

A3G910-AO83-90 ebmpapst Datasheet

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Nominal data

Type	A3G910-AO83-90	
Motor	M3G112-IA	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min ⁻¹	610
Power consumption	W	625
Current draw	A	1.1
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	60

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to Commission Regulation (EU) 327/2011 (EN 17166)

		Actual	Req. 2015			
01 Overall efficiency η_{es}	%	45.5	32.2	09 Power consumption P_{ed}	kW	0.59
02 Measurement category		A		09 Air flow q_v	m ³ /h	11680
03 Efficiency category		Static		09 Pressure increase p_{fs}	Pa	76
04 Efficiency grade N		53.3	40	10 Speed (rpm) n	min ⁻¹	615
05 Variable speed drive		Yes		11 Specific ratio*		1.00

Data obtained at optimum efficiency level.

The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

* Specific ratio = $1 + p_{fs} / 100\,000\text{ Pa}$

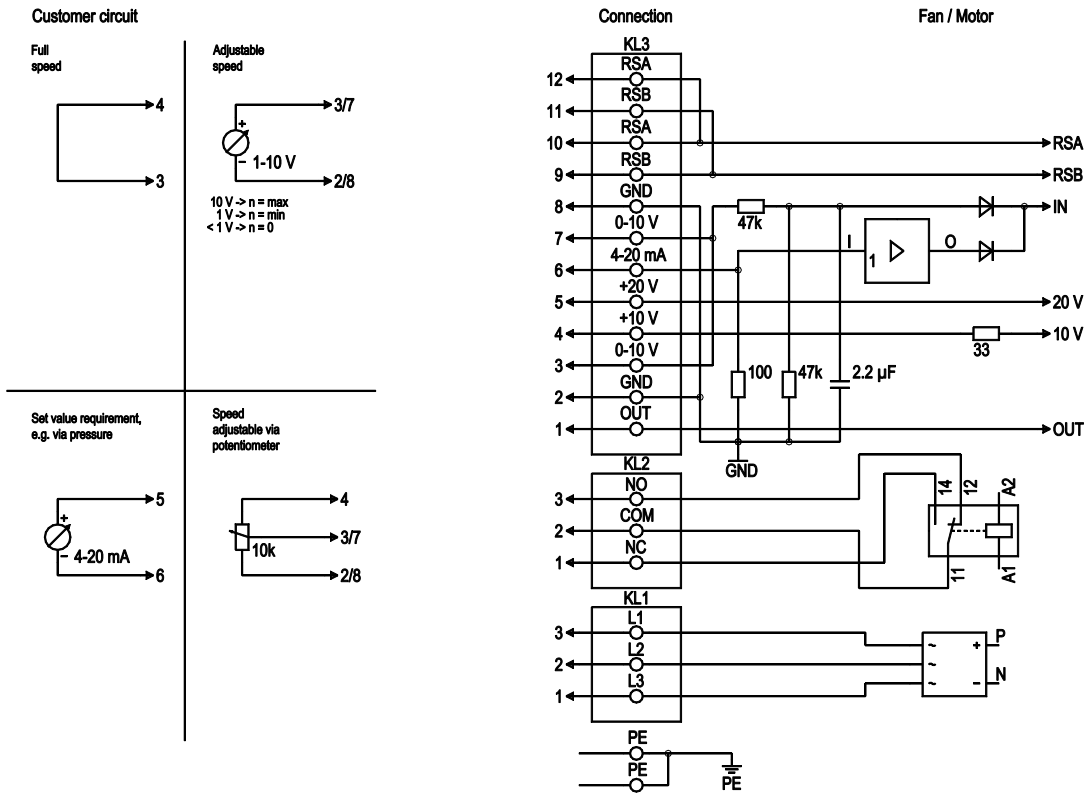
LU-120677



Technical description

Weight	13 kg
Size	910 mm
Motor size	112
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum, painted black
Blade material	Press-fitted sheet steel blank, sprayed with PP plastic
Number of blades	5
Airflow direction	V
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP54
Insulation class	"B"
Moisture (F) / Environmental (H) protection class	H2
Max. permitted ambient temp. for motor (transport/storage)	+ 80 °C
Min. permitted ambient temp. for motor (transport/storage)	- 40 °C
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	<ul style="list-style-type: none"> - Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - External 24 V input (parameter setting) - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC circuit feedback	According to EN 61000-3-2/3
EMC interference emission	According to EN 61000-6-3 (household environment)
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Terminal box
Motor protection	Thermal overload protector (TOP) internally connected
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approval	EAC; UL 1004-7 + 60730-1

