

A3G800-AV01-61 ebmpapst Datasheet

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Nominal data

Type	A3G800-AV01-61	
Motor	M3G150-NA	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
Speed (rpm)	min ⁻¹	1090
Power input	W	2980
Current draw	A	4.5
Max. back pressure	Pa	260
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	65

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations

Data according to ErP directive

		Actual	Request 2015
01 Overall efficiency η_{es}	%	43.2	36.3
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		46.9	40
05 Variable speed drive		Yes	

Data definition with optimum efficiency.

The ErP data is determined using a motor-impeller combination in a standardised measurement configuration.

09 Power input P_{ed}	kW	2.6
09 Air flow q_v	m³/h	18115
09 Pressure increase p_{fs}	Pa	212
10 Speed (rpm) n	min ⁻¹	1080
11 Specific ratio*		1.00

* Specific ratio = $1 + p_{fs} / 100\,000\text{ Pa}$

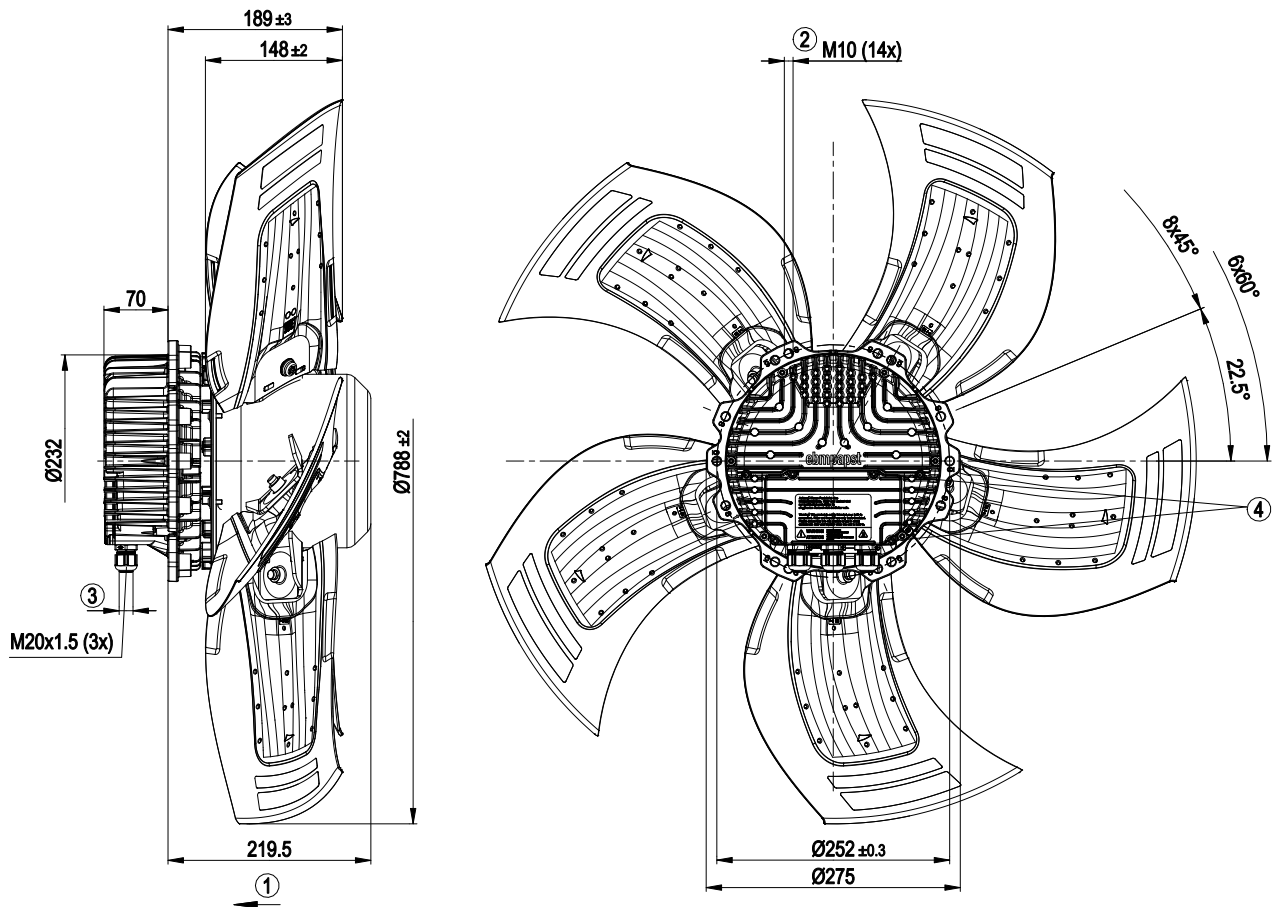
LU-113933



Technical features

Mass	31.2 kg
Size	800 mm
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium, coated in black
Material of blades	Aluminium sheet insert, sprayed with PP plastic
