



A3G910-AO83-01 ebmpapst Datasheet
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Nominal data

Type	A3G910-AO83-01	
Motor	M3G112-IA	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
Speed (rpm)	min ⁻¹	610
Power input	W	625
Current draw	A	1.1
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	60

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
 Subject to alterations

Data according to ErP directive

		Actual	Request 2015		
01 Overall efficiency η_{es}	%	45.5	32.2	09 Power input P_{ed}	kW
02 Measurement category		A		09 Air flow q_v	m ³ /h
03 Efficiency category		Static		09 Pressure increase p_{fs}	Pa
04 Efficiency grade N		53.3	40	10 Speed (rpm) n	min ⁻¹
05 Variable speed drive		Yes		11 Specific ratio*	1.00

Data definition with optimum efficiency.
 The ErP data is determined using a motor-impeller combination in a standardised measurement configuration.

* Specific ratio = $1 + p_{fs} / 100\,000\text{ Pa}$

LU-120677

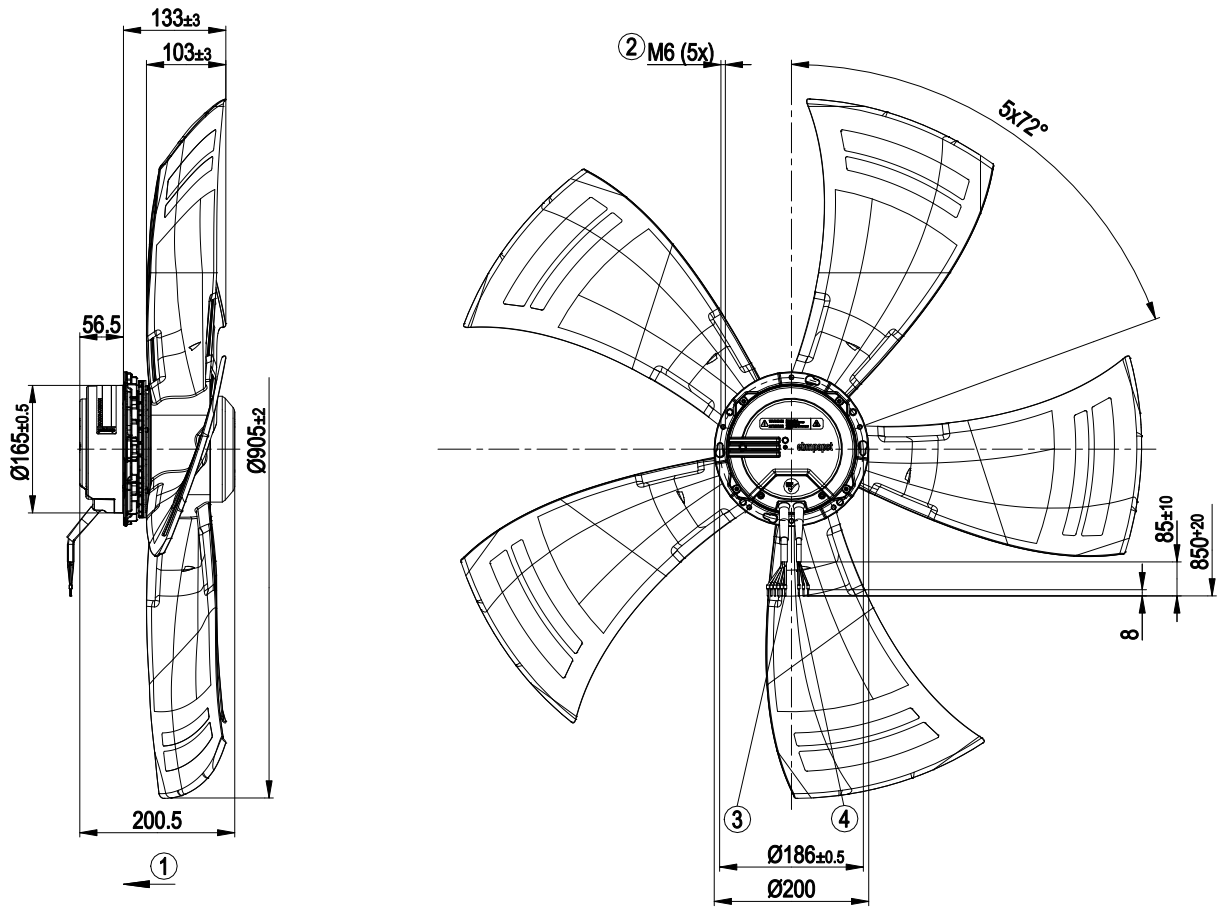


Technical features

Mass	12.3 kg
Size	910 mm
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium, coated in black
Material of blades	Press-fitted sheet steel blank, sprayed with PP plastic
