

A3G500-AM56-35 ebmpapst Datasheet

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Nominal data

Type	A3G500-AM56-35	
Motor	M3G112-EA	
Phase		1~
Nominal voltage	VAC	230
Nominal voltage range	VAC	200 .. 277
Frequency	Hz	50/60
Type of data definition		ml
Speed (rpm)	min ⁻¹	1420
Power input	W	750
Current draw	A	3.4
Max. back pressure	Pa	175
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	60

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations

Data according to ErP directive

		Actual	Request 2015
01 Overall efficiency η_{es}	%	41.6	32.8
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		48.8	40
05 Variable speed drive		Yes	

Data definition with optimum efficiency.

The ErP data is determined using a motor-impeller combination in a standardised measurement configuration.

09 Power input P_{ed}	kW	0.73
09 Air flow q_v	m³/h	5850
09 Pressure increase p_{fs}	Pa	173
10 Speed (rpm) n	min ⁻¹	1425
11 Specific ratio*		1.00

* Specific ratio = $1 + p_{fs} / 100\,000\text{ Pa}$

LU-121382



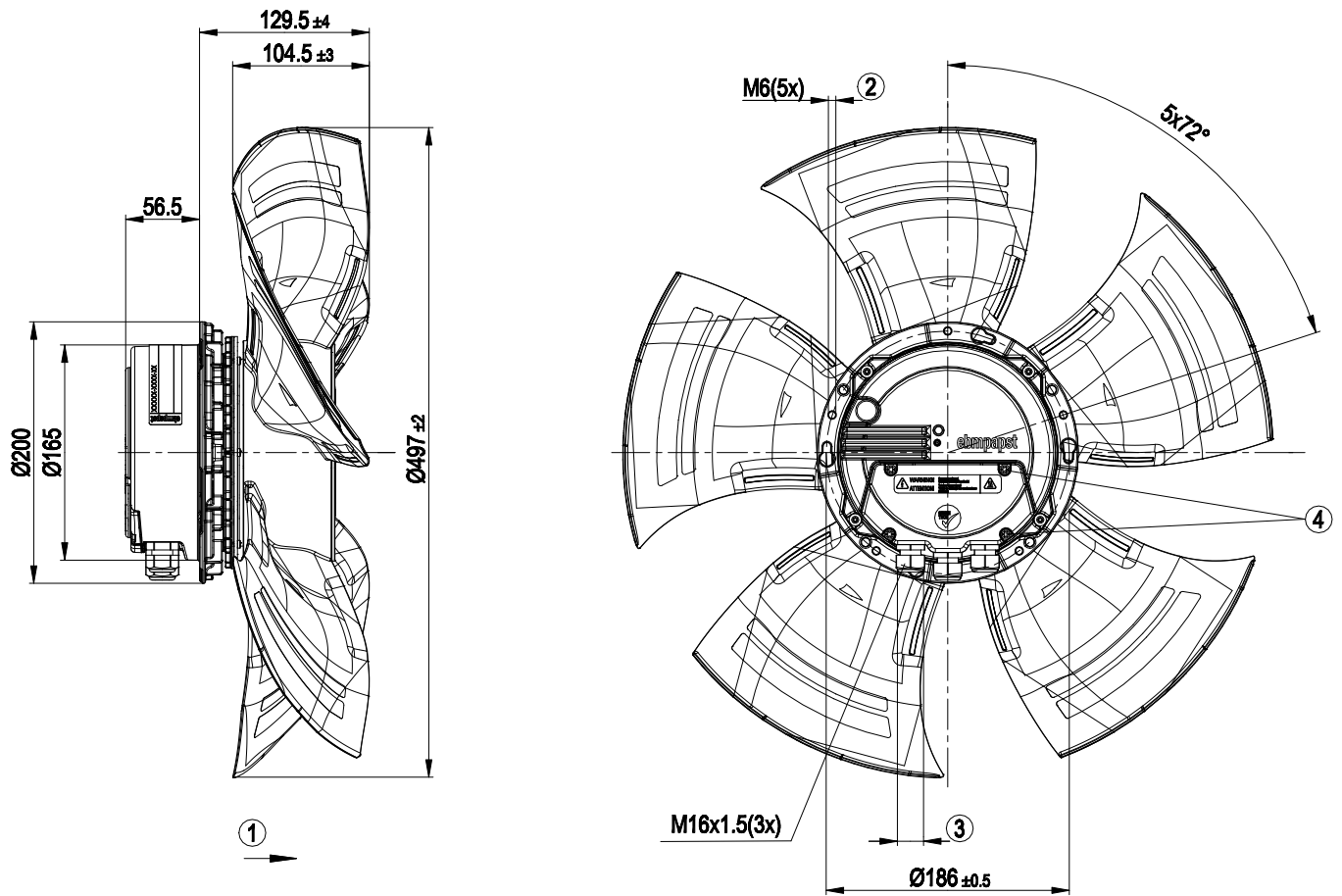
Technical features

Mass	7.7 kg
Size	500 mm
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium, coated in black
Material of blades	Press-fitted, coated sheet steel blank, sprayed with PP plastic
