket



K3G280-AU15-K2 ebmpapst Datasheet
sales@fansco.com
www.fansco.com

Nominal data

Type	K3G280-AU15-K2	
Motor	M3G084-GF	
Phase		3~
Nominal voltage	VAC	200
Nominal voltage range	VAC	200 .. 240
Frequency	Hz	50/60
Method of obtaining data		ml
Status		prelim.
Speed (rpm)	min ⁻¹	3100
Power consumption	W	1000
Current draw	A	3.3
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	60

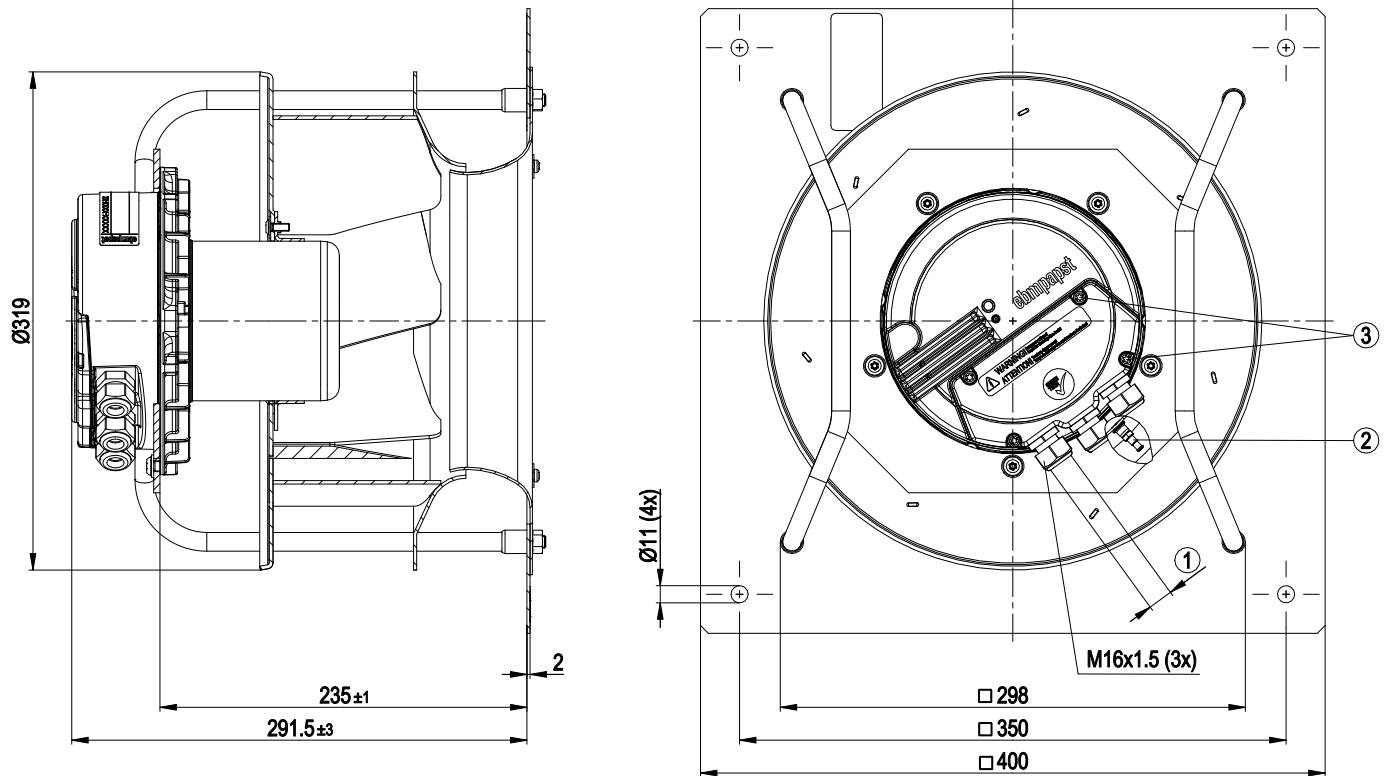
ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change



