

8300101724  
VBF0630PTVNZ

# EC centrifugal module - RadiPac

backward-curved, single-intake  
with cube design

8300101724 ebmpapst Datasheet

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## Nominal data

Item	8300101724	
Motor	E20003-75	
Phase		3~
Nominal voltage	VAC	200
Nominal voltage range	VAC	200 .. 240
Frequency	Hz	50/60
Method of obtaining data		ml
Status		prelim.
Speed (rpm)	min <sup>-1</sup>	1840
Power consumption	W	7850
Current draw	A	24.0
Min. ambient temperature	°C	-40
Max. ambient temperature	°C	40

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment  
Subject to change

## Data according to Commission Regulation (EU) 327/2011 (prEN 17166)

		Actual	Req. 2015			
01 Overall efficiency $\eta_{es}$	%	65.6	60.9	09 Power consumption $P_{ed}$	kW	7.77
02 Measurement category		A		09 Air flow $q_v$	m <sup>3</sup> /h	15155
03 Efficiency category		Static		09 Pressure increase $p_{fs}$	Pa	1174
04 Efficiency grade N		66.7	62	10 Speed (rpm) n	min <sup>-1</sup>	1825
05 Variable speed drive		Yes		11 Specific ratio <sup>*</sup>		1.01

Data obtained at optimum efficiency level.

<sup>\*</sup> Specific ratio =  $1 + p_{fs} / 100\,000\text{ Pa}$

LU-219876

The efficiency values displayed for achieving conformity with the Ecodesign Regulation EU 327/2011 has been reached with defined air duct components (e.g. inlet rings).  
The dimensions must be requested from ebm-papst. If other air conduction geometries are used on the installation side, the ebm-papst evaluation loses its validity/the conformity must be confirmed again.  
The product does not fall within the scope of Regulation (EU) 2019/1781 due to the exception specified in Article 2 (2a) (motors completely integrated into a product).

