

Nominal data

| | | |
|--------------------------|-------------------|------------|
| Type | A3G800-AO81-35 | |
| Motor | M3G112-IA | |
| Phase | | 1~ |
| Nominal voltage | VAC | 230 |
| Nominal voltage range | VAC | 200 .. 277 |
| Frequency | Hz | 50/60 |
| Type of data definition | | ml |
| Speed (rpm) | min ⁻¹ | 710 |
| Power input | W | 730 |
| Current draw | A | 3.2 |
| Max. back pressure | Pa | 100 |
| Min. ambient temperature | °C | -25 |
| Max. ambient temperature | °C | 50 |

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations

Data according to ErP directive

| | | Actual | Request 2015 | | |
|-----------------------------------|---|--------|--------------|-------------------------------|-------------------|
| 01 Overall efficiency η_{es} | % | 43.7 | 32.6 | 09 Power input P_{ed} | kW |
| 02 Measurement category | | A | | 09 Air flow q_v | m ³ /h |
| 03 Efficiency category | | Static | | 09 Pressure increase p_{fs} | Pa |
| 04 Efficiency grade N | | 51.1 | 40 | 10 Speed (rpm) n | min ⁻¹ |
| 05 Variable speed drive | | Yes | | 11 Specific ratio* | 1.00 |

Data definition with optimum efficiency.
The ErP data is determined using a motor-impeller combination in a standardised measurement configuration.