Material of guard grille	Steel, coated in black plastic (RAL9005)
Number of blades	5
Direction of air flow	"V"
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP 54
Insulation class	"B"
Humidity (F)/environmental protection class (H)	F4-1
Max. permissible ambient motor temp. (transp./ storage)	+ 80 °C
Min. permissible ambient motor temp. (transp./storage)	- 40 °C
Mounting position	Shaft horizontal or rotor on bottom
Condensate discharge holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	<ul style="list-style-type: none"> - Output 10 VDC, max. 10 mA - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection
EMC interference immunity	Acc. to EN 61000-6-2 (industrial environment)
EMC harmonics	Acc. to EN 61000-3-2/3
EMC interference emission	Acc. to EN 61000-6-4 (industrial environment)
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Motor protection	Thermal overload protector (TOP) wired internally
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE
Approval	CCC; EAC



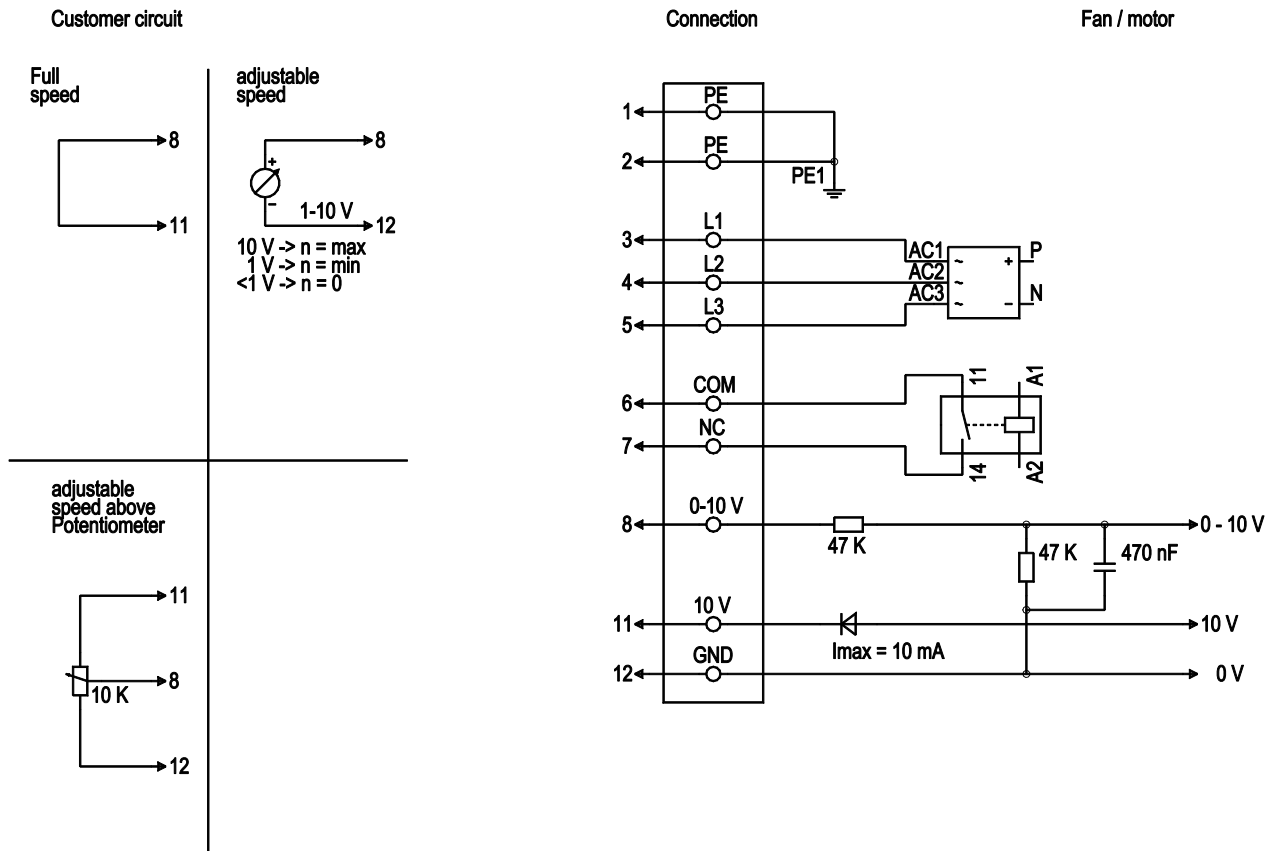
Product drawing



1	Direction of air flow "V"
2	Depth of screw 12 - 16 mm
3	Connection line PVC AWG18, 6x crimped core-end sleeves
4	Connection line PVC AWG22, 3x crimped core-end sleeves