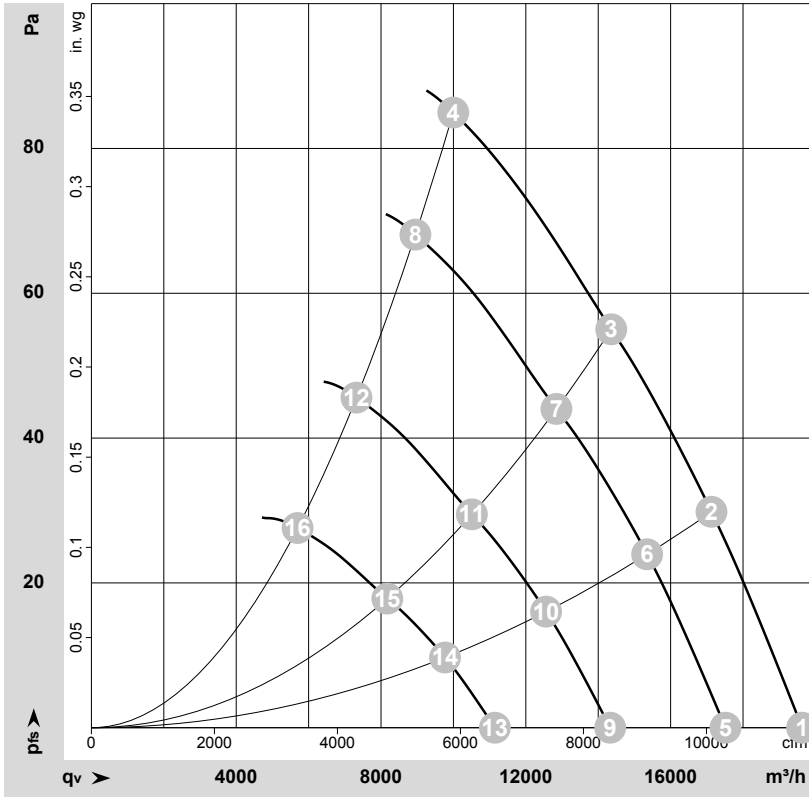
Connection diagram



No.	Conn.	Designation	Function/assignment
PE		PE	Protective earth terminal
KL1	1, 2, 3	L1, L2, L3	Power supply, voltage range (see nameplate), 50/60 Hz
KL2	1	NC	Floating status contact, break for failure
KL2	2	COM	floating status contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status contact, make for failure
KL3	1	OUT	Analog output, 0-10 VDC, max. 3 mA, SELV, output of current motor modulation level: 1 V corresponds to 10% modulation level. 10 V corresponds to 100% modulation level.
KL3	2, 8	GND	Reference ground for control interface, SELV
KL3	3, 7	0-10 V	Use control / current sensor value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (±3%), max. 10 mA, power supply for external devices (e.g. potentiometer), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25%/-10%), max. 50 mA, power supply for external devices (e.g. sensors), SELV
KL3	6	4-20 mA	Use control / current sensor value input 4-20 mA, impedance 100 Ω only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for MODBUS, RSB
KL3	10, 12	RSA	RS485 interface for MODBUS, RSA



Curves: Air performance 50 Hz



$\rho = 1.15 \text{ kg/m}^3 \pm 2 \%$

Measurement: LU-120677-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebmpapst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	Wired	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	LwA _{out}	q _v	p _{fs}	q _v	p _{fs}
		V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m ³ /h	Pa	cfm	in. wg
1	3~	400	50	610	380	0.69	60	68	67	19635	0	11555	0.00
2	3~	400	50	610	471	0.79	58	66	65	17130	30	10080	0.12
3	3~	400	50	610	543	0.89	59	66	65	14360	55	8450	0.22
4	3~	400	50	610	625	1.10	64	72	72	9995	85	5885	0.34
5	3~	400	50	550	270	0.49	58	65	64	17515	0	10310	0.00
6	3~	400	50	550	339	0.57	56	63	62	15350	24	9035	0.10
7	3~	400	50	550	389	0.64	56	63	62	12845	44	7560	0.18
8	3~	400	50	550	448	0.72	62	69	70	8950	68	5265	0.27
9	3~	400	50	450	148	0.27	53	60	59	14330	0	8435	0.00
10	3~	400	50	450	186	0.31	51	58	57	12560	16	7395	0.06
11	3~	400	50	450	213	0.35	51	58	57	10510	29	6185	0.12
12	3~	400	50	450	245	0.39	57	64	65	7320	46	4310	0.18
13	3~	400	50	350	70	0.13	46	54	53	11145	0	6560	0.00
14	3~	400	50	350	87	0.15	44	52	51	9770	10	5750	0.04
15	3~	400	50	350	100	0.16	44	51	51	8175	18	4810	0.07
16	3~	400	50	350	115	0.19	50	58	58	5695	28	3350	0.11

Wired = Wiring · U = Voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side · LwA_{out} = Sound power level outlet side · q_v = Air flow · p_{fs} = Pressure increase