Technical description

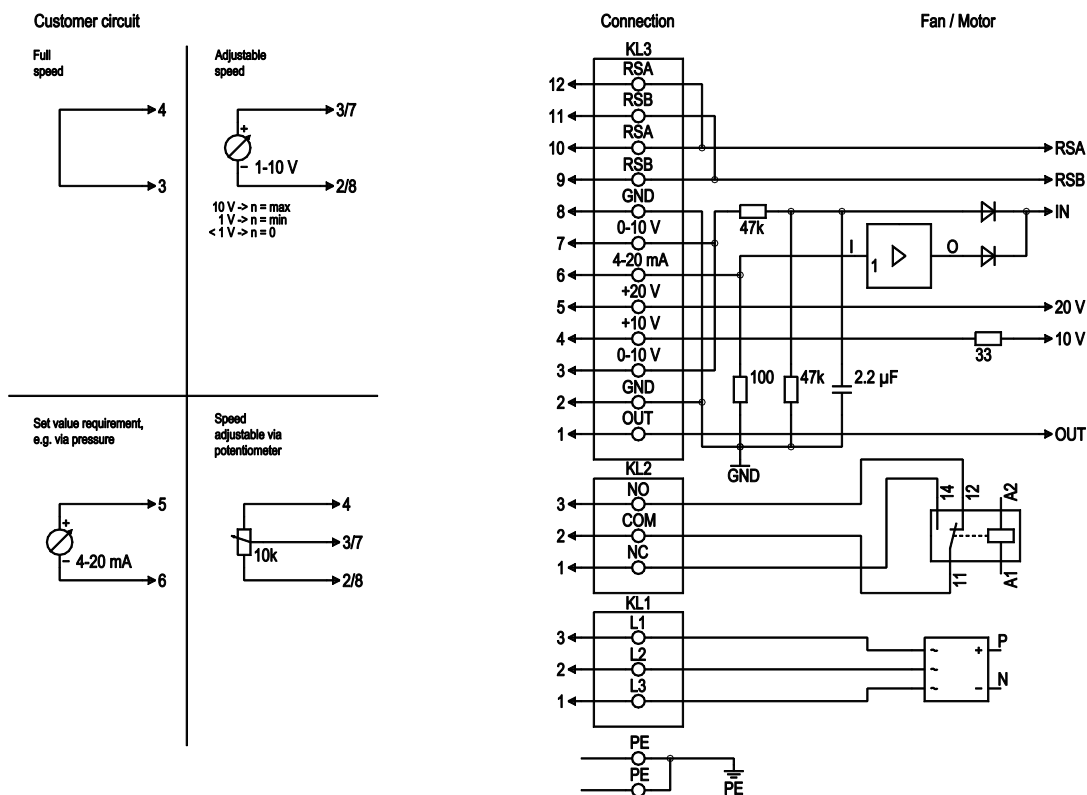
Weight	11.7 kg
Size	280 mm
Motor size	84
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum
Impeller material	Sheet aluminum
Support plate material	Sheet steel, galvanized
Support bracket material	Steel, painted black
Inlet nozzle material	Sheet steel, galvanized
Number of blades	7
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP54
Insulation class	"B"
Moisture (F) / Environmental (H) protection class	H1
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing; (sealed)
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - External 24 V input (parameter setting) - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from supply - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Terminal box
Motor protection	Thermal overload protector (TOP) internally connected
Protection class	I (if protective earth is connected by customer to the housing's connection point)
Conformity with standards	EN 61800-5-1
Approval	CSA C22.2 No. 77 + CAN/CSA-E60730-1; UL 1004-7 + 60730