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## Technical description

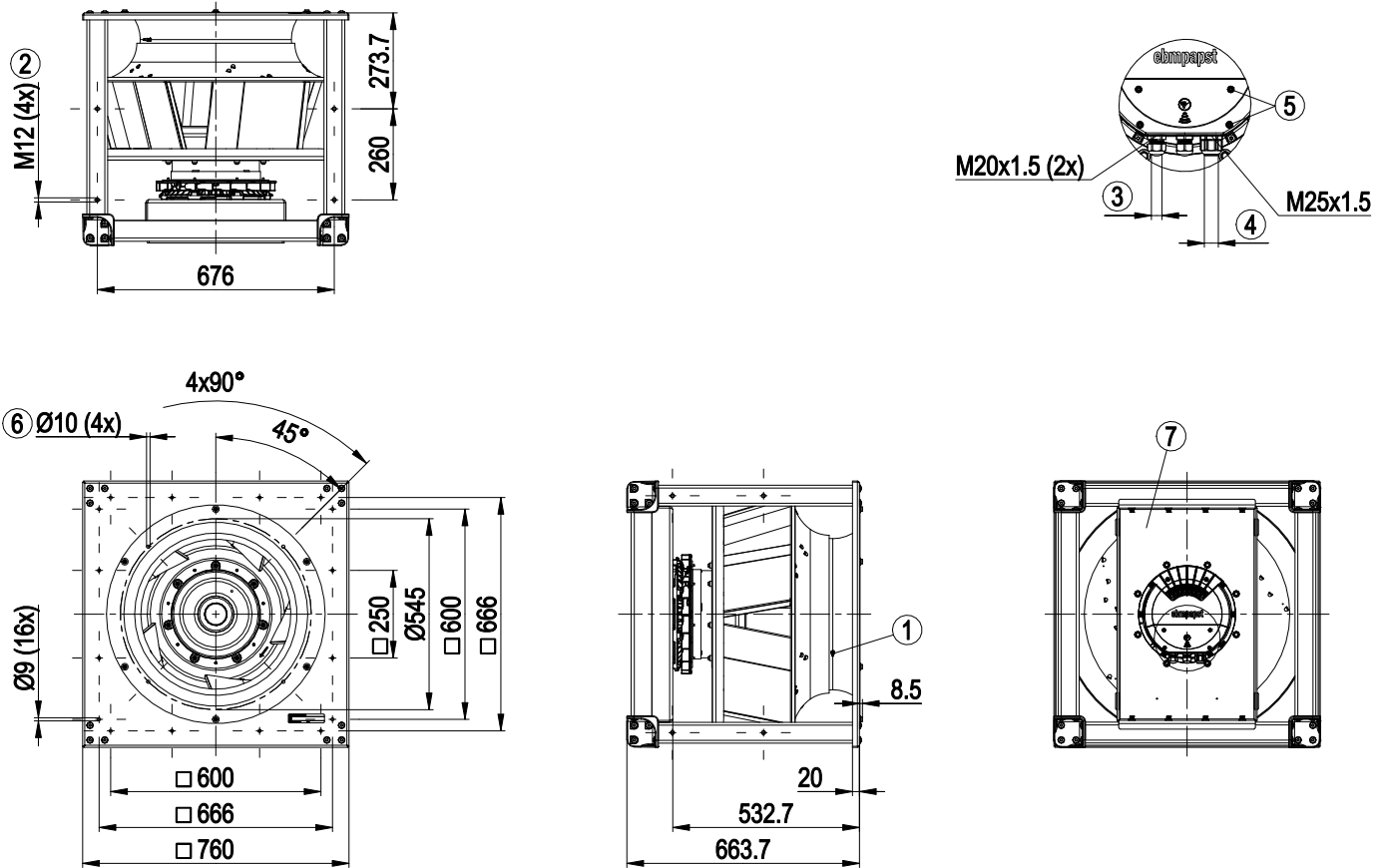
Weight	95 kg
Size	630 mm
Motor size	200
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum
Impeller material	Sheet aluminum
Support plate material	Sheet steel, galvanized
Spacer material	Aluminum
Inlet nozzle material	Sheet steel, galvanized
Number of blades	5
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	"F"
Moisture (F) / Environmental (H) protection class	H1
Ambient temperature note	Occasional start-up at temperatures between -40°C and -25°C is permitted. For continuous operation at ambient temperatures below -25°C (such as refrigeration applications), use must be made of a fan design with special low-temperature bearings.
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	See legend on product drawing
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing; (sealed)
Technical features	<ul style="list-style-type: none"><li>- Operation and alarm display with LED</li><li>- External 15-50 VDC input (parameterization)</li><li>- Alarm relay</li><li>- Integrated PI controller</li><li>- Configurable inputs/outputs (I/O)</li><li>- MODBUS V6.4</li><li>- Motor current limitation</li><li>- RS-485 MODBUS-RTU</li><li>- Soft start</li><li>- Voltage output 3.3-24 VDC, Pmax = 800 mW</li><li>- Control interface with SELV potential safely disconnected from the mains</li><li>- Thermal overload protection for electronics/motor</li><li>- Line undervoltage / phase failure detection</li><li>- Vibration sensor</li></ul>
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Terminal box
Protection class assignment	I; If a protective earth is connected. The built-in component has several local protection class assignments. The final protection class is determined by the intended installation.
Conformity with standards	EN 61800-5-1; CE
Approval	EAC