* Specific ratio = $1 + p_{fs} / 100\,000\text{ Pa}$

LU-121620



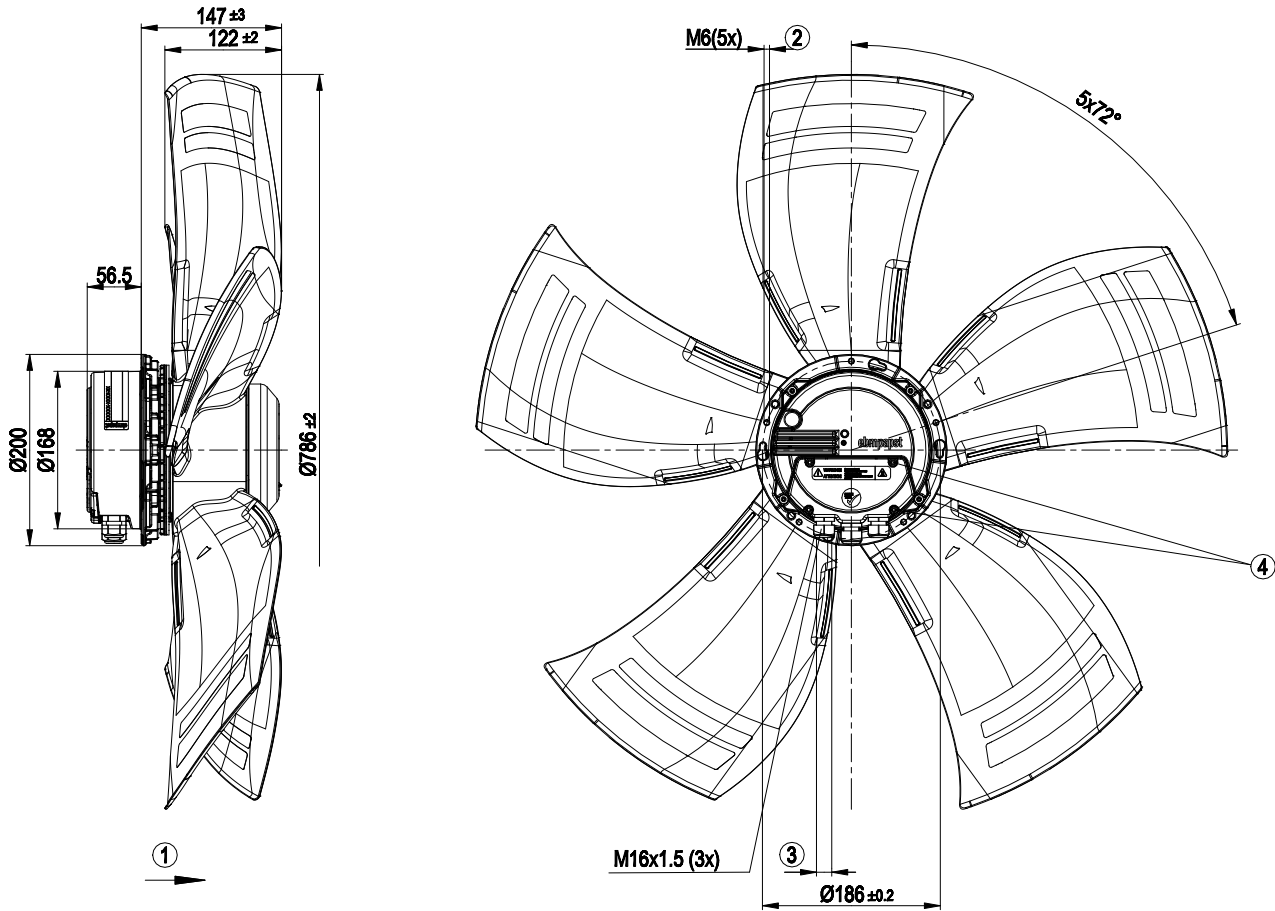
Technical features

| | |
|--|---|
| Mass | 11.9 kg |
| Size | 800 mm |
| Surface of rotor | Coated in black |
| Material of electronics housing | Die-cast aluminium, coated in black |
| Material of blades | Press-fitted, coated sheet steel blank, sprayed with PP plastic |
| Number of blades | 5 |
| Direction of air flow | "A" |
| Direction of rotation | Counter-clockwise, seen on rotor |
| Type of protection | IP 54 |
| Insulation class | "B" |
| Humidity (F)/environmental protection class (H) | F4-2 |
| Max. permissible ambient motor temp. (transp./ storage) | + 80 °C |
| Min. permissible ambient motor temp. (transp./storage) | - 40 °C |
| Mounting position | Shaft horizontal or rotor on top; rotor on bottom on request |
| Condensate discharge holes | On the stator side |
| Operation mode | S1 |
| Motor bearing | Ball bearing |
| Technical features | <ul style="list-style-type: none"> - Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Operation and alarm display - Direction of rotation selection counter-clockwise / clockwise - Input for sensor 0-10 V or 4-20 mA - External 24 V input (programming) - Alarm relay - Integrated PID controller - Motor current limit - PFC, active - RS485 MODBUS RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection |
| Touch current acc. IEC 60990 (measuring network Fig. 4, TN system) | <= 3.5 mA |
| Electrical leads | Via terminal box |
| Motor protection | Thermal overload protector (TOP) wired internally |
| Protection class | I (if protective earth is connected by customer) |
| Product conforming to standard | EN 61800-5-1; CE |
| Approval | EAC |