Product drawing



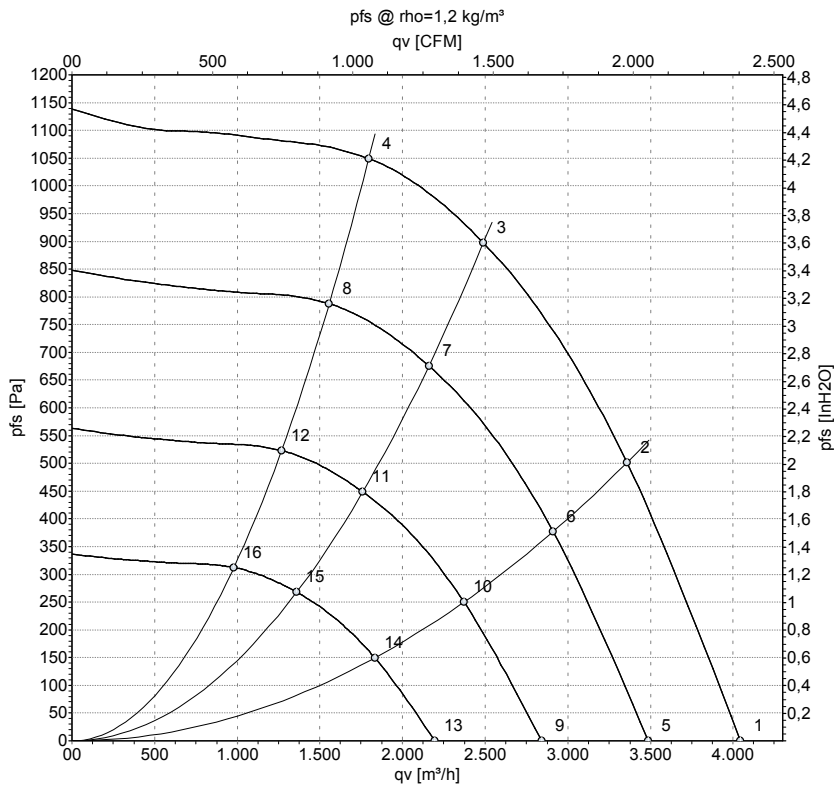
1	Cable diameter min. 4 mm, max. 10 mm, tightening torque 2.5 ± 0.4 Nm
2	Inlet ring with pressure tap (k-factor: 93)
3	Tightening torque 3.5 ± 0.5 Nm

Connection diagram



No.	Conn.	Designation	Function/assignment
PE		PE	Protective earth terminal
KL1	1, 2, 3	L1, L2, L3	Power supply, voltage range (see nameplate), 50/60 Hz
KL2	1	NC	Floating status contact, break for failure
KL2	2	COM	floating status contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status contact, make for failure
KL3	1	OUT	Analog output, 0-10 VDC, max. 3 mA, SELV, output of current motor modulation level: 1 V corresponds to 10% modulation level. 10 V corresponds to 100% modulation level.
KL3	2, 8	GND	Reference ground for control interface, SELV
KL3	3, 7	0-10 V	Use control / current sensor value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (±3%), max. 10 mA, power supply for external devices (e.g. potentiometer), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25%/-10%), max. 50 mA, power supply for external devices (e.g. sensors), SELV
KL3	6	4-20 mA	Use control / current sensor value input 4-20 mA, impedance 100 Ω only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for MODBUS, RSB
KL3	10, 12	RSA	RS485 interface for MODBUS, RSA

Curves: Air performance 50 Hz



Measurement: LU-147135-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	q _v	p _{fs}	q _v	p _{fs}
	V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	m³/h	Pa	cfm	in. wg
1	200	50	3100	692	2.31	78	86	4045	0	2380	0.00
2	200	50	3100	913	2.97	74	82	3360	500	1975	2.01
3	200	50	3100	1000	3.30	72	80	2490	900	1465	3.61
4	200	50	3100	896	2.87	75	83	1795	1050	1055	4.22
5	200	50	2700	444	1.48			3490	0	2055	0.00
6	200	50	2700	595	1.93			2910	377	1715	1.51
7	200	50	2700	657	2.10			2160	677	1270	2.72
8	200	50	2700	583	1.87			1555	787	915	3.16
9	200	50	2200	240	0.80			2840	0	1675	0.00
10	200	50	2200	322	1.05			2370	250	1395	1.00
11	200	50	2200	356	1.14			1760	449	1035	1.80
12	200	50	2200	315	1.01			1270	523	745	2.10
13	200	50	1700	111	0.37			2195	0	1295	0.00
14	200	50	1700	149	0.48			1835	149	1080	0.60
15	200	50	1700	164	0.52			1360	268	800	1.08
16	200	50	1700	145	0.47			980	312	575	1.25

U = Voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
q_v = Air flow · p_{fs} = Pressure increase