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## Product drawing

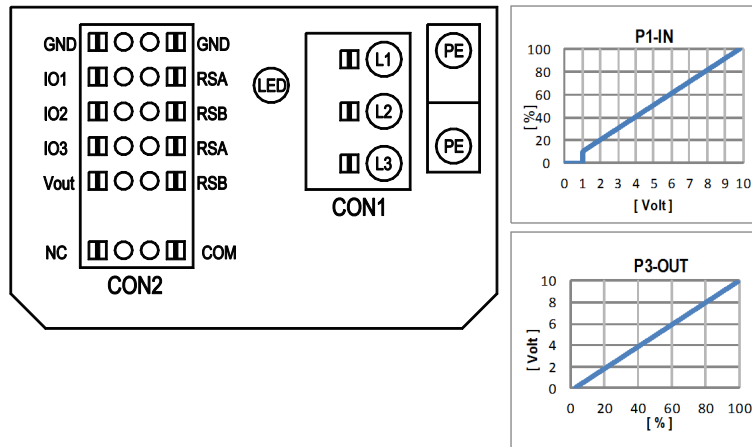


1	Inlet ring with pressure tap (k-factor: 438)
2	Mounting position for vibration-absorbing elements, tightening torque max. 40 Nm
3	Cable diameter min. 4 mm, max. 10 mm, tightening torque $4 \pm 0.6$ Nm
4	Cable diameter min. 5 mm, max. 14 mm, tightening torque $6 \pm 0.9$ Nm
	(The tightening torque is designed for PVC cables. If the cable materials are different, the tightening torque may have to be adjusted)
5	Tightening torque $3 \pm 0.3$ Nm
6	Attachment holes for FlowGrid 00630-2-2957 (not included in scope of delivery)
7	Motor support plate
	Installation position: Only base mounting, shaft horizontal (motor support plate must be vertical!). Rotor on top or rotor on bottom on request
	The drawing shows the dimensions only and does not represent the installation position

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## Connection diagram



No.	Conn.	Designation	Function/assignment
	CON1	L1, L2, L3	Power supply, phase, see nameplate for voltage range
	PE	PE	Protective earth
	CON2	RSA	RS485 interface for MODBUS, RSA; SELV
	CON2	RSB	RS485 interface for MODBUS, RSB; SELV
	CON2	GND	Reference ground for control interface, SELV
	CON2	IO1	Function parameterizable (see "Optional interface functions" table) Factory setting: Digital input - high active, function: Disable input, SELV - inactive: Pin open or applied voltage < 1.5 VDC - active: applied voltage 3.5-50 VDC Reset function: Triggering of error reset on change of state from "enabled" to "disabled"
	CON2	IO2	Function parameterizable (see "Optional interface functions" table) Factory setting: Analog input 0-10 V/PWM, Ri=100 kΩ, function: Set value Characteristic curve parameterizable (see input characteristic curve P1-IN), SELV
	CON2	IO3	Function parameterizable (see "Optional interface functions" table) Factory setting: Analog output 0-10 V, max. 5 mA, function: Actual speed Characteristic curve parametrizable (see output characteristic curve P3-OUT), SELV
	CON2	Vout	Voltage output 3.3-24 VDC ±5%, Pmax=800 mW, voltage parameterizable Factory setting: 10 VDC short-circuit-proof, supply for external devices, SELV alternatively: 15-50 VDC input for parameterization via MODBUS without line voltage
	CON2	COM	Status relay, floating status contact, common connection, contact rating 250 VAC / 2 A (AC1) / min. 10 mA, reinforced insulation on supply side and on control interface side
	CON2	NC	Status relay, floating status contact, break for failure
		LED	green: status = good, ready for operation orange: status = warning red: status = failure
		P1-IN	Input characteristic curve
		P3-OUT	Output characteristic curve