EC axial fan - HyBlade

sickled blades (S series)
for agricultural ventilation

Product drawing



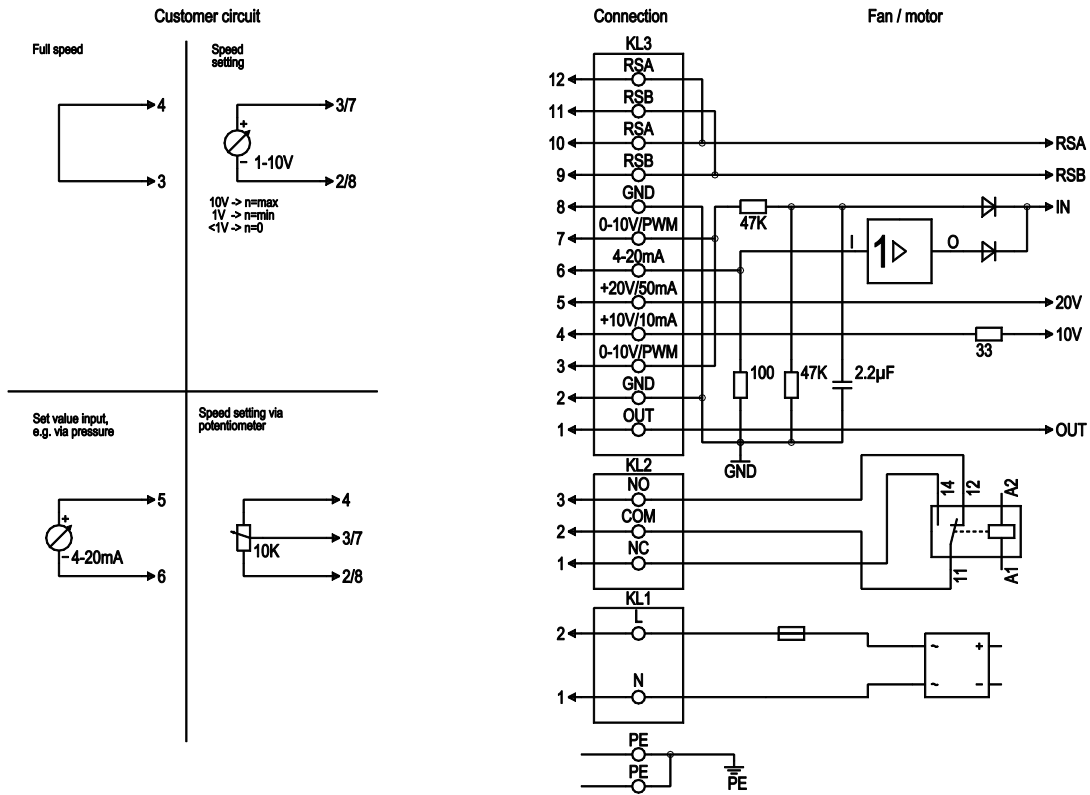
| | |
|---|--|
| 1 | Direction of air flow "A" |
| 2 | Depth of screw max. 16 mm |
| 3 | Cable diameter: min. 4 mm, max. 10 mm, tightening torque: 2.5±0.4 Nm |
| 4 | Tightening torque 3.5±0.5 Nm |



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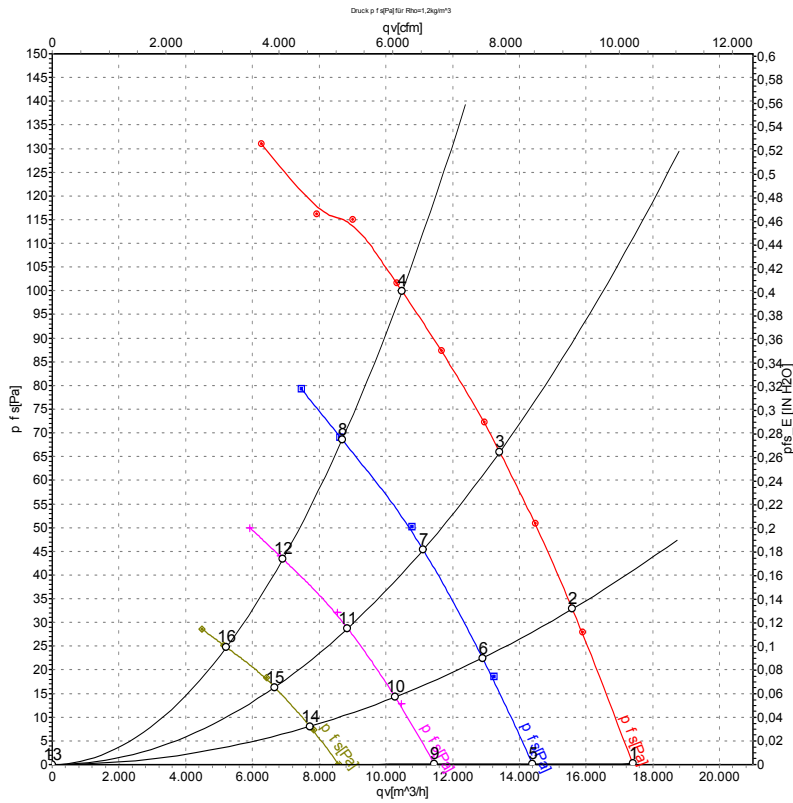
Connection screen