Number of blades	5
Direction of air flow	"A"
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP 54
Insulation class	"B"
Humidity (F)/environmental protection class (H)	F4-2
Max. permissible ambient motor temp. (transp./ storage)	+ 80 °C
Min. permissible ambient motor temp. (transp./storage)	- 40 °C
Mounting position	Shaft horizontal or rotor on top; rotor on bottom on request
Condensate discharge holes	On the stator side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Operation and alarm display - Direction of rotation selection counter-clockwise / clockwise - Input for sensor 0-10 V or 4-20 mA - External 24 V input (programming) - Alarm relay - Integrated PID controller - Output limit - Motor current limit - PFC, active - RS485 MODBUS RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical leads	Via terminal box
Motor protection	Thermal overload protector (TOP) wired internally
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE
Approval	EAC

EC axial fan - HyBlade

sickled blades (S series)
for agricultural ventilation

Product drawing



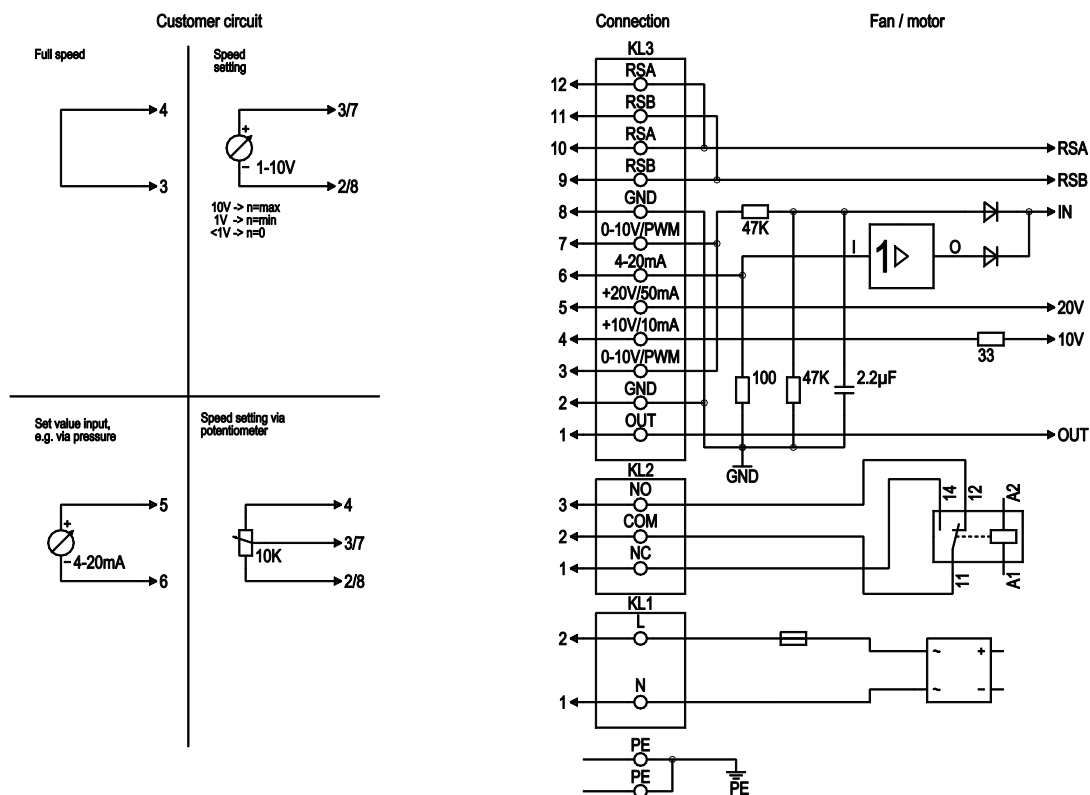
1	Direction of air flow "A"
2	Depth of screw max. 16 mm
3	Cable diameter: min. 4 mm, max. 10 mm; tightening torque: 2.5±0.4 Nm
4	Tightening torque 3.5 Nm±0.5 Nm