## Terminal/plug assignment

CON2	configurable IO mode	electrical specification	configurable IO functions: normal / inverse	INPUT		OUTPUT												
				source: set value	source: sensor value	switch: parameter set: #1 / #2	switch: control function: heating (pos.) / cooling (neg.)	switch: direction of rotation: cw / ccw	switch: set value source	switch: fan enable / disable	signal: tach out (selected directly via IO mode)	signal: diagnostics out (selected directly via IO mode)	signal: fan modulation level %	signal: actual speed	signal: system modulation level %	signal: remote control output 0-10V	pulse input for auto-addressing	pulse output for auto-addressing
IO1	○ Din1 (active high): digital input	active: applied voltage 3.5-50VDC, SELV not active: pin open or applied voltage < 1.5VDC	D158 [0]	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
	○ Ain1 0-10V/PWM: analog input	RI = 100k, characteristic curve parameterizable, f <sub>PWM</sub> = 1k..10kHz, SELV	D158 [2]	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
	○ Tach out (open collector output)	U <sub>max</sub> = 50VDC, I <sub>max</sub> = 20mA, SELV	D158 [5]	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
	○ Diagnostics out (open collector output)	U <sub>max</sub> = 50VDC, I <sub>max</sub> = 20mA, SELV	D158 [6]	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
	○ Din2 (active high): digital input	active: applied voltage 3.5-50VDC, SELV not active: pin open or applied voltage < 1.5VDC	D159 [0]	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
	○ Ain2 0-10V/PWM: analog input	RI = 100k, characteristic curve parameterizable, f <sub>PWM</sub> = 1k..10kHz, SELV	D159 [2]	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
IO2	○ Ain2 4-20mA: analog input	RI = 125R, characteristic curve parameterizable, SELV	D159 [3]	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
	○ Din3 (active high): digital input	active: applied voltage 3.5-50VDC, SELV not active: pin open or applied voltage < 1.5VDC	D15A [0]	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
	○ Din3 (active low): digital input	active: applied voltage < 1.5VDC, SELV not active: pin open or applied voltage 3.5-50VDC	D15A [1]	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
	○ PWMIn3: digital input idle level high	PWM = 40Hz - 10kHz, characteristics parameterizable active: pin open or applied voltage 3.5-50VDC not active: applied voltage < 1.5VDC, SELV	D15A [7]	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
IO3	○ PWMIn3: digital input idle level low	40Hz - 10kHz, characteristics parameterizable active: applied voltage 3.5-50VDC not active: pin open or applied voltage < 1.5VDC, SELV	D15A [8]	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
	○ Aout3 0-10V: analog output	function parameterizable, max. 5mA max output frequency 300Hz, SELV	D15A [4]	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
	○ Tacho out (pulses), analog output	0-10V max. 5mA max output frequency 300Hz, SELV	D15A [5]	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
RSA RSB	○ Diagnostics out (pulses)	0-10V max. 5mA max output frequency 300Hz, SELV	D15A [6]	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
	RS485 bus connection,	MODBUS RTU, specification V6.4, SELV		○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
Vout	voltage output	voltage parameterizable 3.3...24VDC +/- 5%, P <sub>max</sub> =800mW, short-circuit-proof, supply for external devices, SELV	D16E [..]	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
	alternatively: Input auxiliary power supply/for parameterization via RS485/MODBUS RTU without line voltage	15...50VDC		○	○	○	○	○	○	○	○	○	○	○	○	○	○	○

