

A3G630-AS25-71 ebmpapst Datasheet

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Nominal data

Type	A3G630-AS25-71	
Motor	M3G150-FF	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
State		prelim.
Speed (rpm)	min ⁻¹	1230
Power input	W	1750
Current draw	A	2.8
Max. back pressure	Pa	200
Min. ambient temperature	°C	-40
Max. ambient temperature	°C	70

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations

Data according to ErP directive

		Actual	Request 2015
01 Overall efficiency η_{es}	%	37.9	35.2
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		42.7	40
05 Variable speed drive		Yes	

Data definition with optimum efficiency.
The ErP data is determined using a motor-impeller combination in a standardised measurement configuration.

09 Power input P_{ed}	kW	1.78
09 Air flow q_v	m³/h	10495
09 Pressure increase p_{fs}	Pa	217
10 Speed (rpm) n	min ⁻¹	1235
11 Specific ratio*		1.00

* Specific ratio = $1 + p_s / 100\,000\text{ Pa}$

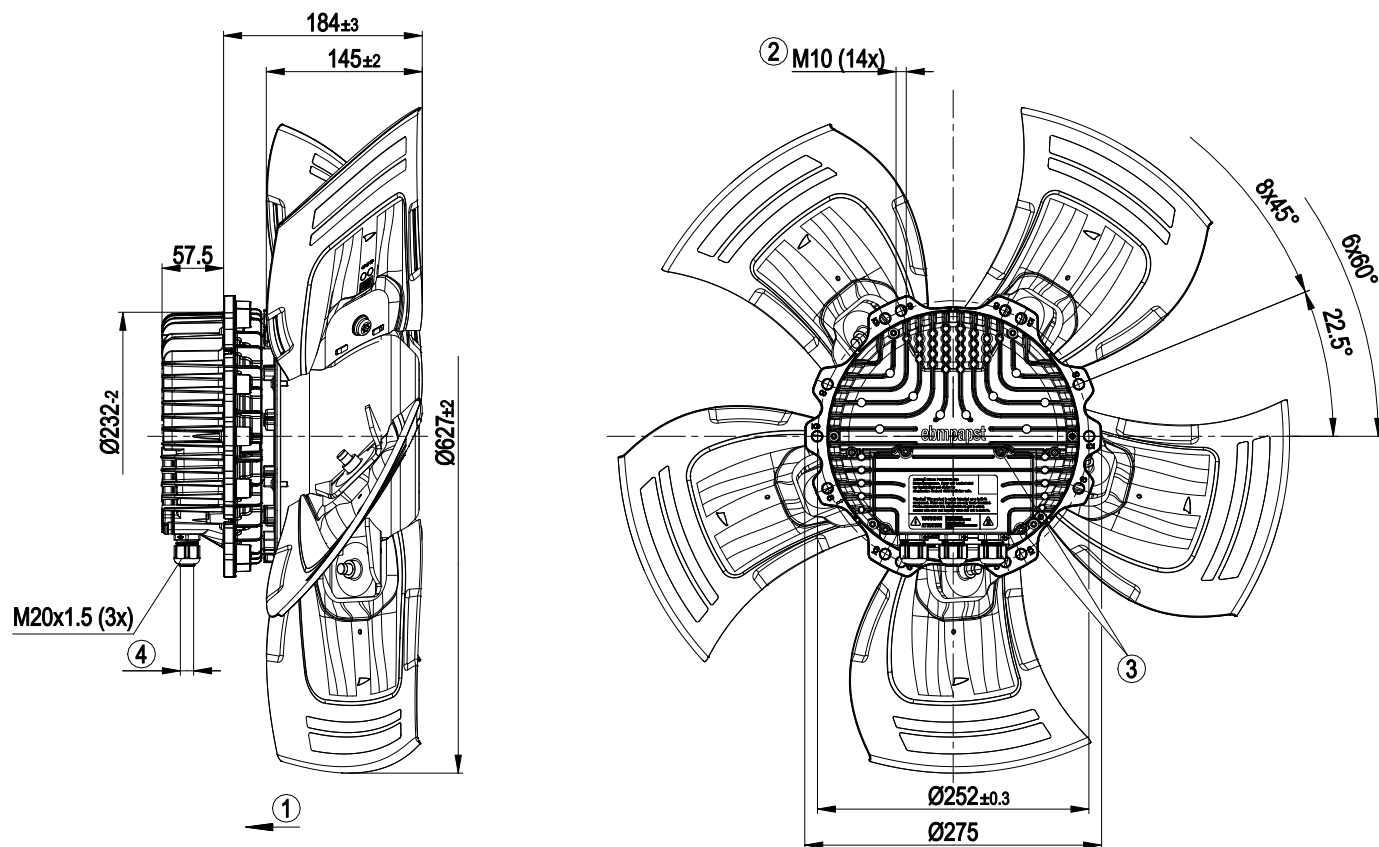
LU-165507