Number of blades	5
Blade angle	0°
Direction of air flow	"V"
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP 55
Insulation class	"F"
Humidity (F)/environmental protection class (H)	F4-1
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Shaft horizontal or rotor on bottom
Condensate discharge holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - External 24 V input (programming) - External release input - Alarm relay - Integrated PID controller - Output limit - Motor current limit - PFC, passive - RS485 MODBUS RTU - Soft start -Maximum EEPROM write cycles 100,000 - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical leads	Via terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE
Approval	C22.2 Nr.77 + CAN/CSA-E60730-1; EAC; UL 1004-7 + 60730

Product drawing



1	Direction of air flow "V"
2	Thread reach max. 25 mm
3	Cable diameter min. 4 mm, max. 10 mm, tightening torque 4 ± 0.6 Nm
4	Tightening torque 3.5 ± 0.5 Nm

Connection screen

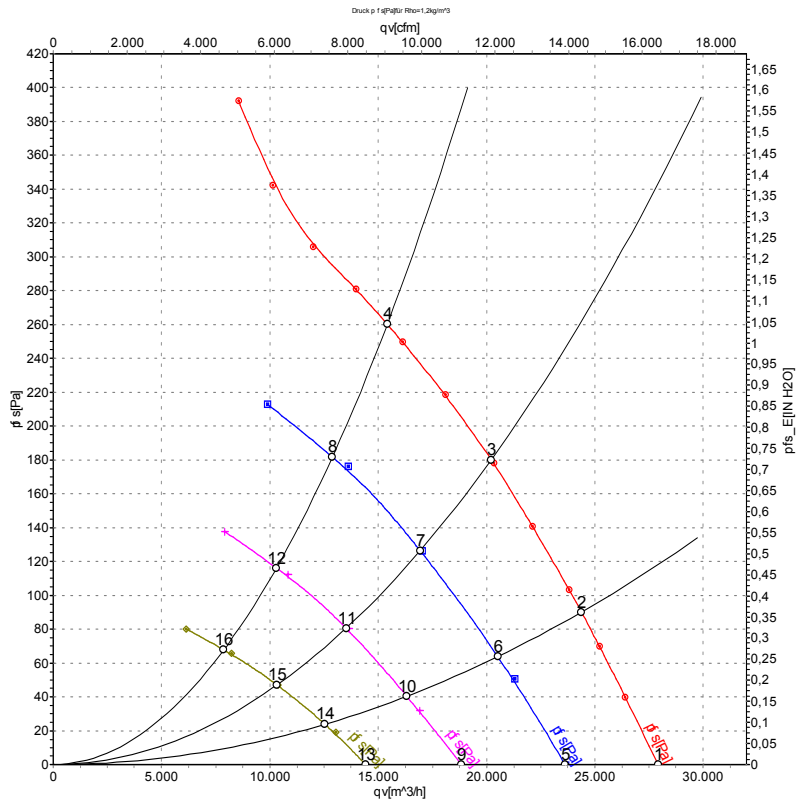
1	2	3	4	5	6	7	8	9	10	11	12	13	14
RSA	RSB	GND	Ain 1 U	+ 10 V	Ain 1 I	Din 1	Din 2	Din 3	GND	Ain 2 U	+ 20 V	Ain 2 I	Aout
KL 3	KL 2	PE	KL 1										