○ configurable option

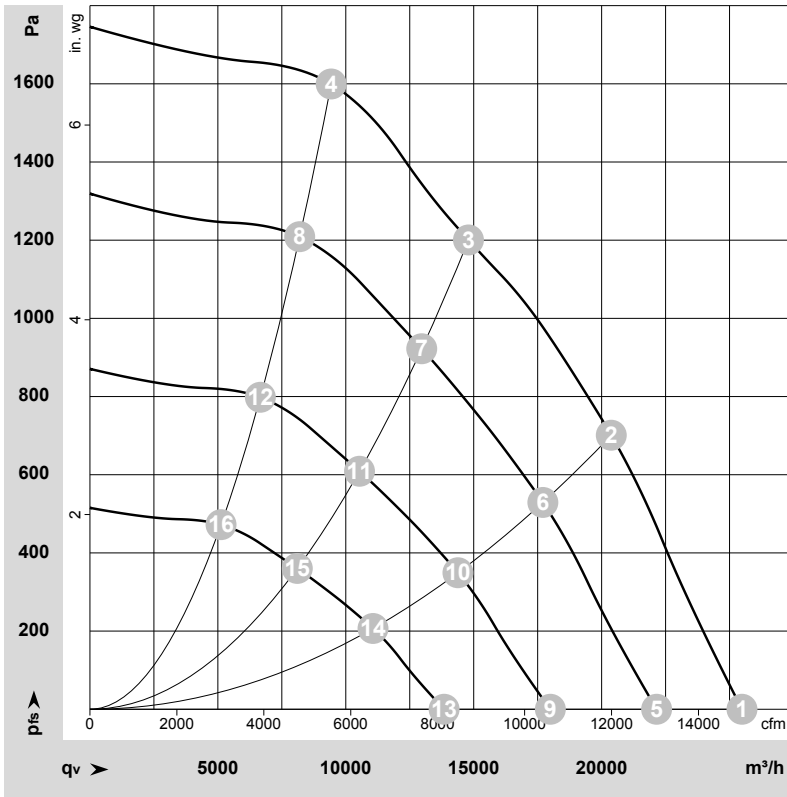
For further information and additional functions see EC Control Software: Fan-Set-App. or MODBUS Parameter Specification V6.4

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## Curves: Air performance 50 Hz



$\rho = 1.15 \text{ kg/m}^3 \pm 2 \%$

Measurement: LU-219876-1  
Date: 2022-03-16  
Nozzle: 64040-2-4013

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

## Measured values

	Wired	U	f	n	P <sub>e</sub>	I	LpA <sub>in</sub>	LwA <sub>in</sub>	LwA <sub>out</sub>	LwA	q <sub>v</sub>	P <sub>fs</sub>	q <sub>v</sub>	P <sub>fs</sub>
		V	Hz	min <sup>-1</sup>	W	A	dB(A)	dB(A)	dB(A)	dB	m <sup>3</sup> /h	Pa	cfm	in. wg
1	3~	200	50	1840	4020	12.34	90	97	99	101	25485	0	15000	0.00
2	3~	200	50	1840	6824	20.85	84	91	96	98	20380	700	11995	2.81
3	3~	200	50	1840	7850	24.00	81	88	95	96	14795	1200	8710	4.82
4	3~	200	50	1840	7546	23.15	85	92	98	99	9430	1600	5550	6.42
5	3~	200	50	1600	2639	8.10	86	93	96	98	22150	0	13035	0.00
6	3~	200	50	1600	4475	13.67	80	88	93	94	17705	530	10420	2.13
7	3~	200	50	1600	5243	16.14	78	85	92	93	12970	923	7635	3.71
8	3~	200	50	1600	4959	15.21	81	89	94	96	8200	1210	4825	4.86
9	3~	200	50	1300	1415	4.35	81	88	90	93	17995	0	10595	0.00
10	3~	200	50	1300	2400	7.33	75	83	88	89	14385	350	8465	1.41
11	3~	200	50	1300	2812	8.65	73	80	87	88	10535	609	6200	2.44
12	3~	200	50	1300	2660	8.16	76	84	89	90	6660	799	3920	3.21
13	3~	200	50	1000	644	1.98	74	82	84	86	13845	0	8150	0.00
14	3~	200	50	1000	1092	3.34	69	76	81	82	11065	207	6510	0.83
15	3~	200	50	1000	1280	3.94	66	73	80	81	8105	360	4770	1.45
16	3~	200	50	1000	1211	3.71	70	77	83	84	5125	473	3015	1.90

Wired = Wiring · U = Voltage · f = Frequency · n = Speed (rpm) · P<sub>e</sub> = Power consumption · I = Current draw · LpA<sub>in</sub> = Sound pressure level intake side · LwA<sub>in</sub> = Sound power level intake side  
LwA<sub>out</sub> = Sound power level outlet side · q<sub>v</sub> = Air flow · P<sub>fs</sub> = Pressure increase