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Amtsgericht (court of registration) Stuttgart · HRB 590142

Nominal data

Type	A3G800-BA77-51	
Motor	M3G112-EA	

Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60

Method of obtaining data		ml
Speed (rpm)	min ⁻¹	520
Power consumption	W	275
Current draw	A	0.49
Max. back pressure	Pa	55
Max. back pressure	in. wg	0.22
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	60

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to Commission Regulation (EU) 327/2011 (EN 17166)

		Actual	Req. 2015
01 Overall efficiency η_{es}	%	45	30
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		55	40
05 Variable speed drive		Yes	

Data obtained at optimum efficiency level.

The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

09 Power consumption P_{ed}	kW	0.26
09 Air flow q_v	m³/h	8365
09 Pressure increase p_{fs}	Pa	46
10 Speed (rpm) n	min ⁻¹	520
11 Specific ratio*		1.00

* Specific ratio = $1 + p_s / 100\,000\text{ Pa}$

LU-164182

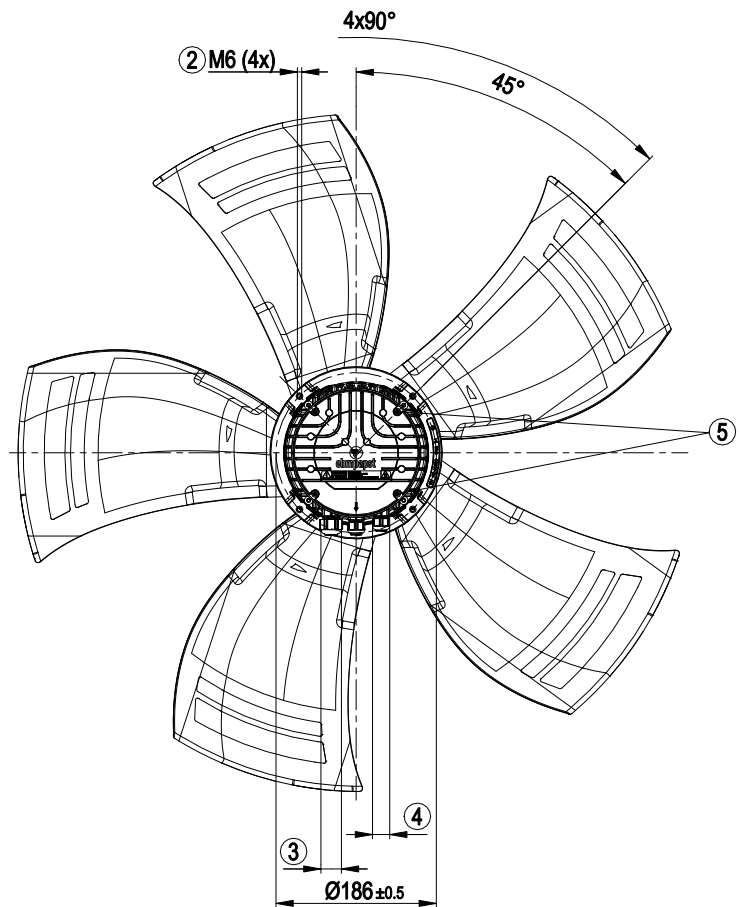
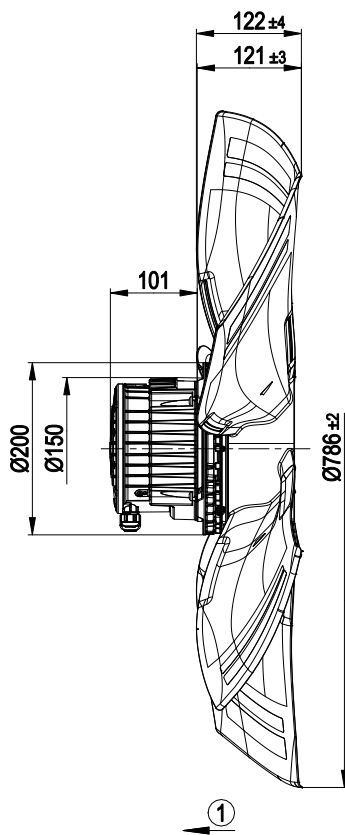


Technical description

Weight	8.75 kg
Size	800 mm
Motor size	112
Rotor surface	Painted black
Terminal box material	PP plastic
Electronics housing material	Die-cast aluminum, painted black
Blade material	Press-fitted sheet steel blank, sprayed with PP plastic
Number of blades	5
Airflow direction	V
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	"F"
Moisture (F) / Environmental (H) protection class	H2
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing; (sealed)
Technical features	- Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (parameter setting) - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - EEPROM write cycles: 100,000 maximum - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Terminal box
Motor protection	Thermal overload protector (TOP) internally connected
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approval	CSA C22.2 No. 77 + CAN/CSA-E60730-1; UL 1004-7 + 60730-1; CCC; EAC
Comment	Conformity with standard EN 60335-1 on request