No.	Conn.	Designation	Function / assignment
KL 1	1	L1	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
KL 1	2	L2	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
KL 1	3	L3	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
PE		PE	Earth connection, PE connection
KL 2	1	NO	Status relay, floating status contact; normally open; close with error
KL2	2	COM	Status relay; floating status contact; changeover contact; common connection; contact rating 250 VAC / max. 2 A (AC1) / min. 10 mA
KL2	3	NC	Status relay, floating status contact; break with error
KL 3	1	RSA	Bus connection RS-485, RSA, MODBUS RTU; SELV
KL 3	2	RSB	Bus connection RS-485, RSB, MODBUS RTU; SELV
KL 3	3 / 10	GND	Signal ground for control interface; SELV
KL 3	4	Ain1 U	Analogue input 1, set value: 0-10 V, Ri = 100 kΩ, parametrisable curve, only usable as alternative to input Ain1; SELV
KL 3	5	+ 10 V	Fixed voltage output 10 VDC, +10 V ±3%, max. 10 mA, short-circuit-proof, power supply for external devices (e.g. potentiometer), SELV
KL 3	6	Ain1 I	Analogue input 1, set value: 4-20 mA; Ri = 100 Ω, parametrisable curve, only usable as alternative to input Ain1 U; SELV
KL 3	7	Din1	Digital input 1: enabling of electronics, enabling: open pin or applied voltage 5-50 VDC disabling: bridge to GND or applied voltage <1 VDC reset function: triggers software reset after a level change to <1 VDC; SELV
KL 3	8	Din2	Digital input 2: parameter set switch 1/2, according to EEPROM setting, the valid/used parameter set can be selected via bus or via digital input DIN2. Parameter set 1: open pin or applied voltage 5-50 VDC Parameter set 2: bridge to GND or applied voltage <1 VDC; SELV
KL 3	9	Din3	Digital input 3: controller function of integrated controller, according to EEPROM setting, the controller function of the integrated controller is normally/inversely selectable per bus or per digital input normal: open pin or applied voltage 5-50 VDC inverse: bridge to GND or applied voltage <1 VDC; SELV
KL 3	11	Ain2 U	Analogue input 2, actual value: 0-10 V, Ri = 100 kΩ, parametrisable curve, only usable as alternative to input Ain2; SELV
KL 3	12	+ 20 V	Fixed voltage output 20 VDC, +20 V ±5/-10%, max. 50 mA, short-circuit-proof, power supply for external devices (e.g. sensors); SELV

No.	Conn.	Designation	Function / assignment
KL 3	13	Ain2 I	Analogue input 2, actual value: 4-20 mA, $R_i = 100\ \Omega$, parametrisable curve, only usable as alternative to input Ain2 U; SELV
KL 3	14	Aout	Analogue output 0-10 VDC, max. 5 mA, output of the current motor level control coefficient / motor speed parametrisable curve; SELV



Charts: Air flow 50 Hz



Measurement: LU-113933-1
 Measurement: LU-115163-1
 Measurement: LU-115164-1
 Measurement: LU-118094-1

Air performance measured as per ISO 5801
 Installation category A. For detailed
 information on the measuring set-up, please
 contact ebm-papst. Suction-side noise
 levels: L_{wA} measured as per ISO 13347 /
 L_{pA} measured with 1m distance to fan axis.
 The values given are valid under the
 measuring conditions mentioned above and
 may vary according to the actual installation
 situation. With any deviation from the
 standard set-up, the specific values have to
 be checked and reviewed with the unit
 installed.

Measured values

	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	LwA _{out}	q _v	P _{fs}	q _v	P _{fs}
	V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m³/h	Pa	cfm	inH ₂ O
1	400	50	1090	1867	2.84	69	76	77	27930	0	16440	0.00
2	400	50	1090	2196	3.34	69	76	76	24380	90	14350	0.36
3	400	50	1090	2520	3.85	72	78	77	20220	180	11900	0.72
4	400	50	1090	2980	4.50	76	84	83	15420	260	9075	1.04
5	400	50	905	1037	1.62	64	71	72	23630	0	13910	0.00
6	400	50	905	1248	1.93	64	71	71	20520	65	12080	0.26
7	400	50	905	1408	2.16	66	73	72	16940	128	9970	0.51
8	400	50	905	1577	2.43	71	79	78	12880	183	7580	0.73
9	400	50	720	547	0.93	59	65	65	18840	0	11090	0.00
10	400	50	720	647	1.06	59	65	65	16320	41	9605	0.16
11	400	50	720	736	1.19	61	67	66	13520	82	7960	0.33
12	400	50	720	808	1.29	65	73	72	10300	117	6060	0.47
13	400	50	550	252	0.53	53	60	59	14410	0	8480	0.00
14	400	50	550	308	0.62	53	59	59	12540	24	7380	0.10
15	400	50	550	347	0.68	53	60	59	10330	48	6080	0.19
16	400	50	550	366	0.73	57	65	64	7870	68	4630	0.27

U = Supply voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power input · I = Current draw · LpA_{in} = Sound pressure level inlet side · LwA_{in} = Sound power level inlet side · LwA_{out} = Sound power level outlet side
 q_v = Air flow · P_{fs} = Pressure increase