Technical features

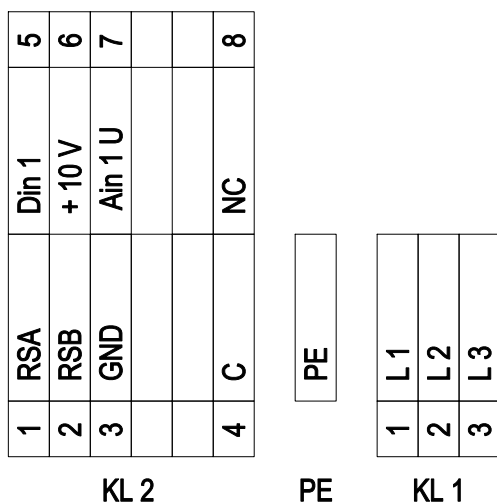
Mass	21.2 kg
Size	630 mm
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium, coated in black
Material of blades	Aluminium sheet insert, sprayed with PP plastic
Number of blades	5
Blade angle	0°
Direction of air flow	"V"
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP 55
Insulation class	"F"
Humidity (F)/environmental protection class (H)	F4-1
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensate discharge holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (programming) - External release input - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive - RS485 MODBUS RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical leads	Via terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE
Approval	EAC

Product drawing



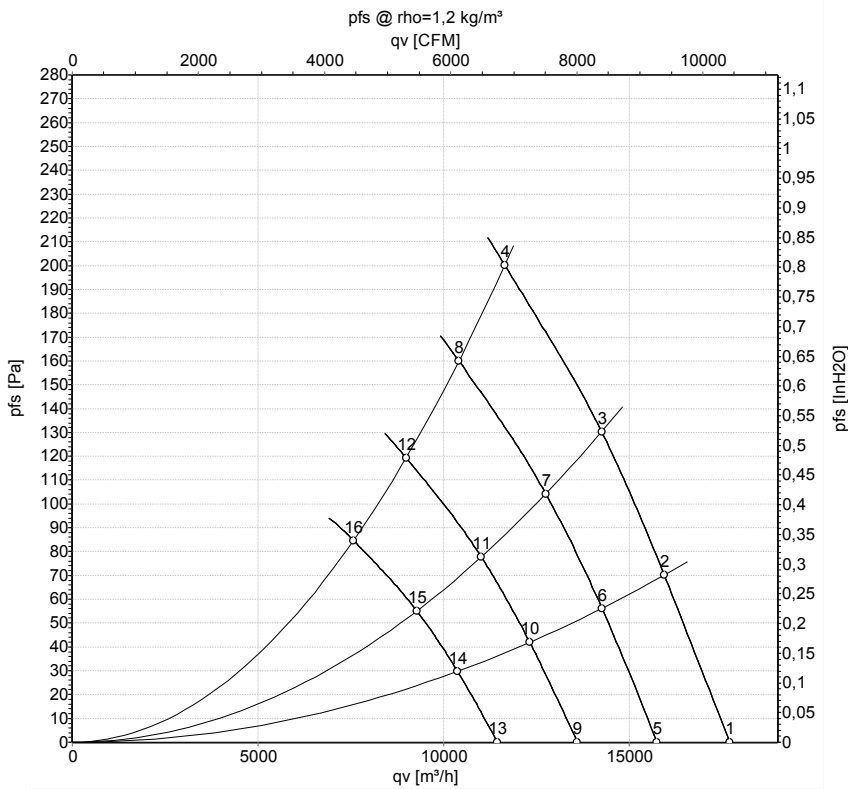
1	Direction of air flow "V"
2	Thread reach max. 25 mm
3	Tightening torque 3.5±0.5 Nm
4	Cable diameter min. 4 mm, max. 10 mm, tightening torque 4±0.6 Nm