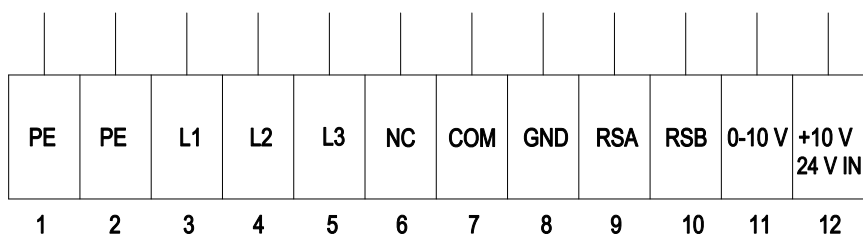


Product drawing



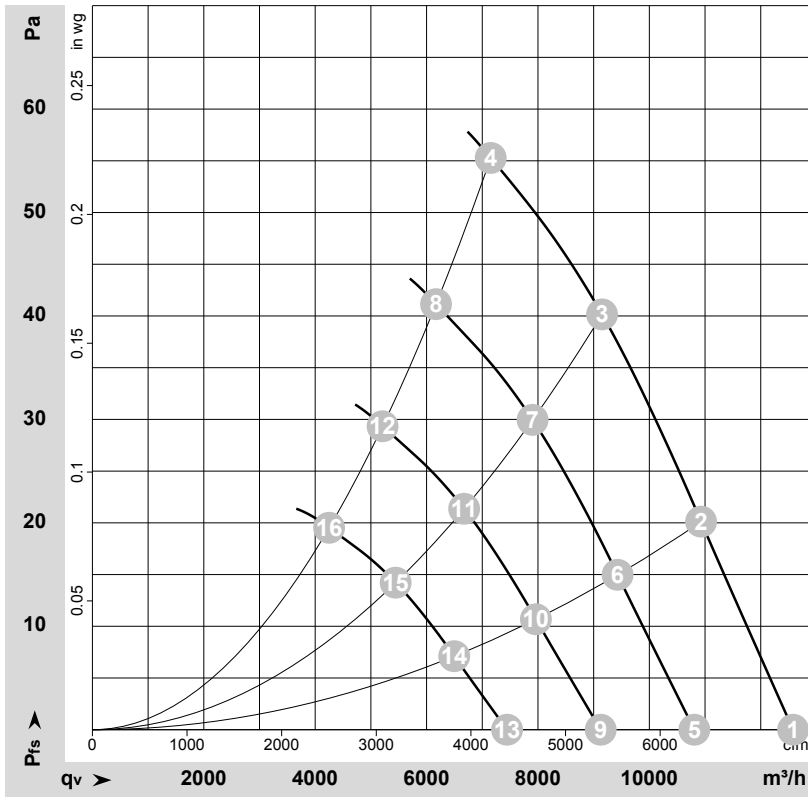
1	Direction of air flow "V"
2	Max. clearance for screw 16 mm
3	Cable diameter min. 8 mm, max. 12 mm, tightening torque 1.8±0.3 Nm (use must be made of seal provided) Cable diameter min. 4 mm, max. 10 mm, tightening torque 1.8±0.3 Nm
4	Cable diameter min. 6 mm, max. 10 mm, tightening torque 1.8±0.3 Nm (use must be made of seal provided) Cable diameter min. 4 mm, max. 7 mm, tightening torque 1.8±0.3 Nm
5	Tightening torque 1.5 ± 0.2 Nm

Connection diagram



No.	Conn.	Designation	Function/assignment
1	PE	PE	Protective earth
2	PE	PE	Protective earth
3	L1	L1	Power supply
4	L2	L2	Power supply
5	L3	L3	Power supply
6	NC	NC	Status relay, floating status contact, break for failure, contact rating 250 VAC / 2 A (AC1) / min. 10 mA; reinforced insulation on supply side and basic insulation on control interface side
7	COM	COM	Status relay, floating status contact, break for failure, contact rating 250 VAC / 2 A (AC1) / min. 10 mA; reinforced insulation on supply side and basic insulation on control interface side
8	GND	GND	Reference ground for control interface, SELV
9	RSA	RSA	RS485 interface for MODBUS, RSA; SELV
10	RSB	RSB	RS485 interface for MODBUS, RSB; SELV
11	0-10 V	0-10 V	Analog input (set value) SELV, 0-10 V, Ri = 100 kΩ, adjustable curve
12	+10 V	+10 V	Fixed voltage output 10 VDC, SELV, +10 V ±3%, max. 10 mA, short-circuit-proof, power supply for external devices (e.g. pot); fixed voltage input 24 VDC for setting parameters via MODBUS without line voltage supply

Curves: Air performance 50 Hz



$$\rho = 1.15 \text{ kg/m}^3 \pm 2 \%$$

Measurement: LU-180191-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	LwA _{out}	q _v	p _{fs}	q _v	p _{fs}
	V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m ³ /h	Pa	cfm	in. wg
1	400	50	520	177	0.37	56	62	62	12580	0	7405	0.00
2	400	50	520	212	0.41	52	59	58	10930	20	6435	0.08
3	400	50	520	242	0.45	51	57	56	9150	40	5385	0.16
4	400	50	520	275	0.49	54	61	61	7150	55	4210	0.22
5	400	50	450	112	0.23	52	59	58	10810	0	6360	0.00
6	400	50	450	136	0.26	49	55	54	9430	15	5550	0.06
7	400	50	450	156	0.29	47	54	53	7905	30	4650	0.12
8	400	50	450	172	0.31	50	57	57	6170	41	3630	0.16
9	400	50	380	68	0.14	48	54	54	9125	0	5370	0.00
10	400	50	380	82	0.16	44	51	50	7965	11	4685	0.04
11	400	50	380	94	0.17	43	49	48	6675	21	3930	0.08
12	400	50	380	104	0.19	46	53	53	5210	29	3065	0.12
13	400	50	310	37	0.08	43	49	48	7445	0	4380	0.00
14	400	50	310	44	0.09	39	46	45	6495	7	3825	0.03
15	400	50	310	51	0.09	38	44	43	5445	14	3205	0.06
16	400	50	310	56	0.10	40	48	48	4250	20	2500	0.08

U = Voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
 LwA_{out} = Sound power level outlet side · q_v = Air flow · p_{fs} = Pressure increase