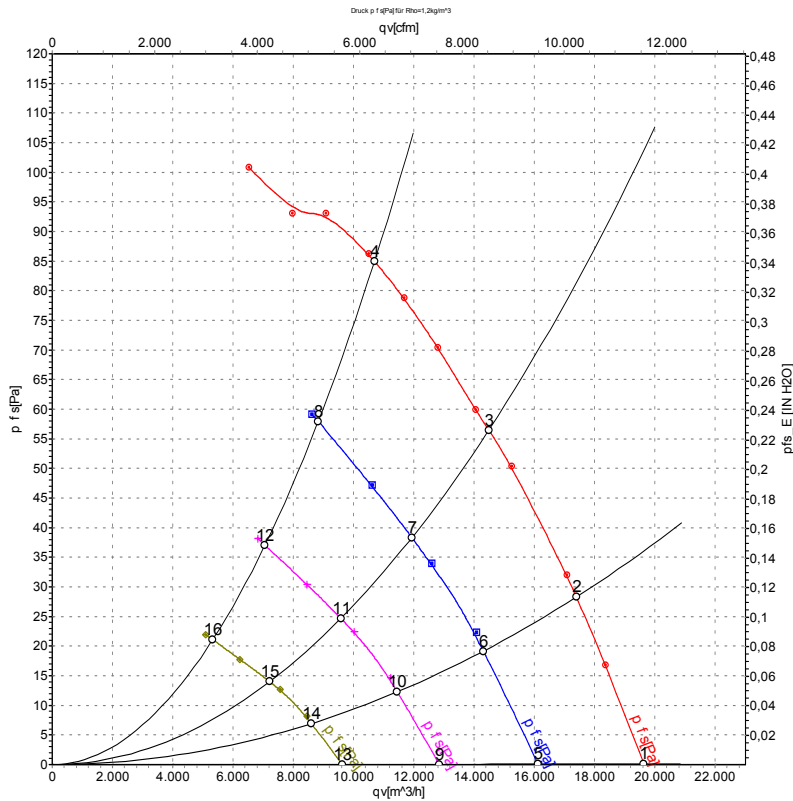
Connection screen



No.	Conn.	Designation	Colour	Function / assignment
1	1, 2	PE	green/yellow	Protective earth
1	3, 4, 5	L1, L2, L3	black	Supply voltage 50 / 60 Hz
1	6	COM	white 1	Floating status contact, break for failure (2 A, max. 250 VAC, min. 10 mA, AC1)
1	7	NC	white 2	Floating status message contact, break for failure
2	8	0 - 10 V	yellow	Control input, set value 0 - 10 VDC, impedance 100 kOhm, SELV
2	11	+ 10 V	red	Voltage output 10 VDC (+/-3%), max. 10 mA, supply voltage for ext. devices (e.g. potentiometer), SELV
2	12	GND	blue	Reference mass for control interface, SELV



Charts: Air flow 50 Hz



Measurement: LU-120677-1
 Measurement: LU-120687-1
 Measurement: LU-120688-1
 Measurement: LU-120689-1

Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebmpapst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

Measured values

	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	LwA _{out}	q _v	P _{fs}	q _v	P _{fs}
	V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m ³ /h	Pa	cfm	inH ₂ O
1	400	50	610	380	0.69	60	68	67	19630	0	11555	0.00
2	400	50	610	463	0.77	59	66	65	17390	28	10235	0.11
3	400	50	610	541	0.89	58	66	65	14480	56	8525	0.22
4	400	50	610	625	1.10	62	70	70	10690	85	6290	0.34
5	400	50	505	213	0.43	56	62	61	16120	0	9490	0.00
6	400	50	505	259	0.51	55	61	60	14300	20	8415	0.08
7	400	50	505	300	0.57	55	61	60	11930	38	7020	0.15
8	400	50	505	340	0.63	56	63	63	8825	58	5195	0.23
9	400	50	405	120	0.28	50	56	56	12830	0	7550	0.00
10	400	50	405	143	0.32	52	56	55	11440	13	6735	0.05
11	400	50	405	165	0.35	50	55	54	9575	25	5635	0.10
12	400	50	405	185	0.38	50	57	57	7060	37	4155	0.15
13	400	50	305	63	0.18	41	47	47	9625	0	5665	0.00
14	400	50	305	71	0.20	43	49	49	8595	7	5060	0.03
15	400	50	305	80	0.21	42	48	48	7215	14	4245	0.06
16	400	50	305	89	0.22	42	48	49	5325	21	3135	0.08

U = Supply voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power input · I = Current draw · LpA_{in} = Sound pressure level inlet side · LwA_{in} = Sound power level inlet side · LwA_{out} = Sound power level outlet side
 q_v = Air flow · P_{fs} = Pressure increase