Connection screen



No.	Conn.	Designation	Function / assignment
KL 1	1	L1	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
KL 1	2	L2	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
KL 1	3	L3	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
PE		PE	Earth connection, PE connection
KL 2	1	RSA	Bus connection RS-485, RSA, MODBUS RTU; SELV
KL 2	2	RSB	Bus connection RS-485, RSB, MODBUS RTU; SELV
KL 2	3	GND	Signal ground for control interface; SELV
KL2	4	C	Status relay; floating status contact; changeover contact; common connection; contact rating 250 VAC / 2 A (AC1)
KL 2	5	Din1	Digital input 1 enabling of electronics, enabling: open pin or applied voltage 5-50 VDC disabling: bridge to GND or applied voltage <1 VDC reset function: triggers software reset after a level change to <1 V; SELV
KL 2	6	+ 10 V	Fixed voltage output 10 VDC; +10 V -3 %, max. 10 mA, short-circuit-proof, power supply for external devices (e.g. potentiometer); SELV Alternative: +24 VDC input for parametrisation via MODBUS without mains power
KL 2	7	Ain1 U	Analogue input 1 (set value) 0-10 V, Ri=100 kΩ, parametrisable curve; SELV
KL2	8	NC	Status relay, floating status contact; break for failure

Charts: Air flow 50 Hz



Measurement: LU-165507-1

Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebm-papst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

Measured values

	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	LwA _{out}	q _v	p _{fs}	q _v	p _{fs}
	V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m³/h	Pa	cfm	inH2O
1	400	50	1230	1378	2.22	68	76	77	17710	0	10425	0.00
2	400	50	1230	1484	2.37	68	75	76	15945	70	9385	0.28
3	400	50	1230	1597	2.54	68	75	76	14260	130	8395	0.52
4	400	50	1230	1750	2.80	71	78	78	11650	200	6855	0.80
5	400	50	1100	969	1.56	65	73	74	15750	0	9270	0.00
6	400	50	1100	1064	1.70	65	72	73	14270	56	8400	0.22
7	400	50	1100	1143	1.81	65	72	73	12755	104	7510	0.42
8	400	50	1100	1236	1.95	68	76	75	10415	160	6130	0.64
9	400	50	950	624	1.01	62	69	70	13605	0	8005	0.00
10	400	50	950	686	1.10	61	69	69	12325	42	7255	0.17
11	400	50	950	736	1.17	61	69	69	11020	78	6485	0.31
12	400	50	950	796	1.26	64	72	71	8995	119	5295	0.48
13	400	50	800	373	0.60	57	65	66	11455	0	6740	0.00
14	400	50	800	409	0.65	57	64	65	10380	30	6110	0.12
15	400	50	800	440	0.70	57	64	65	9280	55	5460	0.22
16	400	50	800	475	0.75	60	68	67	7575	85	4460	0.34

U = Supply voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power input · I = Current draw · LpA_{in} = Sound pressure level inlet side · LwA_{in} = Sound power level inlet side · LwA_{out} = Sound power level outlet side
q_v = Air flow · p_{fs} = Pressure increase