| No. | Conn. | Designation | Function / assignment |
|-----|--------|-------------|---|
| PE | - | PE | Protective earth connection |
| KL1 | 1, 2 | N, L | Supply voltage, 50/60 Hz |
| KL2 | 1 | NC | Floating status message contact, break for failure |
| KL2 | 2 | COM | Floating status message contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1) |
| KL2 | 3 | NO | Floating status message contact, normally open, make for failure |
| KL3 | 1 | OUT | Analogue output, 0-10 VDC, max. 3 mA, SELV, Output of the current motor level control coefficient: 1 V corresponds to 10% level control coefficient, 10 V correspond to 100% level control coefficient. |
| KL3 | 2, 8 | GND | Reference mass for control interface, SELV |
| KL3 | 3, 7 | 0-10 V | Use control / actual value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV |
| KL3 | 4 | +10 V | Voltage output 10 VDC (+/- 3%), max. 10 mA, Supply voltage for ext. devices (e.g. potentiometer), SELV |
| KL3 | 5 | +20 V | Voltage output 20 VDC (+25%/-10%), max. 50 mA Supply voltage for ext. devices (e.g. sensors), SELV |
| KL3 | 6 | 4-20 mA | Use control / actual value input 4-20 mA, impedance 100 Ω, only as alternative to 0-10 V input, SELV |
| KL3 | 9, 11 | RSB | RS485 interface for MODBUS, RSB |
| KL3 | 10, 12 | RSA | RS485 interface for MODBUS, RSA |



Charts: Air flow 50 Hz



Measurement: LU-121620-1
Measurement: LU-121634-1
Measurement: LU-121635-1
Measurement: LU-121636-1

Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebmpapst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

Measured values

| | U | f | n | P _{ed} | I | LpA _{in} | LwA _{in} | LwA _{out} | q _v | P _{fs} | q _v | P _{fs} |
|----|-----|----|-------------------|-----------------|------|-------------------|-------------------|--------------------|-------------------|-----------------|----------------|--------------------|
| | V | Hz | min ⁻¹ | W | A | dB(A) | dB(A) | dB(A) | m ³ /h | Pa | cfm | inH ₂ O |
| 1 | 230 | 50 | 710 | 462 | 2.15 | 63 | 70 | 70 | 17400 | 0 | 10240 | 0.00 |
| 2 | 230 | 50 | 710 | 549 | 2.51 | 60 | 66 | 66 | 15590 | 33 | 9175 | 0.13 |
| 3 | 230 | 50 | 710 | 634 | 2.86 | 58 | 65 | 64 | 13410 | 66 | 7895 | 0.26 |
| 4 | 230 | 50 | 710 | 730 | 3.20 | 61 | 69 | 69 | 10490 | 100 | 6175 | 0.40 |
| 5 | 230 | 50 | 590 | 264 | 1.25 | 59 | 65 | 65 | 14390 | 0 | 8470 | 0.00 |
| 6 | 230 | 50 | 590 | 309 | 1.44 | 56 | 62 | 62 | 12890 | 23 | 7585 | 0.09 |
| 7 | 230 | 50 | 590 | 352 | 1.64 | 54 | 60 | 60 | 11120 | 46 | 6545 | 0.18 |
| 8 | 230 | 50 | 590 | 395 | 1.84 | 57 | 64 | 64 | 8690 | 69 | 5115 | 0.28 |
| 9 | 230 | 50 | 470 | 188 | 0.69 | 54 | 60 | 60 | 11450 | 0 | 6740 | 0.00 |
| 10 | 230 | 50 | 470 | 164 | 0.78 | 51 | 57 | 57 | 10270 | 15 | 6045 | 0.06 |
| 11 | 230 | 50 | 470 | 186 | 0.88 | 49 | 55 | 55 | 8850 | 29 | 5210 | 0.12 |
| 12 | 230 | 50 | 470 | 208 | 0.98 | 50 | 58 | 57 | 6910 | 44 | 4070 | 0.18 |
| 13 | 230 | 50 | 355 | 138 | 0.74 | 44 | 53 | 54 | 0 | 60 | 0 | 0.24 |
| 14 | 230 | 50 | 355 | 81 | 0.46 | 45 | 51 | 51 | 7715 | 8 | 4540 | 0.03 |
| 15 | 230 | 50 | 355 | 90 | 0.51 | 43 | 49 | 49 | 6670 | 16 | 3925 | 0.06 |
| 16 | 230 | 50 | 355 | 98 | 0.55 | 43 | 50 | 50 | 5220 | 25 | 3075 | 0.10 |

U = Supply voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power input · I = Current draw · LpA_{in} = Sound pressure level inlet side · LwA_{in} = Sound power level inlet side · LwA_{out} = Sound power level outlet side
q_v = Air flow · P_{fs} = Pressure increase