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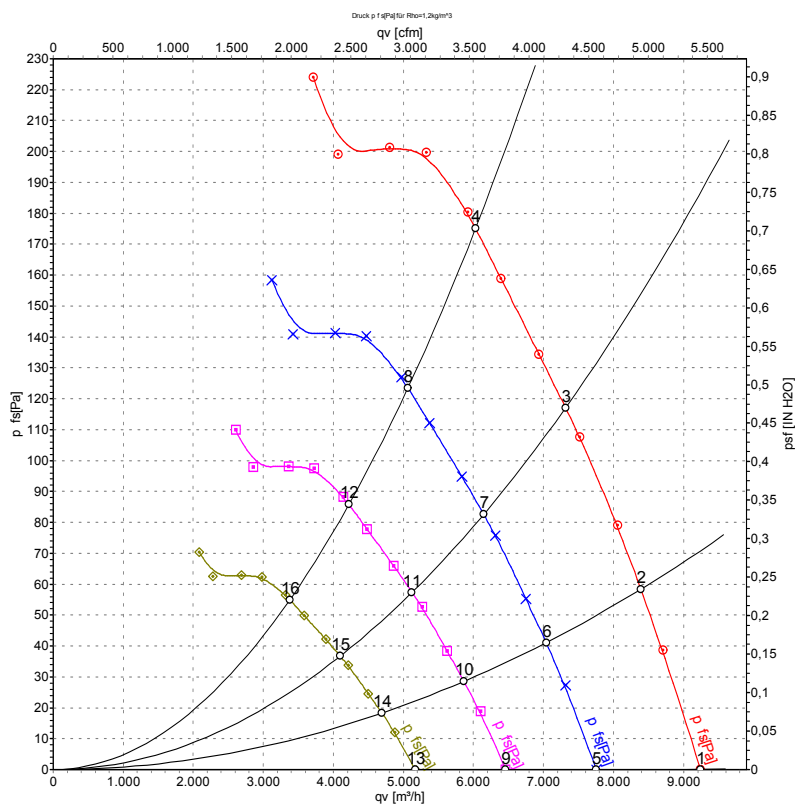
Connection screen



No.	Conn.	Designation	Function / assignment
PE	-	PE	Protective earth connection
KL1	1, 2	N, L	Supply voltage, 50/60 Hz
KL2	1	NC	Floating status message contact, break for failure
KL2	2	COM	Floating status message contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status message contact, normally open, make for failure
KL3	1	OUT	Analogue output, 0-10 VDC, max. 3 mA, SELV, Output of the current motor level control coefficient: 1 V corresponds to 10% level control coefficient, 10 V correspond to 100% level control coefficient.
KL3	2, 8	GND	Reference mass for control interface, SELV
KL3	3, 7	0-10 V	Use control / actual value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (+/- 3%), max. 10 mA, Supply voltage for ext. devices (e.g. potentiometer), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25%/-10%), max. 50 mA Supply voltage for ext. devices (e.g. sensors), SELV
KL3	6	4-20 mA	Use control / actual value input 4-20 mA, impedance 100 Ω, only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for MODBUS, RSB
KL3	10, 12	RSA	RS485 interface for MODBUS, RSA



Charts: Air flow 50 Hz



Measurement: LU-131222-1

Air performance measured as per ISO 5801
Installation category A. For detailed
information on the measuring set-up, please
contact ebm-papst. Suction-side noise
levels: L_{wA} measured as per ISO 13347 /
L_{pA} measured with 1m distance to fan axis.
The values given are valid under the
measuring conditions mentioned above and
may vary according to the actual installation
situation. With any deviation from the
standard set-up, the specific values have to
be checked and reviewed with the unit
installed.

Measured values

	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	LwA _{out}	q _v	P _{fs}	q _v	P _{fs}
	V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m³/h	Pa	cfm	inH ₂ O
1	230	50	1420	554	2.52	70	77	77	9245	0	5440	0.00
2	230	50	1420	633	2.85	67	75	75	8390	58	4940	0.23
3	230	50	1420	696	3.12	66	73	73	7315	117	4305	0.47
4	230	50	1420	750	3.40	66	74	73	6030	175	3550	0.70
5	230	50	1200	327	1.49	66	74	74	7755	0	4565	0.00
6	230	50	1200	373	1.68	64	71	71	7040	41	4145	0.16
7	230	50	1200	413	1.85	62	69	69	6145	83	3620	0.33
8	230	50	1200	443	1.97	62	70	70	5065	124	2980	0.50
9	230	50	1000	189	0.86	62	70	70	6460	0	3805	0.00
10	230	50	1000	216	0.97	60	67	67	5865	28	3455	0.11
11	230	50	1000	239	1.07	58	65	65	5125	57	3015	0.23
12	230	50	1000	256	1.14	58	66	66	4220	86	2485	0.35
13	230	50	800	97	0.44	58	65	65	5170	0	3040	0.00
14	230	50	800	111	0.50	55	62	62	4695	18	2760	0.07
15	230	50	800	122	0.55	53	60	60	4100	37	2410	0.15
16	230	50	800	131	0.59	54	61	61	3375	55	1990	0.22

U = Supply voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power input · I = Current draw · LpA_{in} = Sound pressure level inlet side · LwA_{in} = Sound power level inlet side · LwA_{out} = Sound power level outlet side
q_v = Air flow · P_{fs} = Pressure increase

